

Explicit, Dynamic Memory Management with Temporal and Spatial Guarantees

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Artist Summer School 2009
Tsinghua University, Beijing, China

Memory Management

- Allocation:
 - ▶ `malloc`

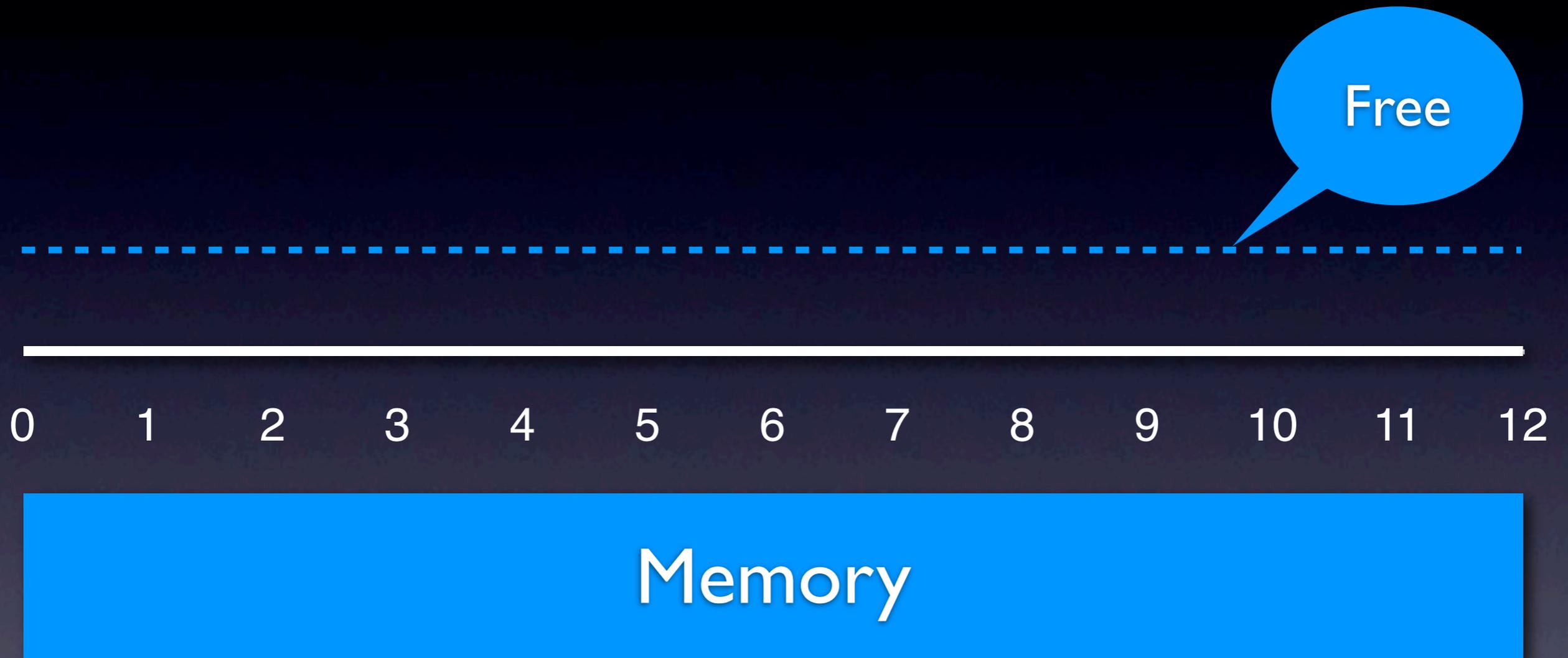
Memory Management

- Allocation:
 - ▶ `malloc`
- Deallocation:
 - ▶ `free`

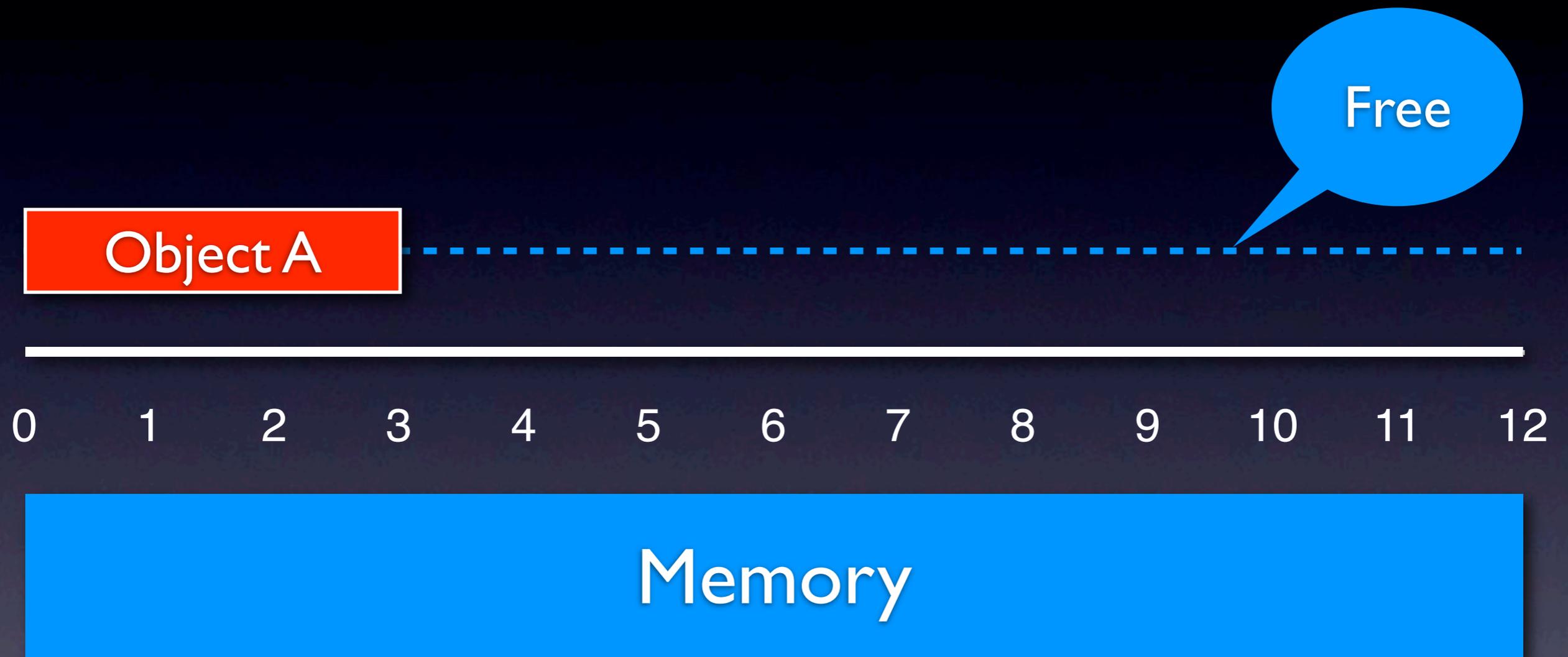
Memory Management

- Allocation:
 - ▶ `malloc`
- Deallocation:
 - ▶ `free`
- Access:
 - ▶ `read` and `write`

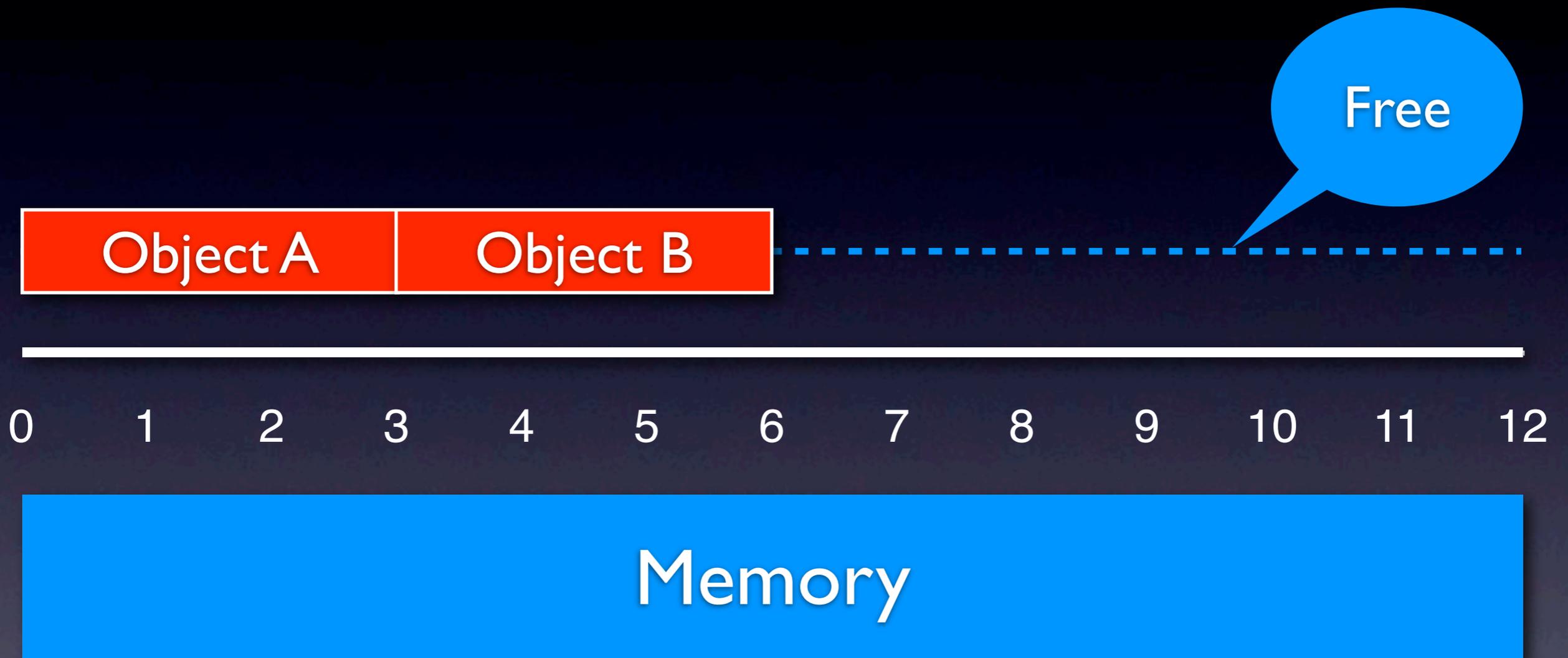
Allocation



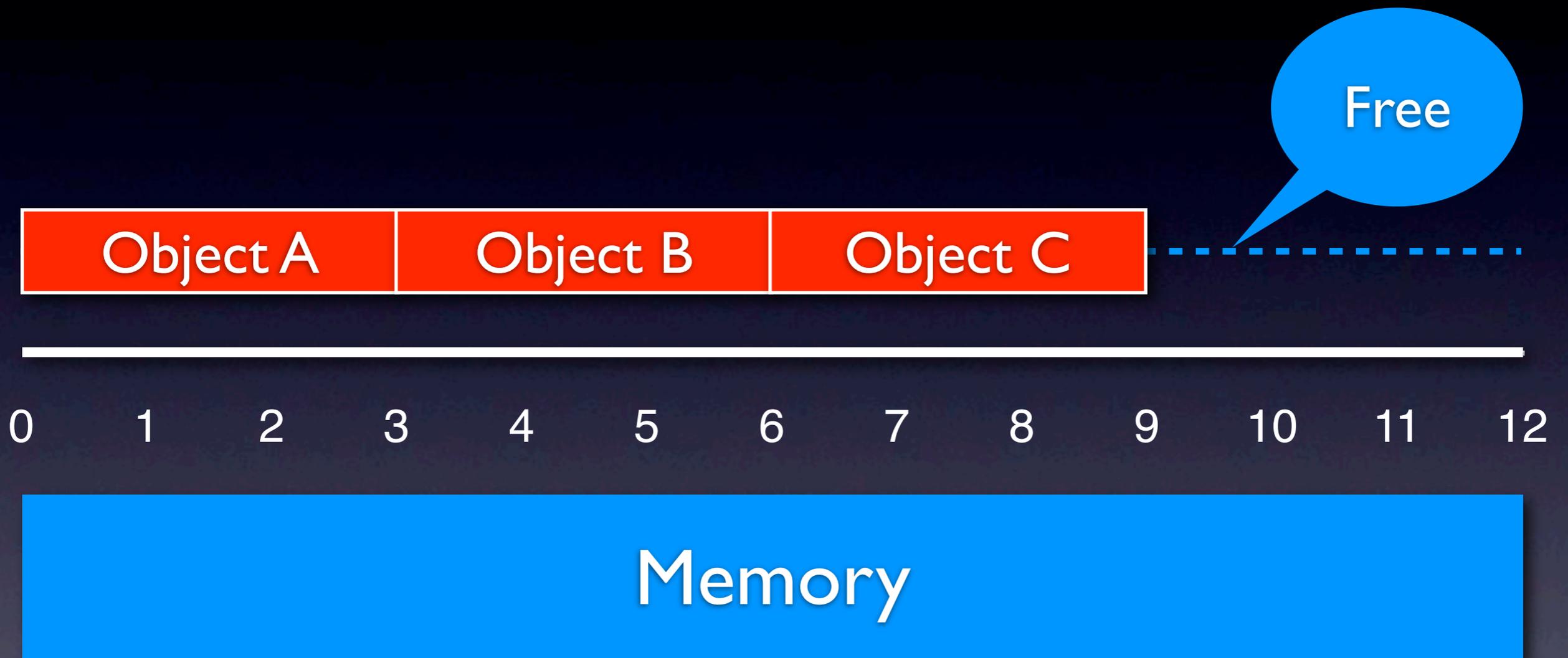
Allocation



Allocation



Allocation



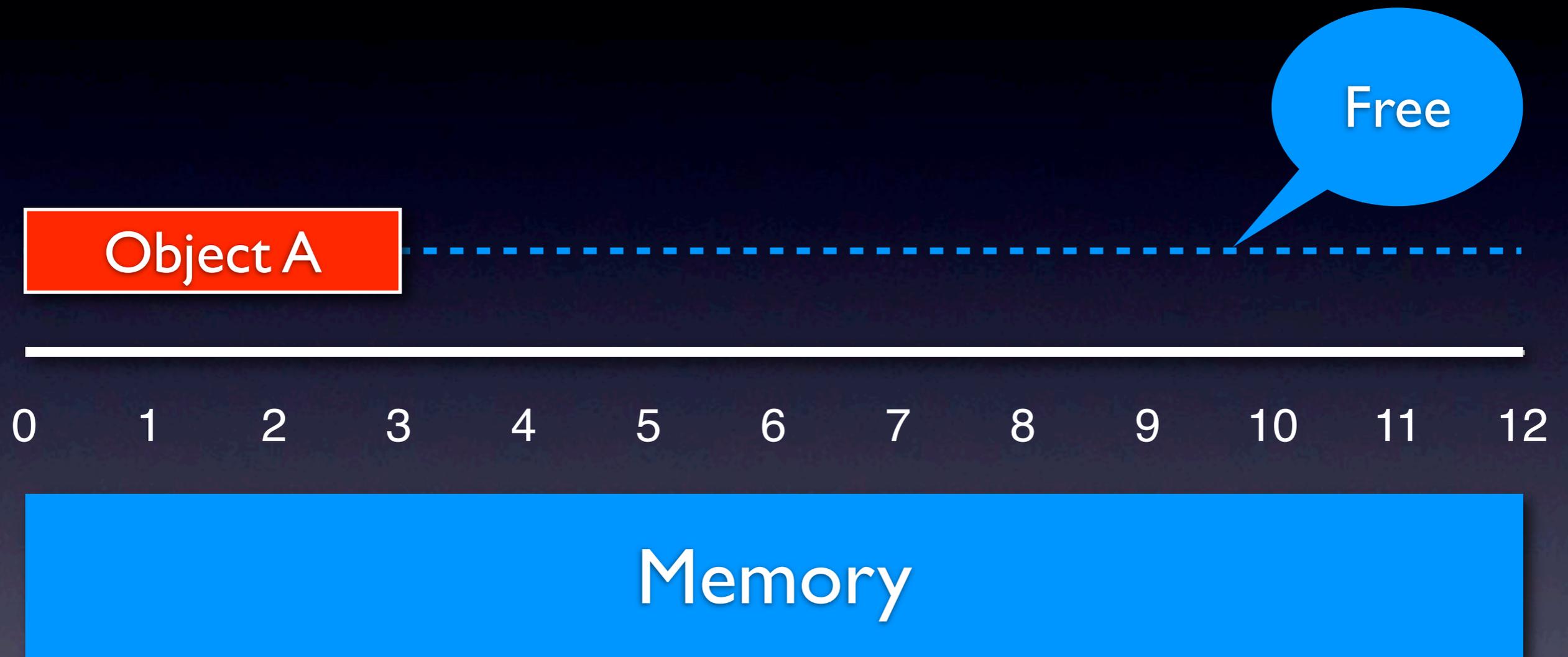
Allocation



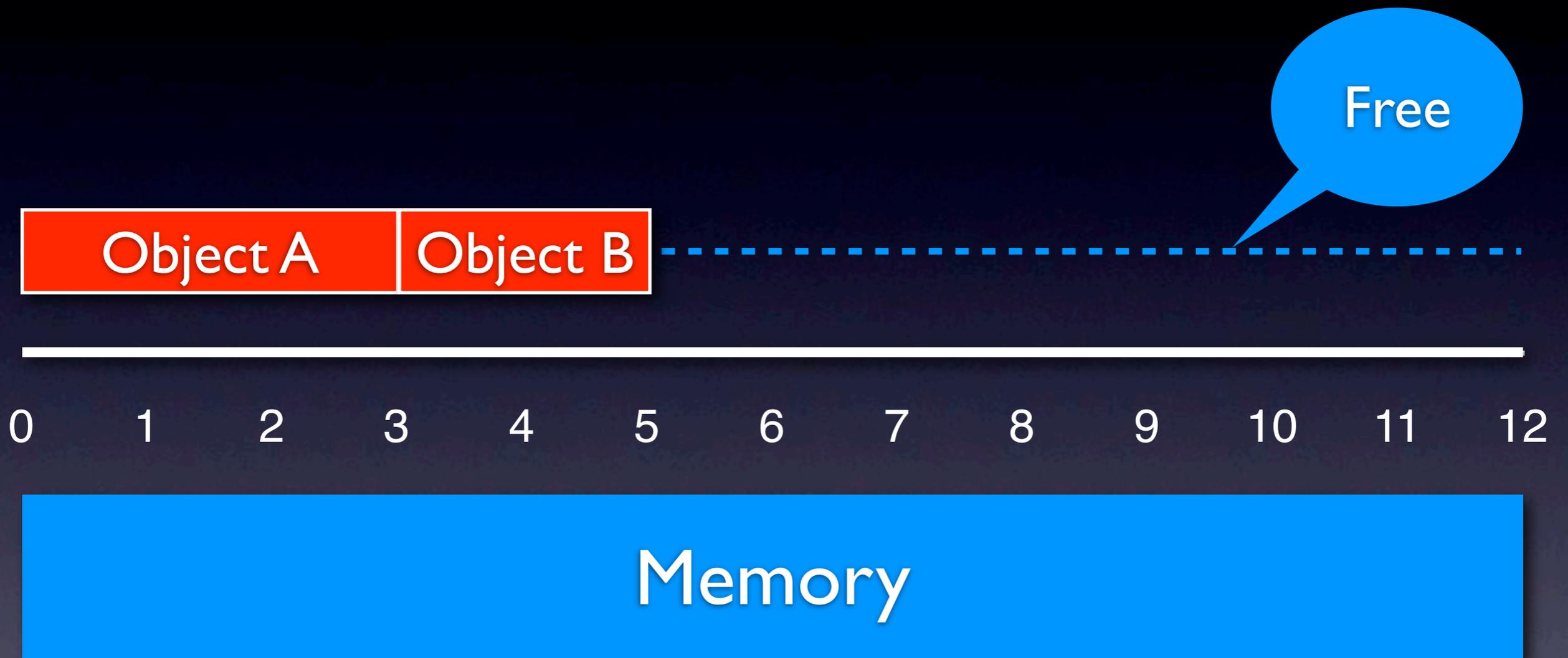
1. Assumption:

Objects may have
different sizes

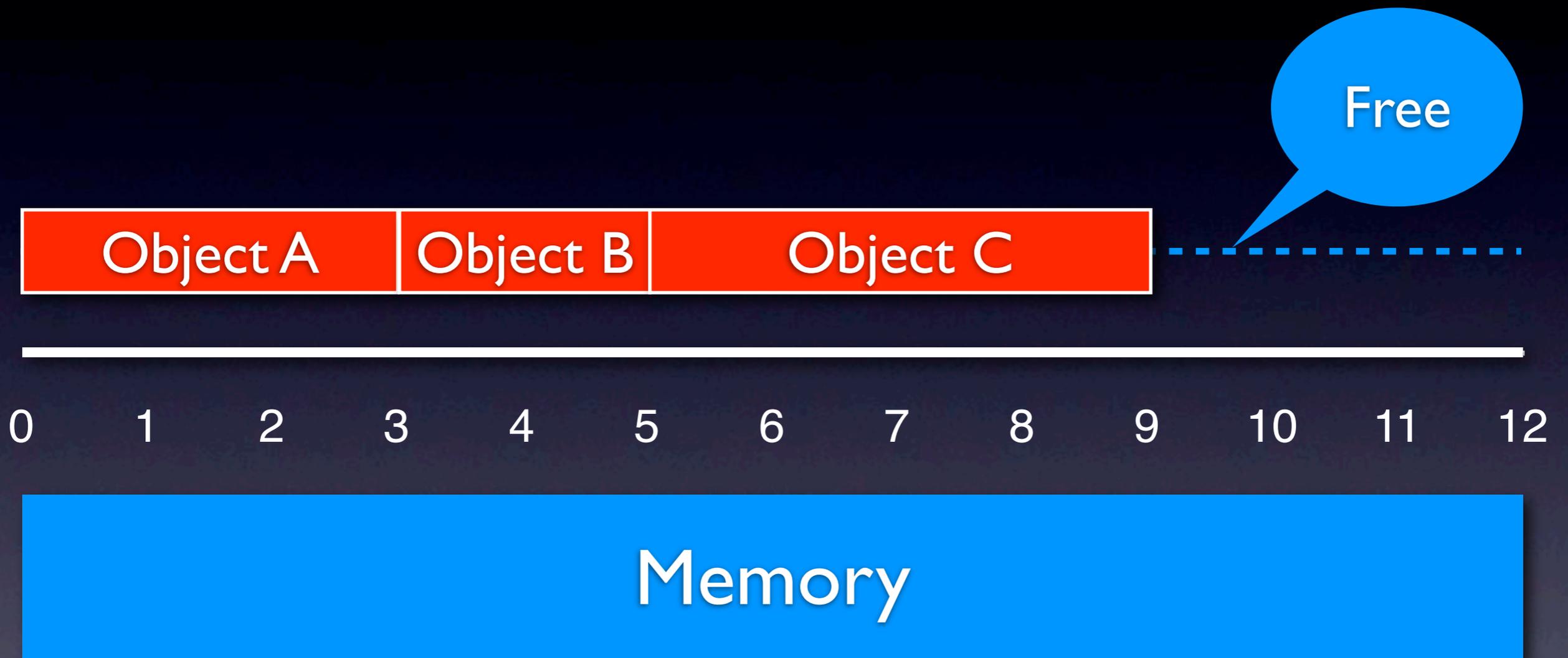
Allocation



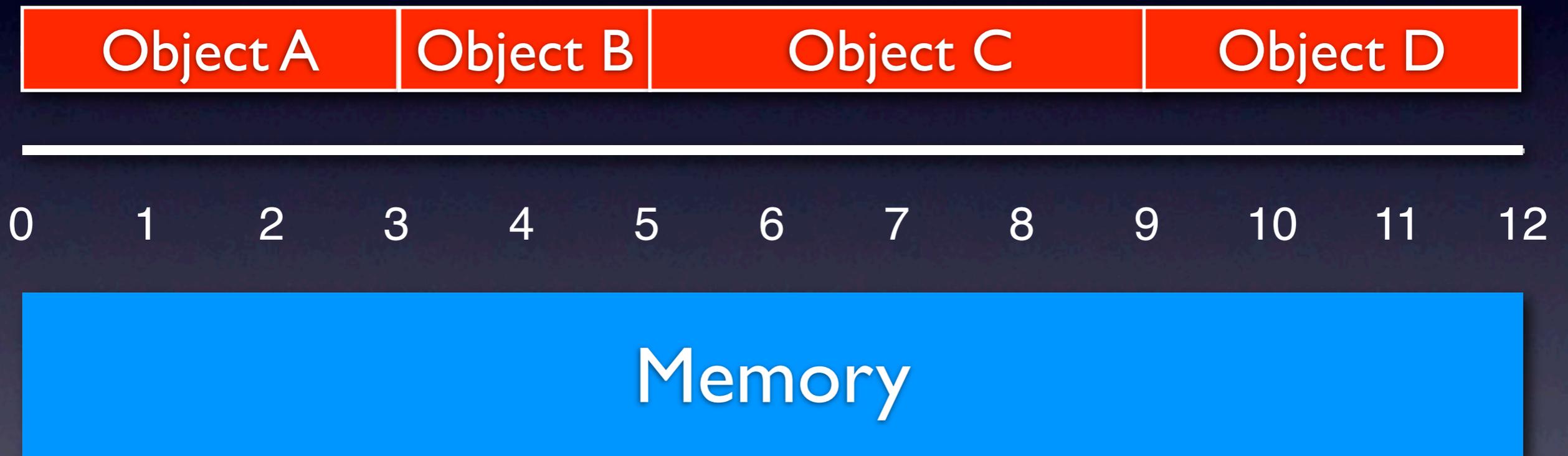
Allocation



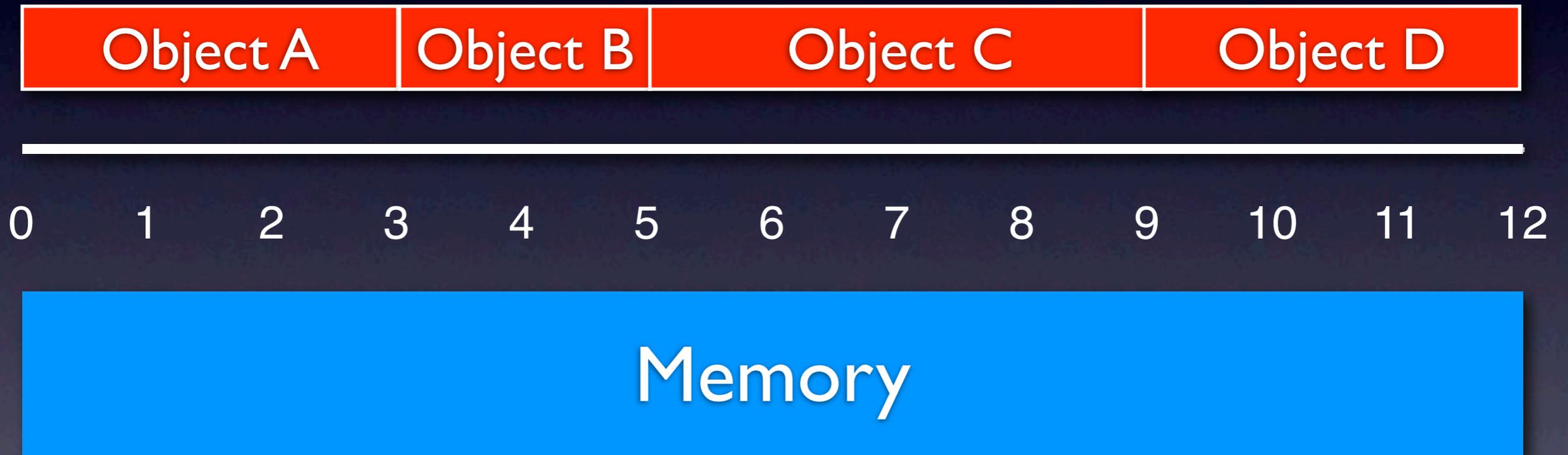
Allocation



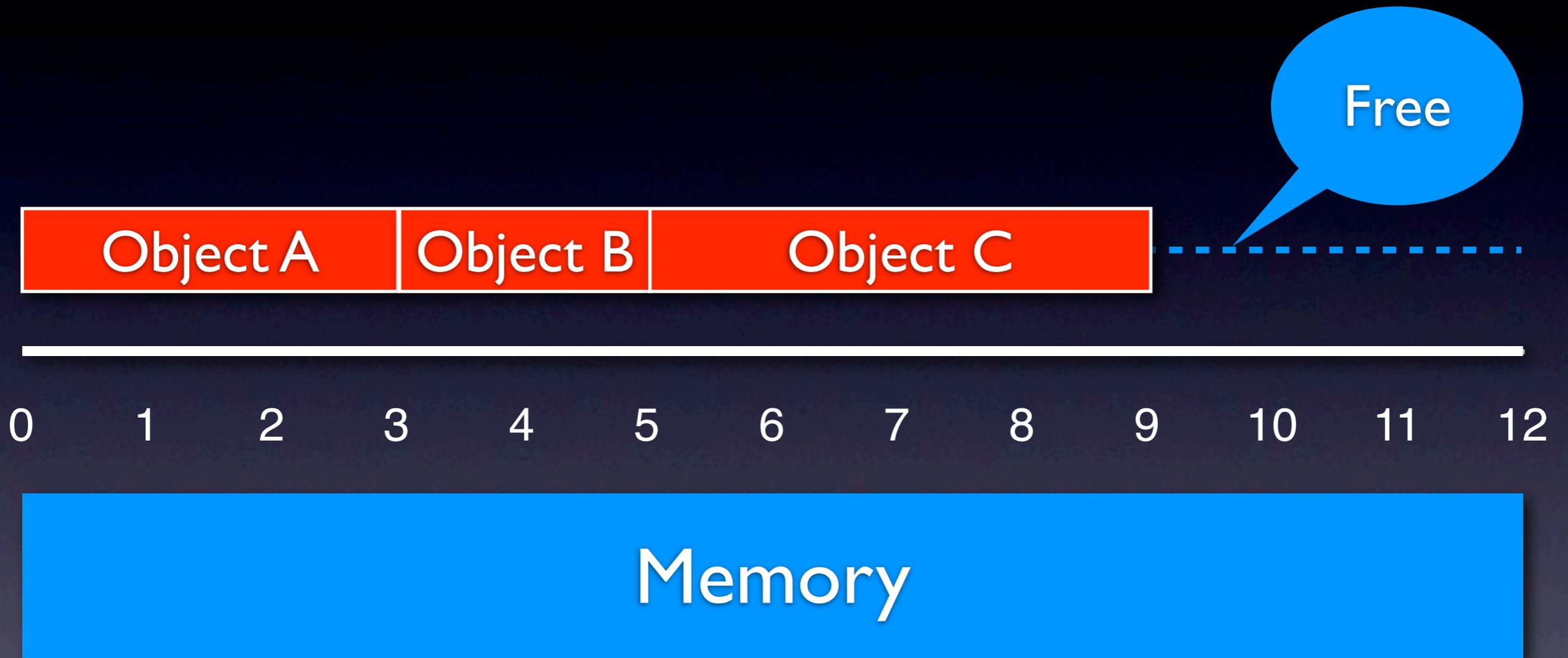
Allocation



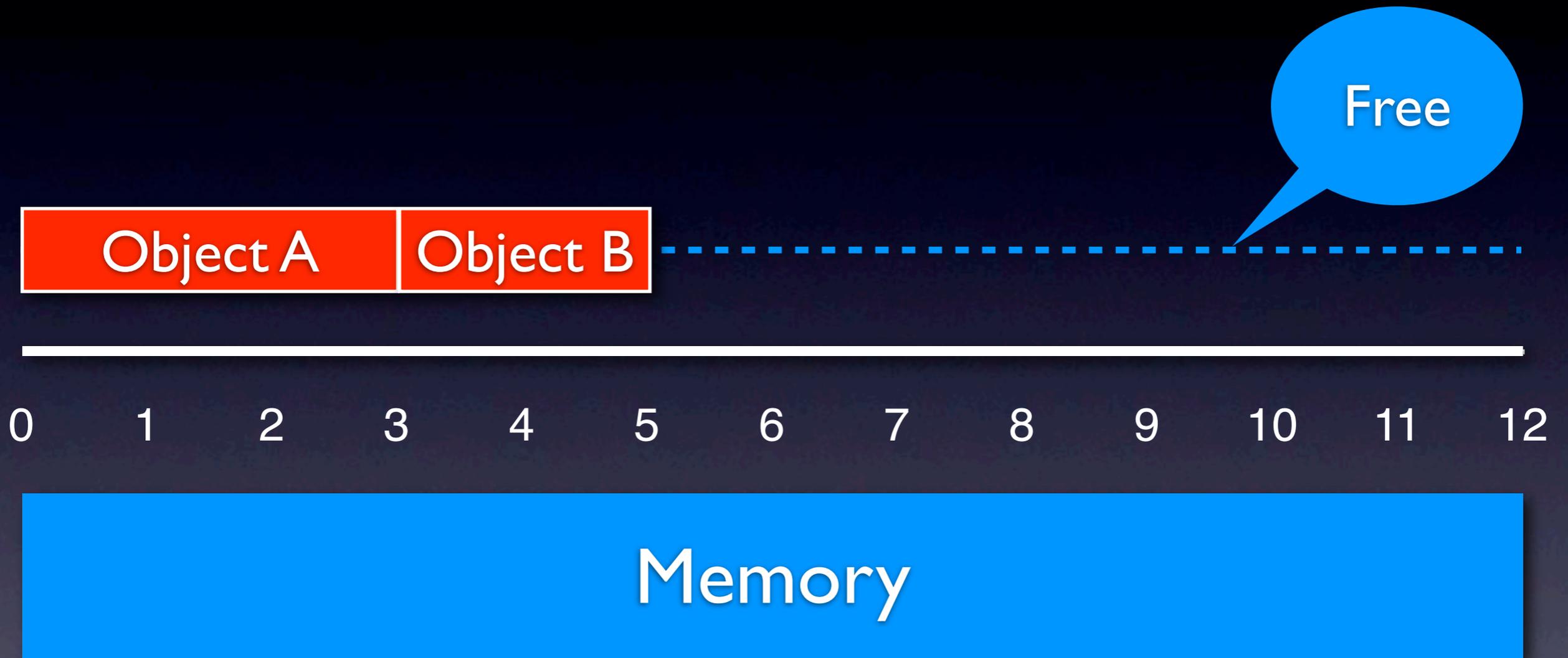
Deallocation



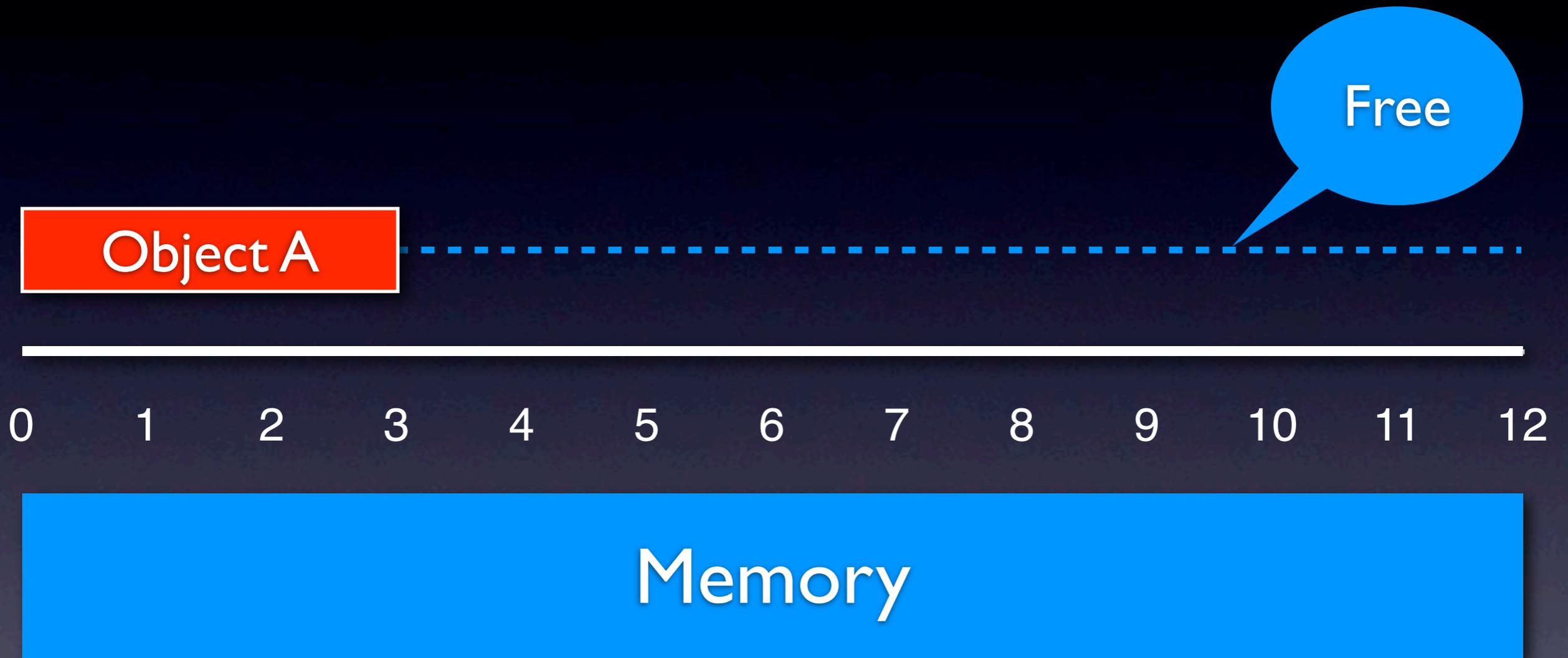
Deallocation



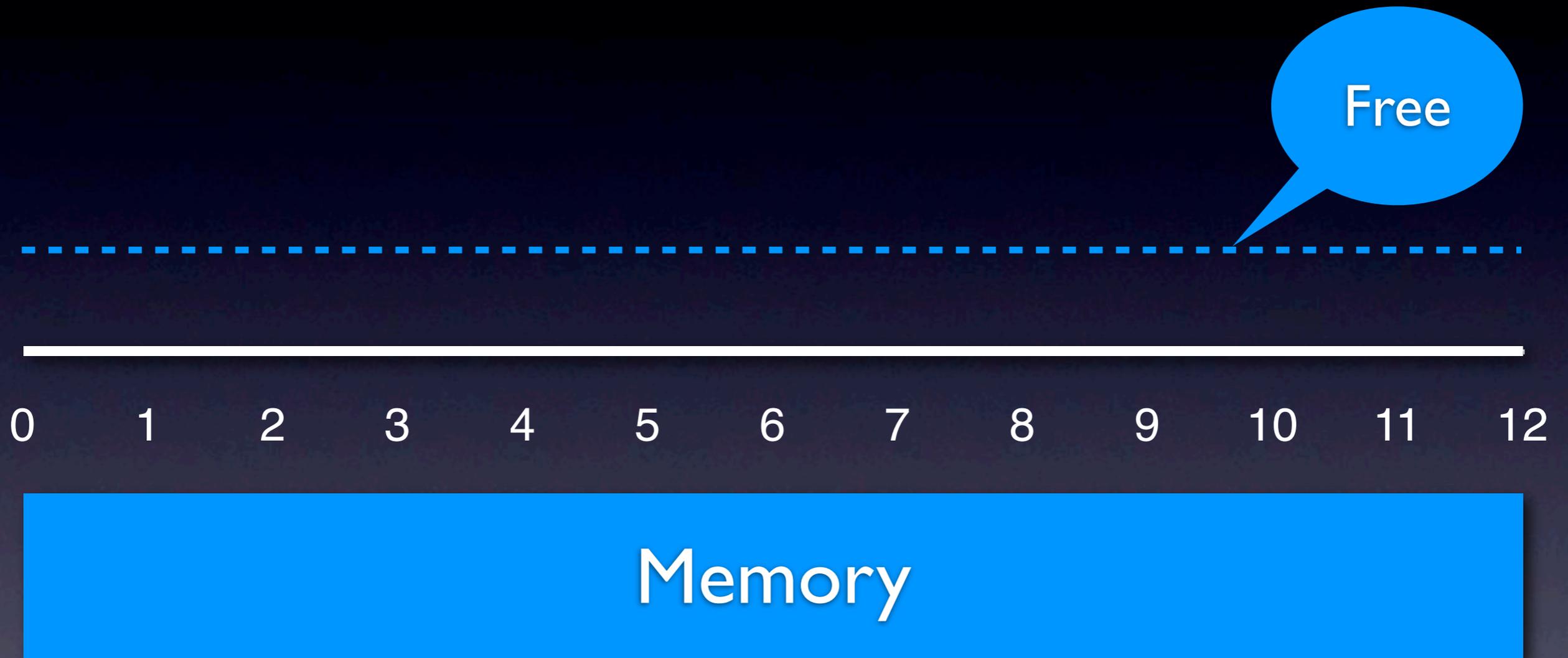
Deallocation



Deallocation



Deallocation



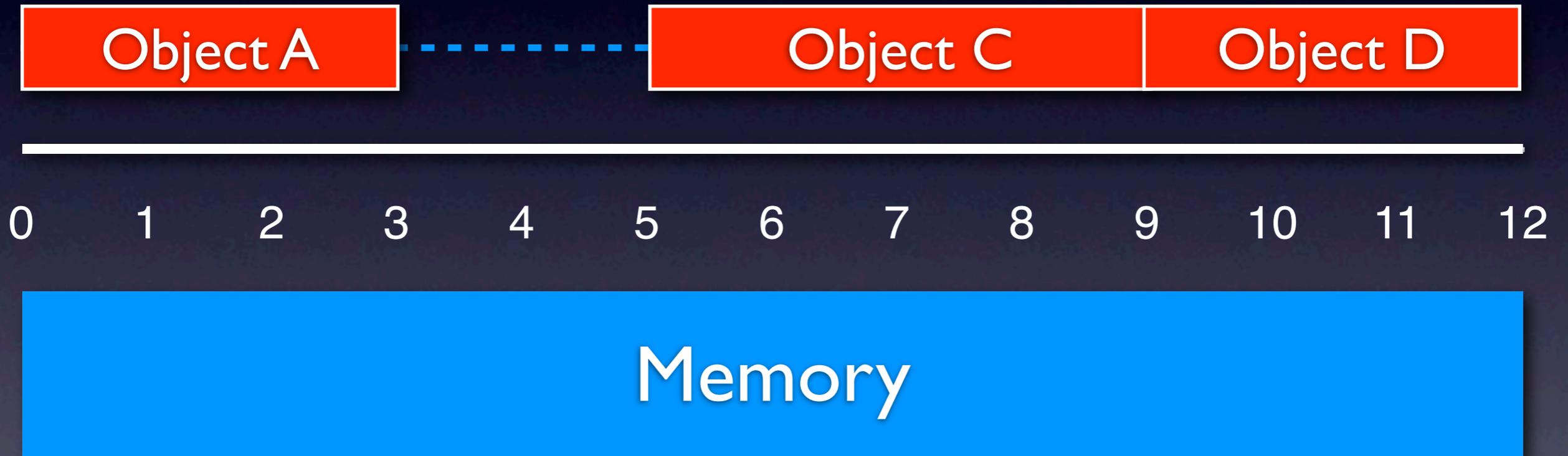
2. Assumption:

Objects may be
allocated and deallocated
in **random** order

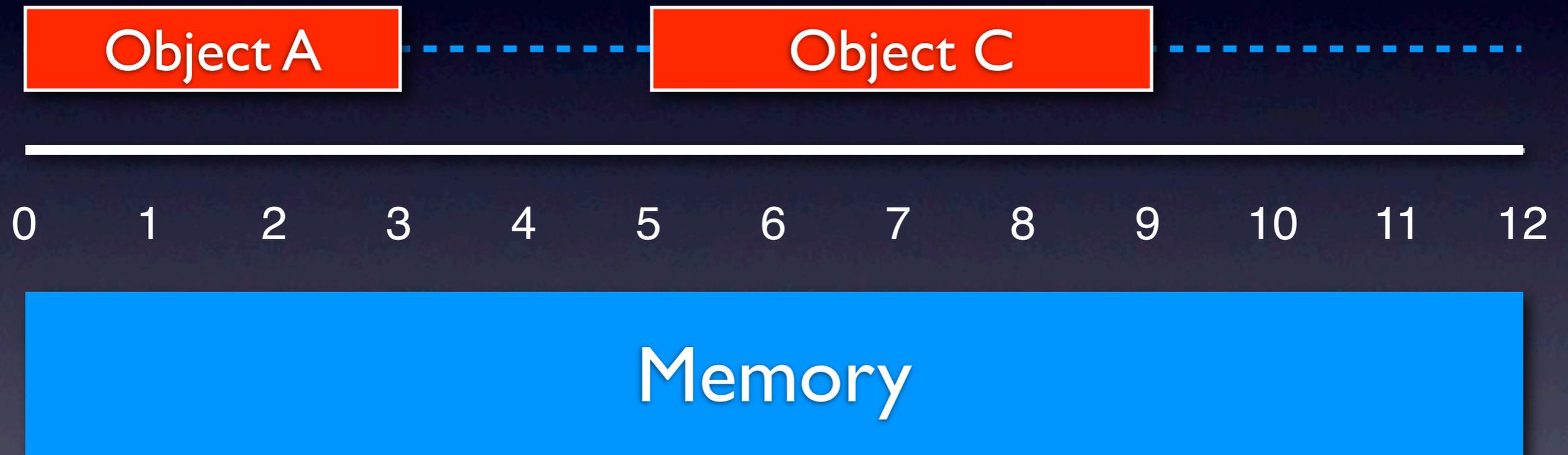
Deallocation



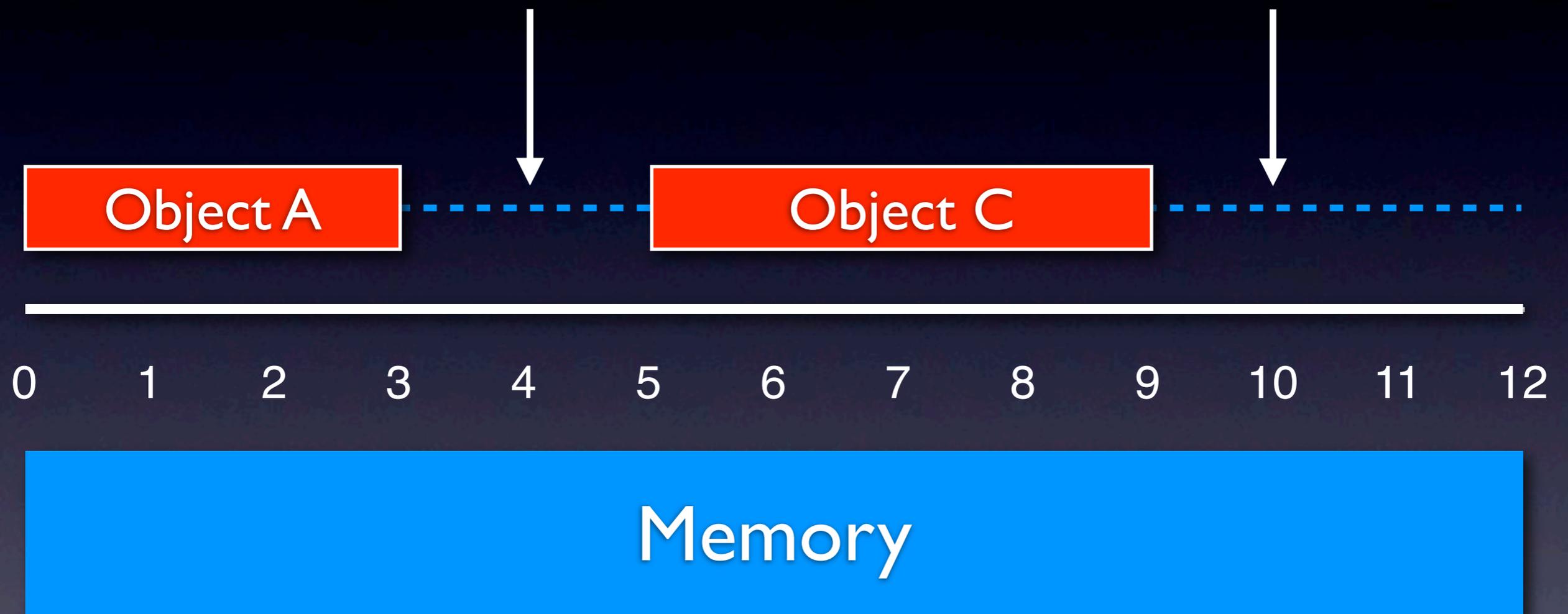
Deallocation



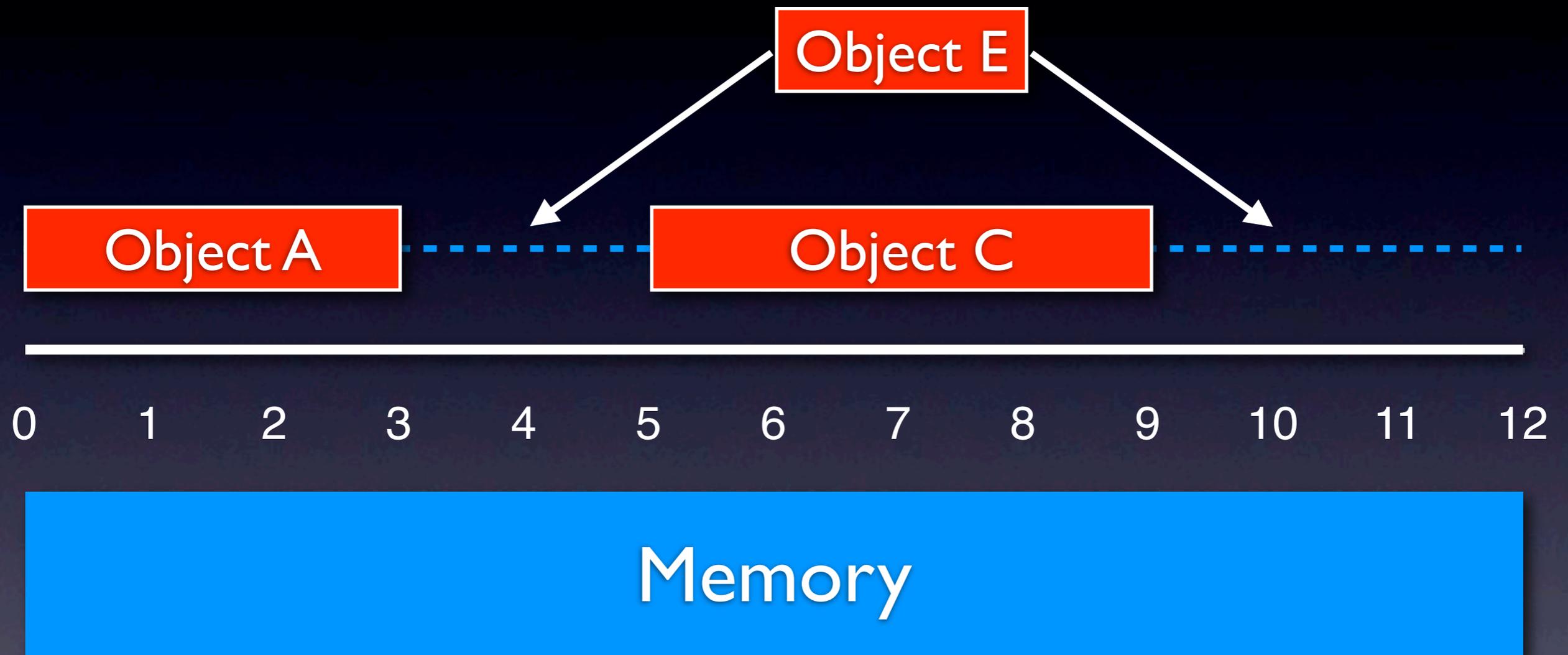
Deallocation



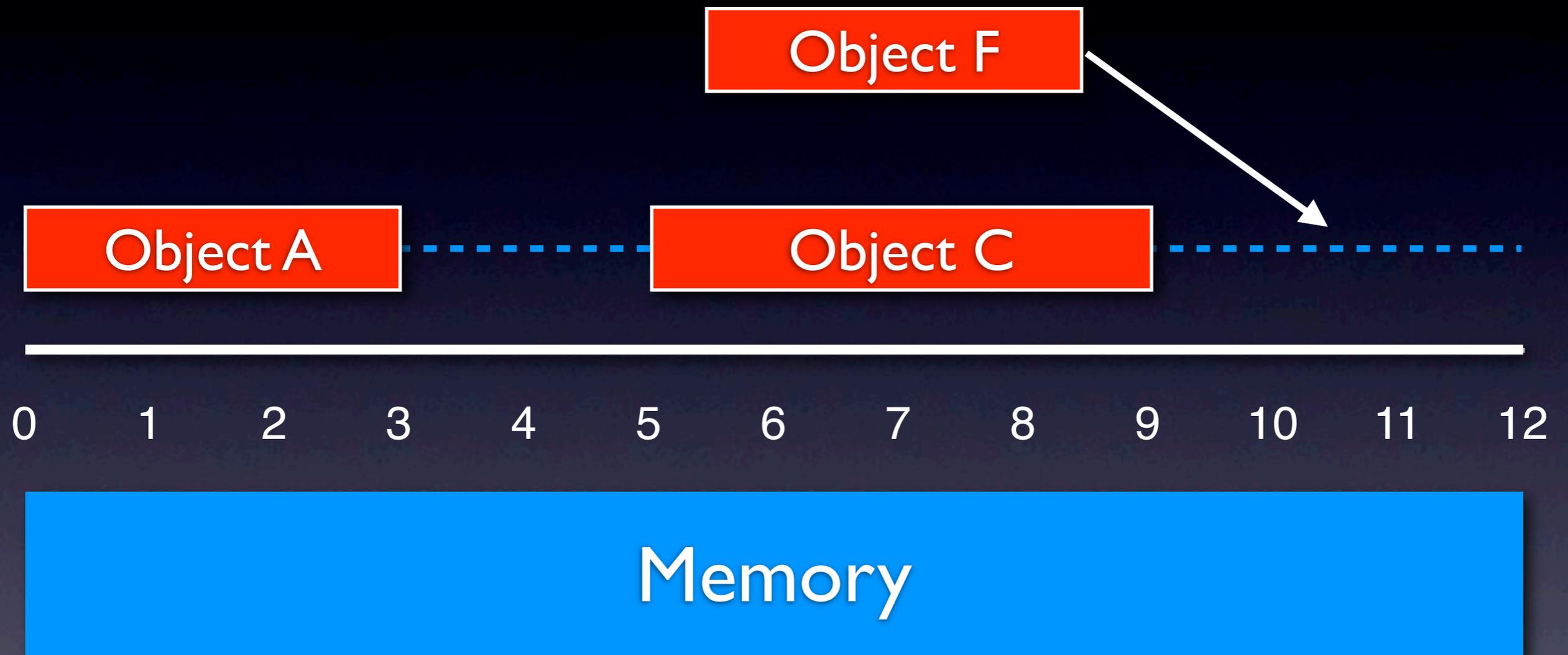
External Fragmentation



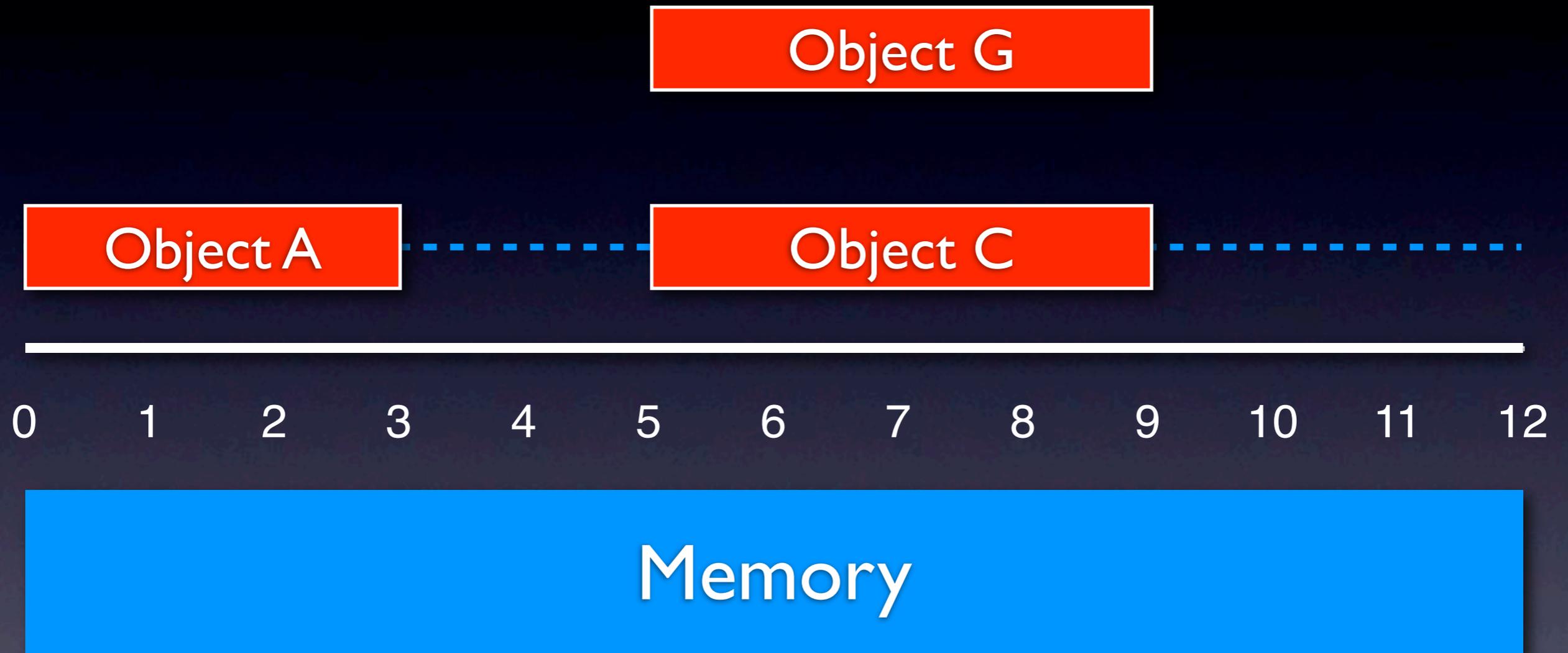
Allocation



Allocation



Allocation



Memory is *fragmented* if
the **largest, contiguous**
piece of available space
is
smaller than
the **total** available space

Fragmentation

- Memory objects may have **different** sizes
- Memory objects may be allocated and deallocated in **random** order
 - ▶ creates the problem of memory **fragmentation!**

Explicit, **Dynamic**
Memory Management with
Temporal and Spatial Guarantees

Static versus Dynamic

- **Static** memory management:
 - ▶ Preallocate all memory at **compile time**

Static versus Dynamic

- **Static** memory management:
 - ▶ Preallocate all memory at **compile time**
- **Dynamic** memory management:
 - ▶ Allocate and deallocate memory at **run time**

Explicit, Dynamic
Memory Management with
Temporal and Spatial Guarantees

Implicit versus Explicit

- **Implicit**, dynamic memory management:
 - ▶ Garbage collector (GC) deallocates objects, not programmer (**implicit** free calls by GC)

Implicit versus Explicit

- **Implicit**, dynamic memory management:
 - ▶ Garbage collector (GC) deallocates objects, not programmer (**implicit** free calls by GC)
- **Explicit**, dynamic memory management:
 - ▶ Objects are deallocated by programmer (**explicit** free calls)

Programming **Abstraction**

Runtime **Overhead**

Implicit, Dynamic Memory Management

Explicit, Dynamic Memory Management

Static Memory Management

Programming Abstraction

Runtime Overhead

Implicit

Web, Safety

Explicit

Server, Performance

Static

Embedded, Real Time

Programming Abstraction

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Temporal Performance

- Throughput:
 - ▶ 10MB/s **allocation** rate
 - ▶ 10MB/s **deallocation** rate

Temporal Performance

- Throughput:
 - ▶ 10MB/s **allocation** rate
 - ▶ 10MB/s **deallocation** rate
- Latency/Responsiveness:
 - ▶ 1ms **execution** time (malloc/free)
 - ▶ 0.1ms **preemption** time (malloc/free)

Spatial Performance

- Degree of fragmentation:
 - ▶ The **number** of contiguous pieces of memory of a given size that can still be allocated

Spatial Performance

- Degree of fragmentation:
 - ▶ The **number** of contiguous pieces of memory of a given size that can still be allocated
- Administrative space:
 - ▶ **meta** data structures (used, free lists)

There is a trade-off
between
temporal and spatial
performance

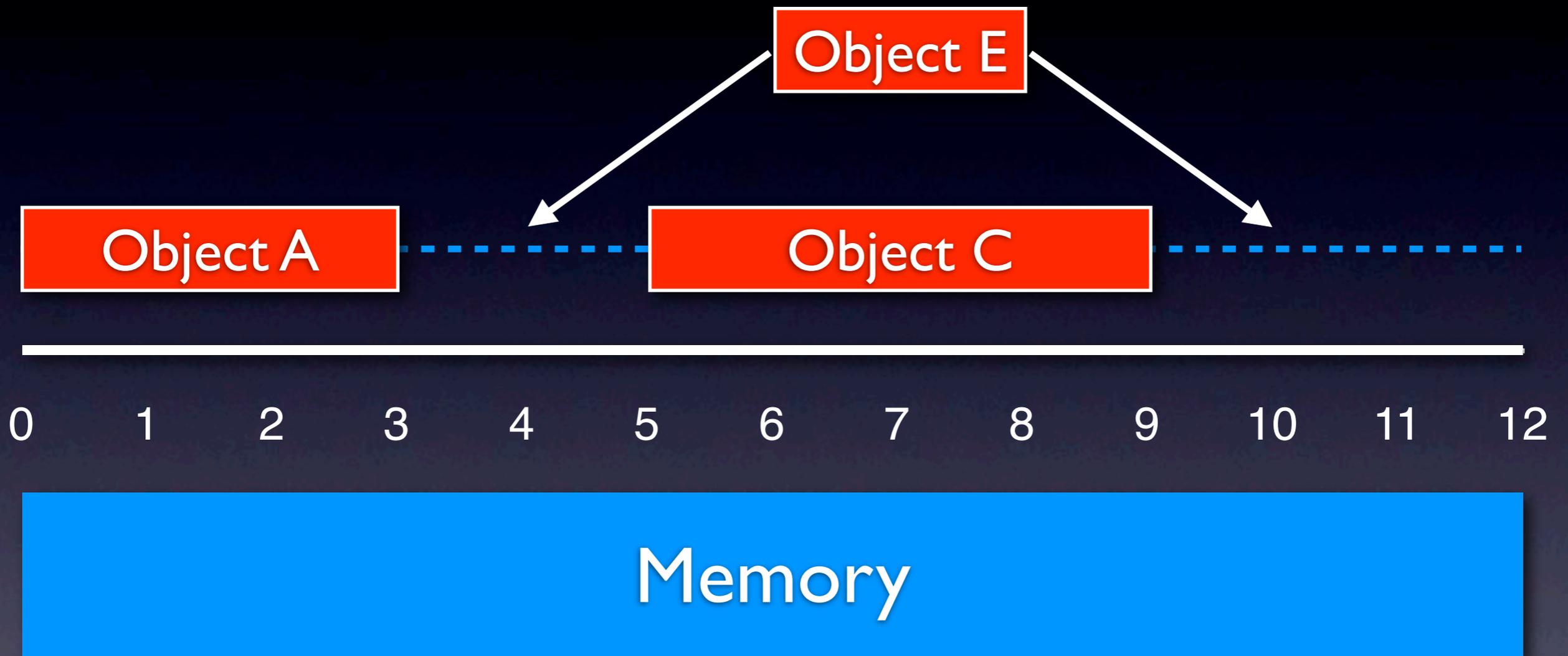
Temporal Predictability

- Unpredictable complexity (in terms of input):
 - ▶ **allocation/deallocation** may take time proportional to the total size of memory

Temporal Predictability

- Unpredictable complexity (in terms of input):
 - ▶ **allocation/deallocation** may take time proportional to the total size of memory
- Predictable complexity (in terms of input):
 - ▶ **allocation/deallocation** takes time at most proportional to the size of involved object
 - ▶ **access** takes time at most proportional to the size of involved object

Allocation Complexity



It may be difficult to
improve

average **performance**

but it may still be possible to
improve

predictability

without loosing too much

performance

Spatial Predictability

- Unpredictable fragmentation:
 - ▶ the degree of fragmentation may depend on the full allocation and deallocation **history**, i.e., the order of invocations

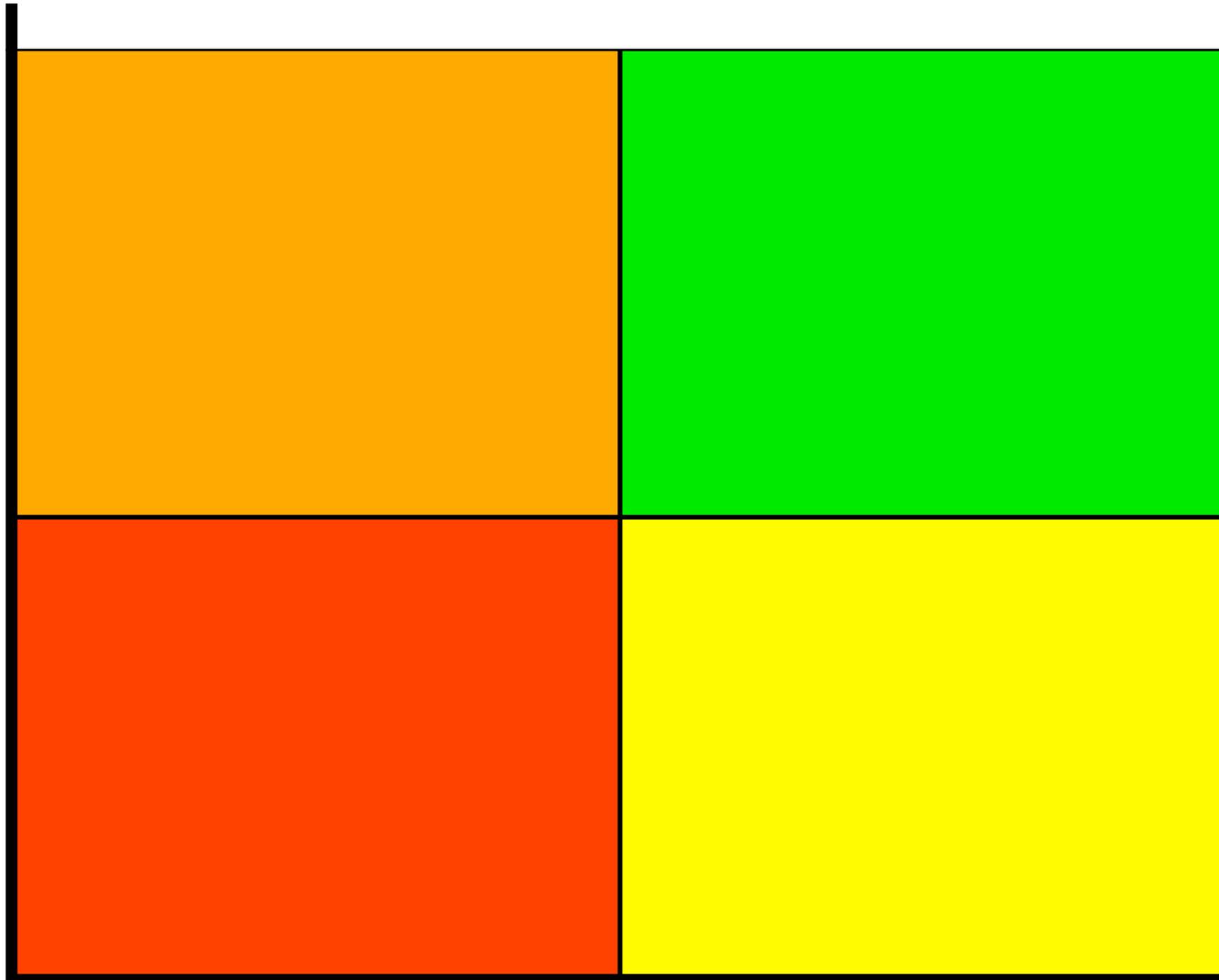
Spatial Predictability

- Unpredictable fragmentation:
 - ▶ the degree of fragmentation may depend on the full allocation and deallocation **history**, i.e., the order of invocations
- Predictable fragmentation:
 - ▶ the degree of fragmentation only depends on the **number** of allocations and deallocations, independently of the order of invocations

Time

predictable

unpredictable



unpredictable

predictable

Space

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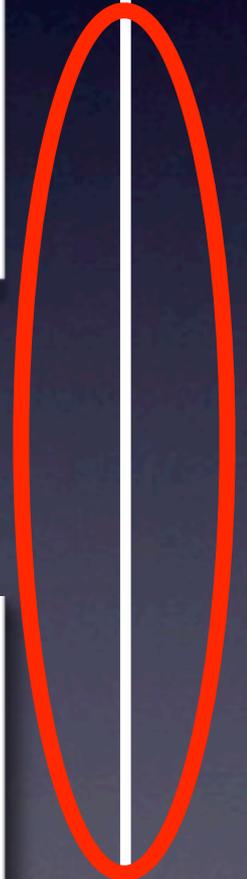
Web, Safety

Explicit

Server, Performance

Static

Embedded, Real Time



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- Silviu Craciunas[#] (Programming Model)
- Andreas Haas (Memory Management)
- Hannes Payer[#] (Memory Management)
- Harald Röck (VM, Scheduling)
- Ana Sokolova^{*} (Theoretical Foundation)

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^{*}Supported by Austrian Science Fund Project V00125.

Tiptoe

- Tiptoe is a microkernel-based virtual machine and process monitor for embedded systems

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- Tiptoe virtualizes the host platform (system VM) and provides infrastructure to run process VMs and processes in real time

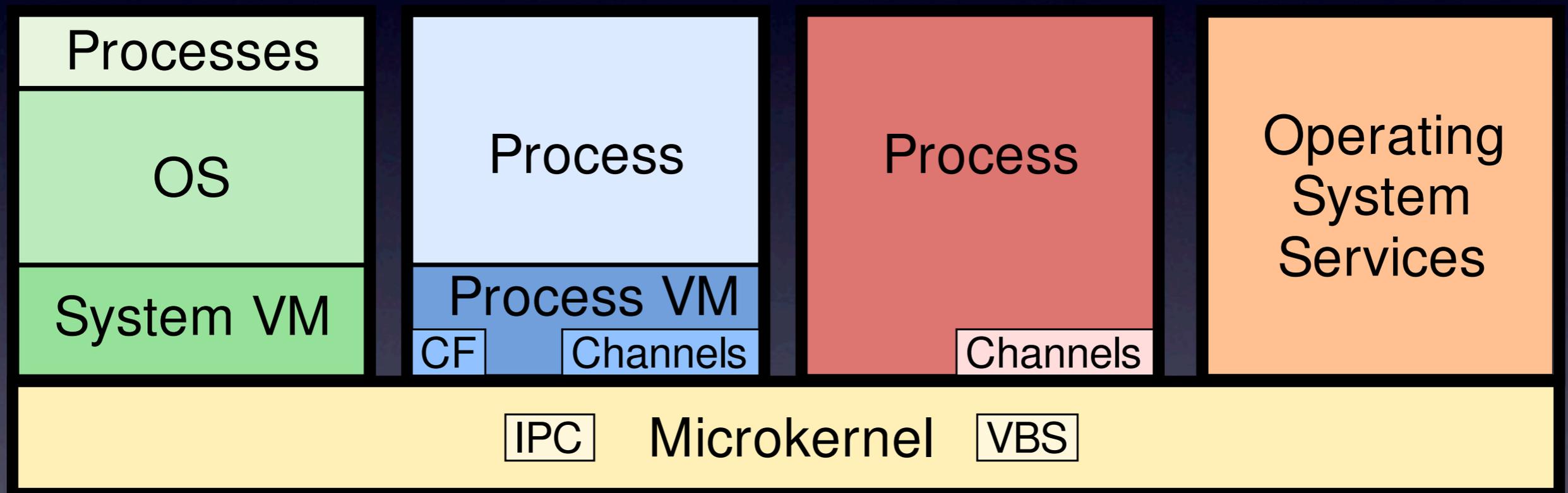
Tiptoe

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- Tiptoe controls throughput and latency of CPU, memory, and I/O

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- Tiptoe virtualizes the host platform (system VM) and provides infrastructure to run process VMs and processes in real time
- Tiptoe controls throughput and latency of CPU, memory, and I/O
- I/O is multiplexed through IPC to a system VM running Linux

Tiptoe





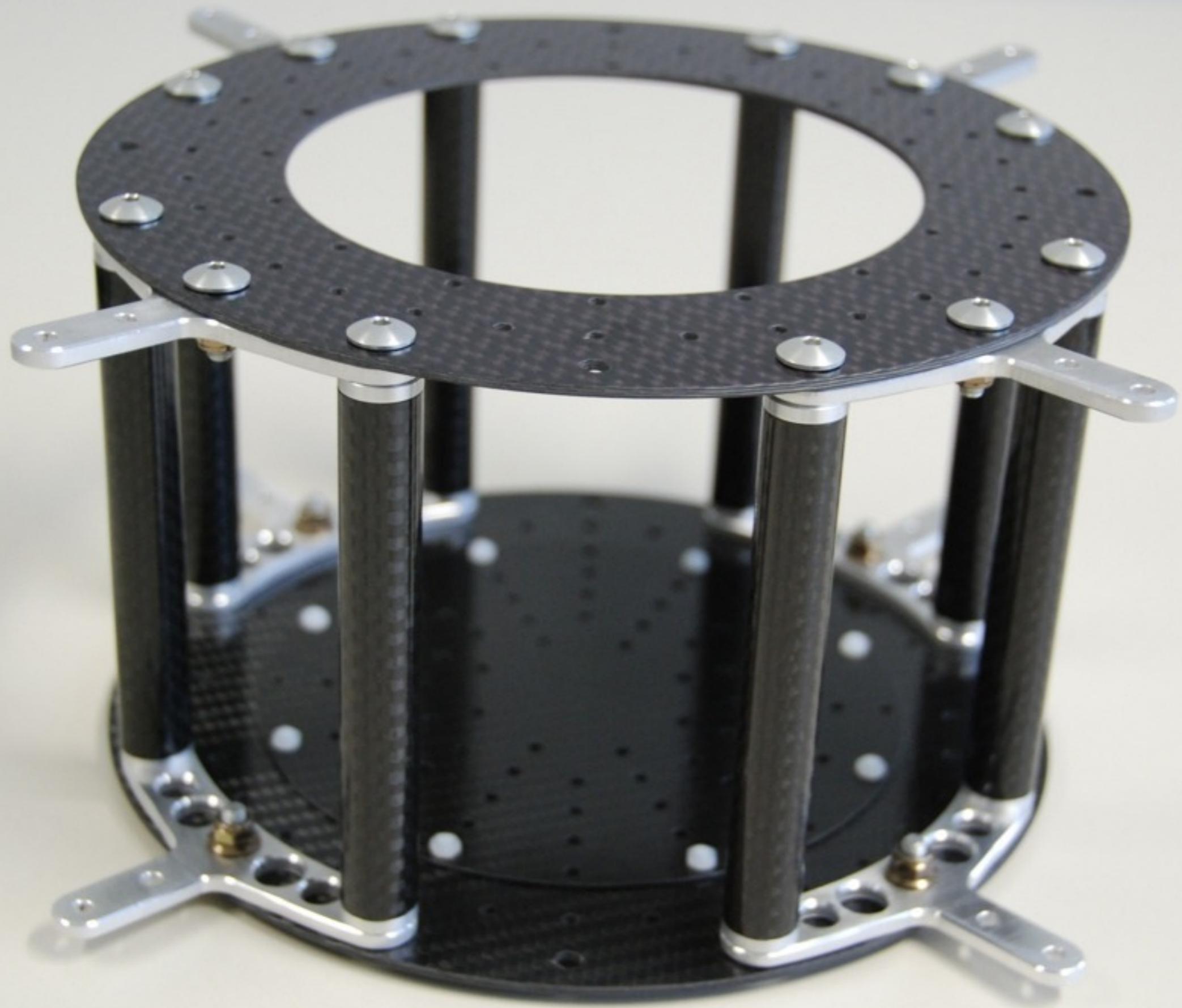
The JAviator

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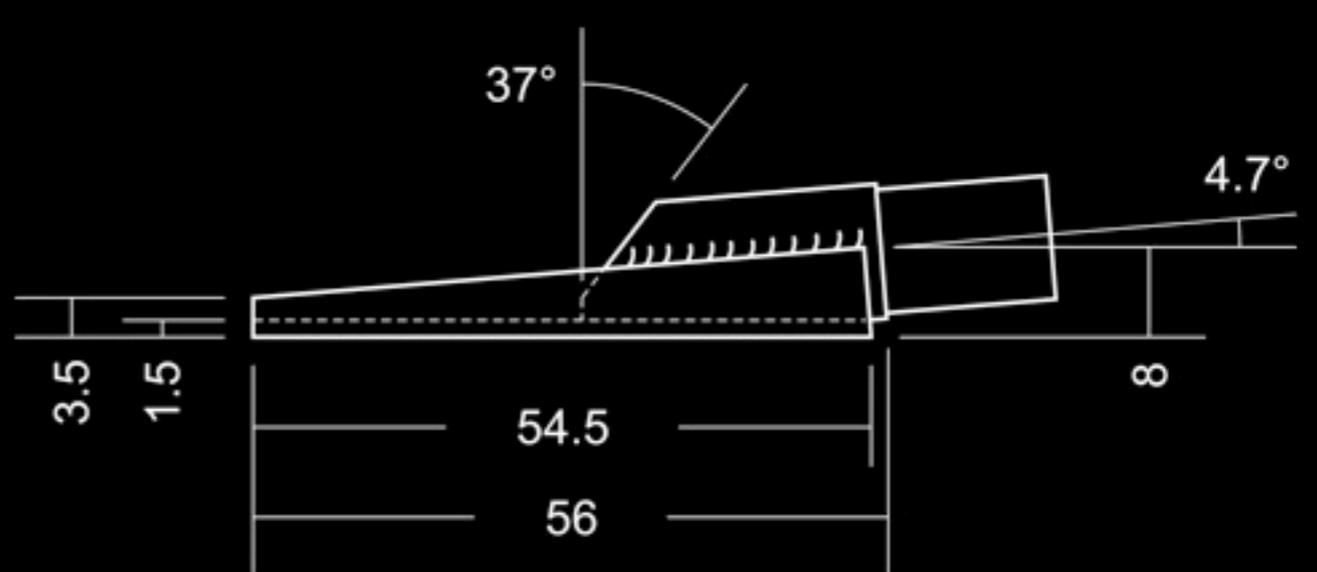
Quad-Rotor Helicopter

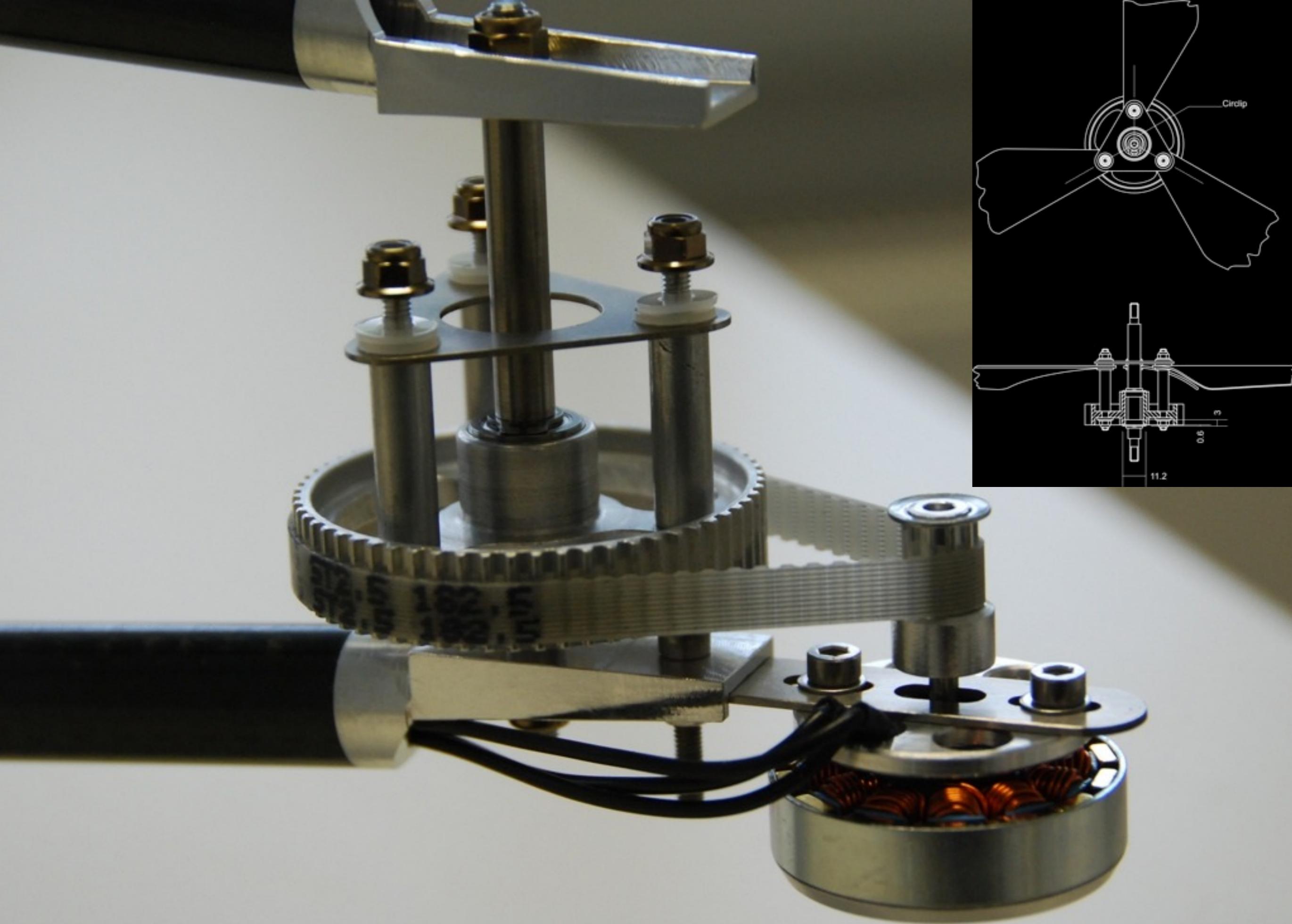






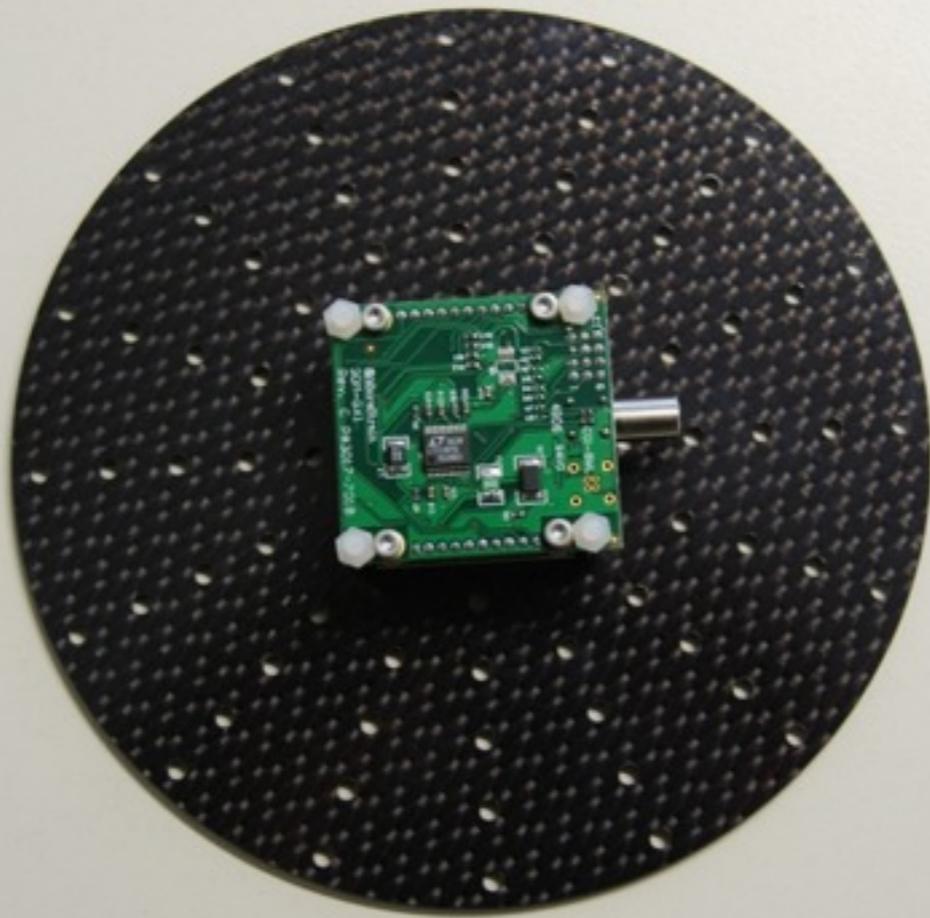






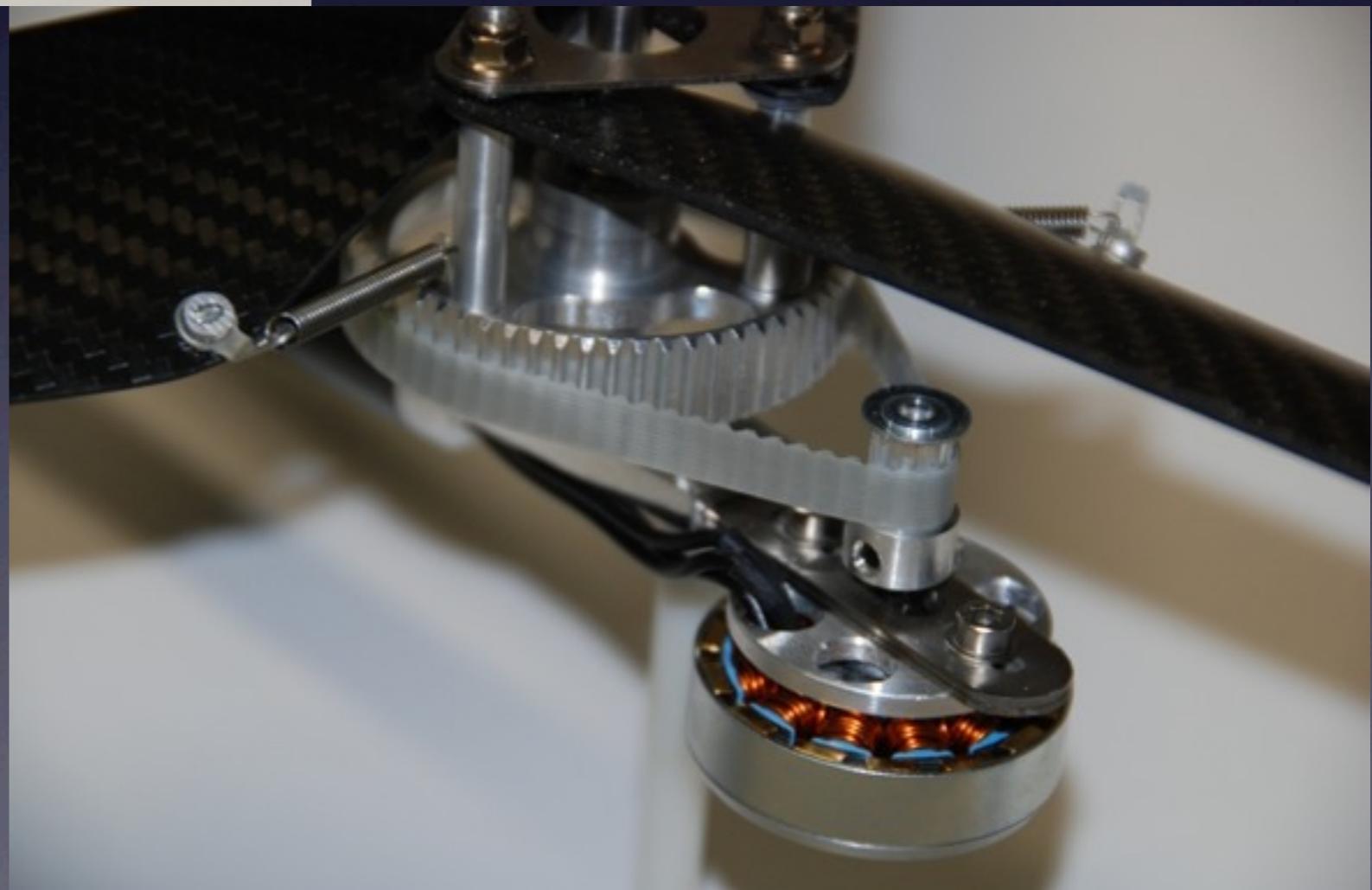




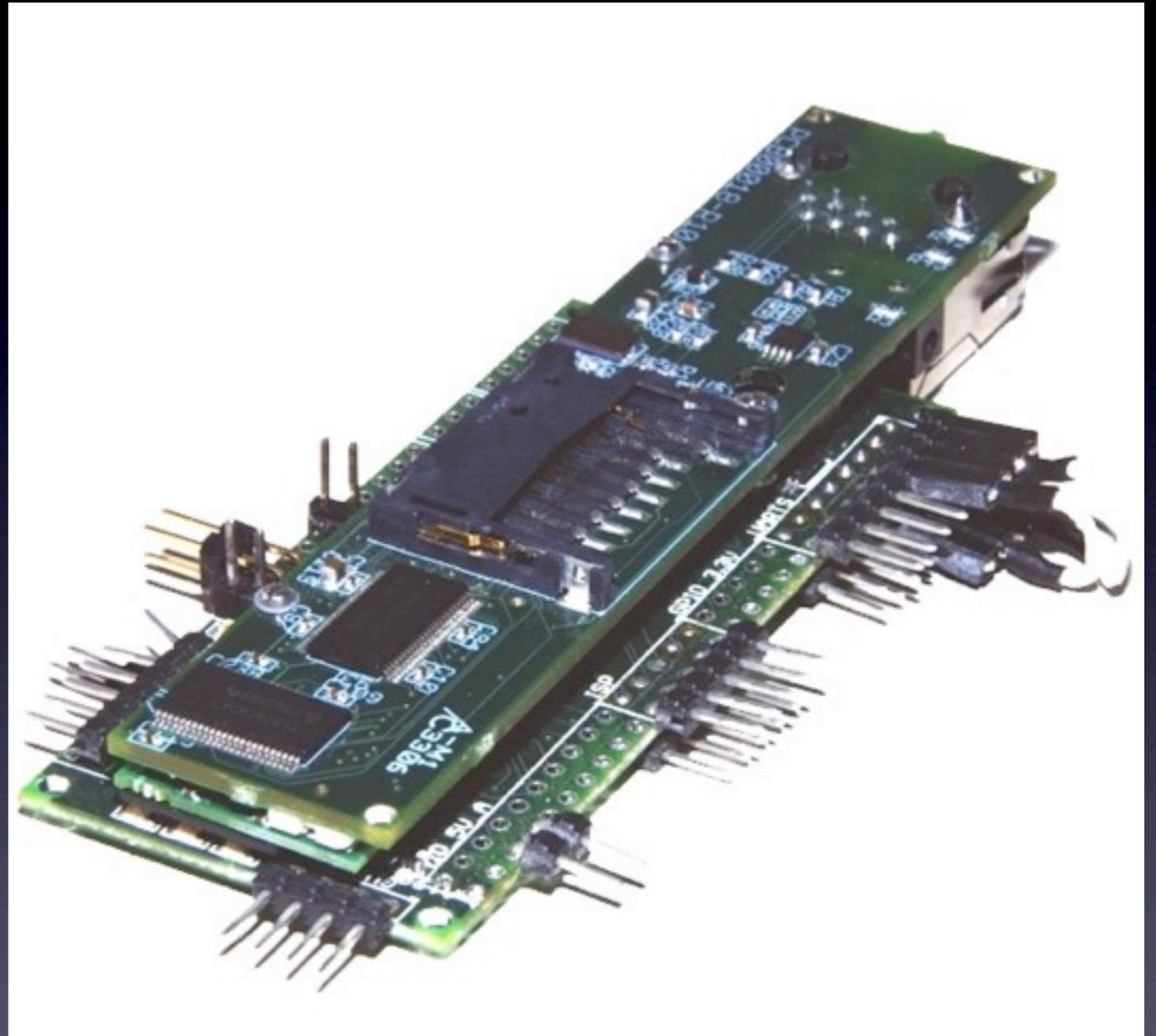


Gyro

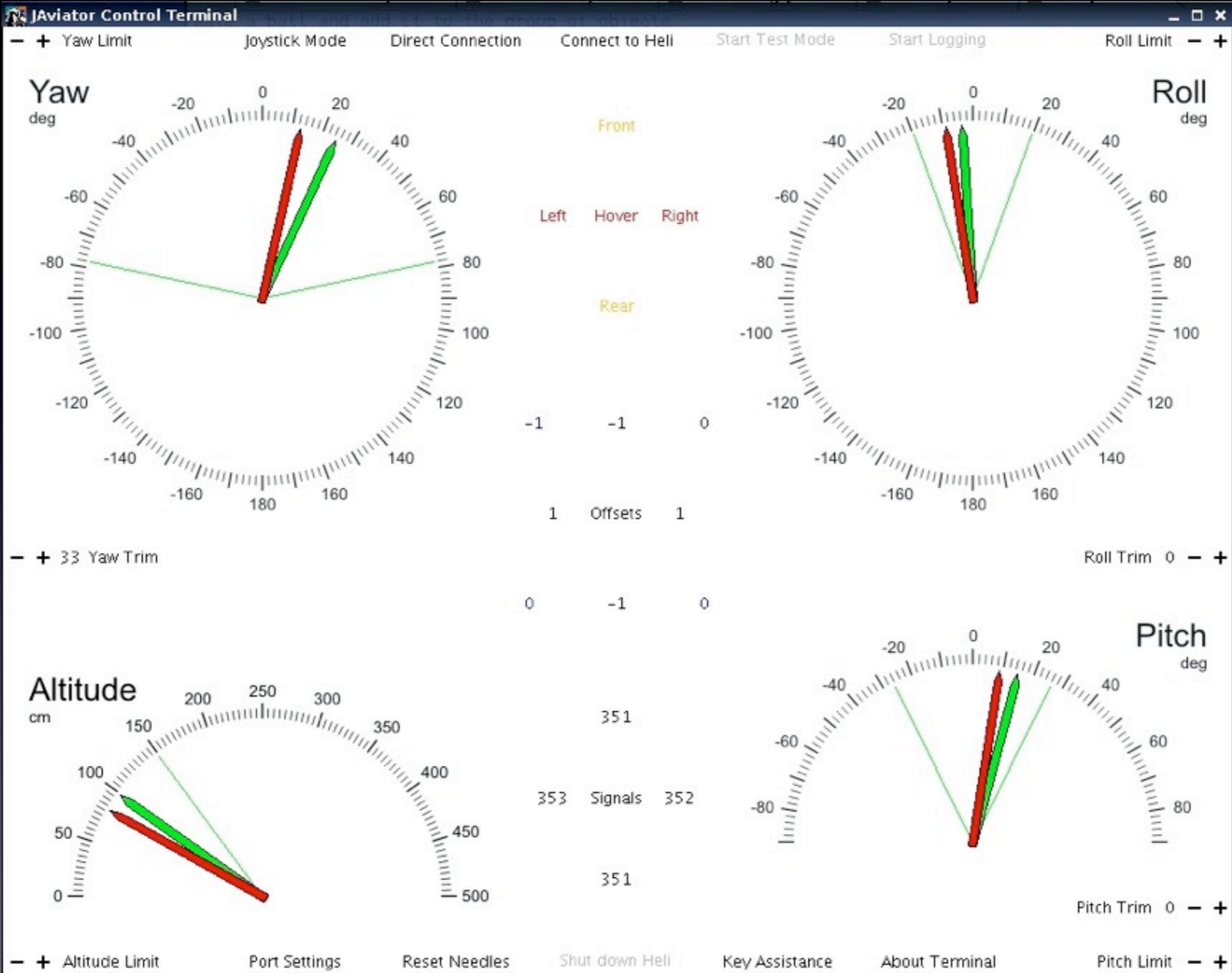
Propulsion

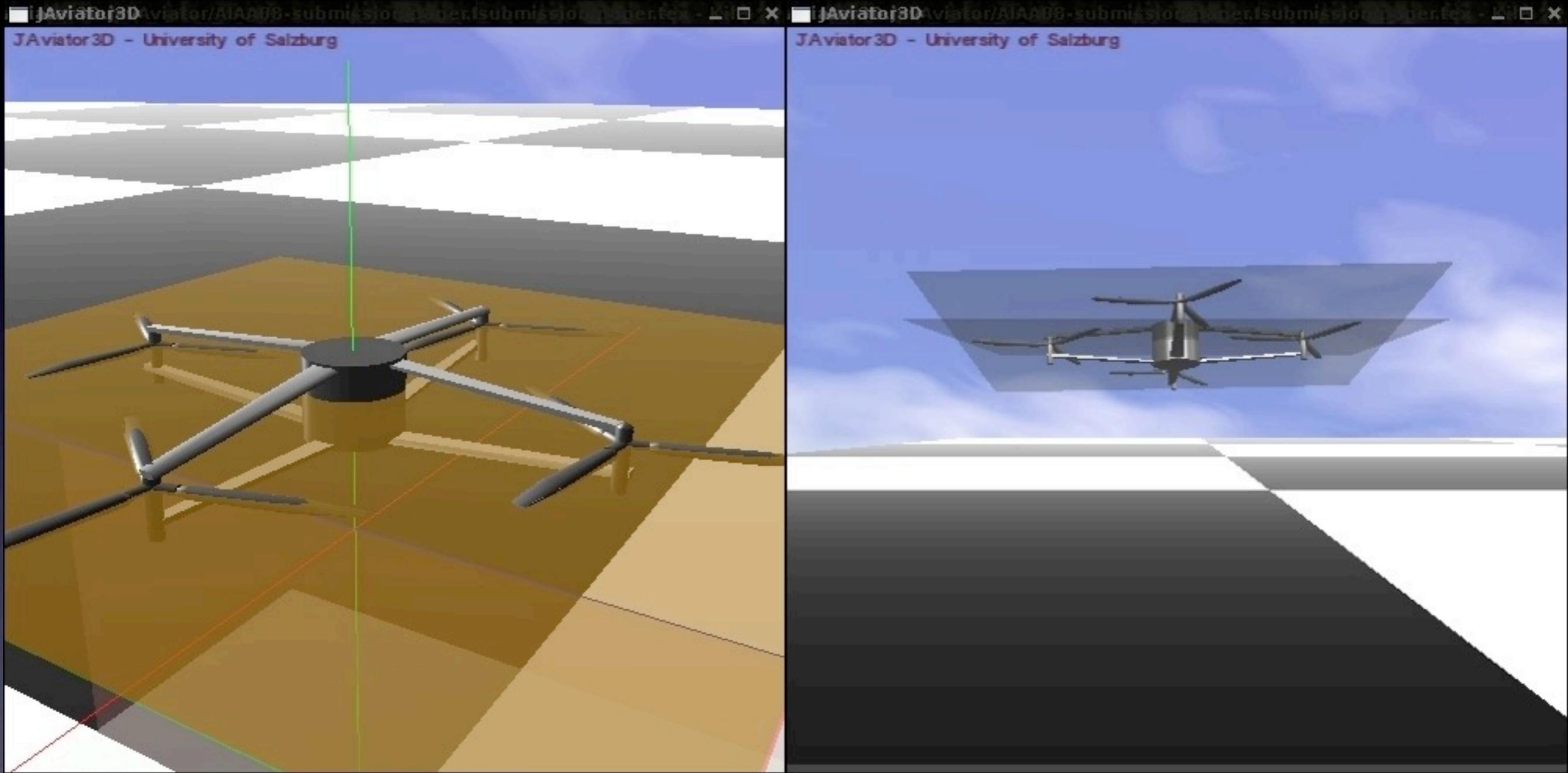


Gumstix



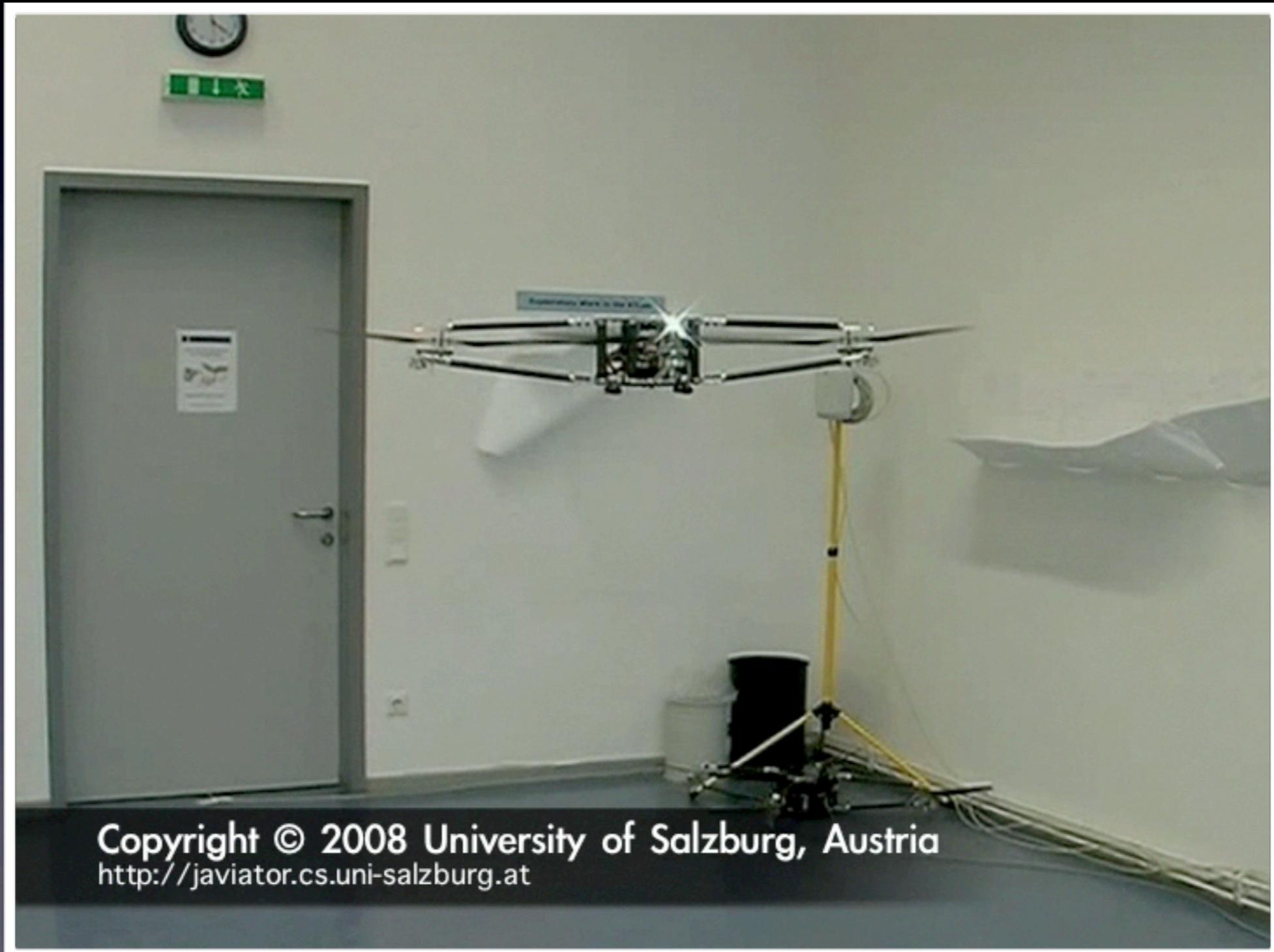
600MHz XScale, 128MB RAM, WLAN, Atmega uController





Indoor Flight STARMAC Controller

Indoor Flight STARMAC Controller



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Outdoor Flight STARMAC Controller

Outdoor Flight STARMAC Controller



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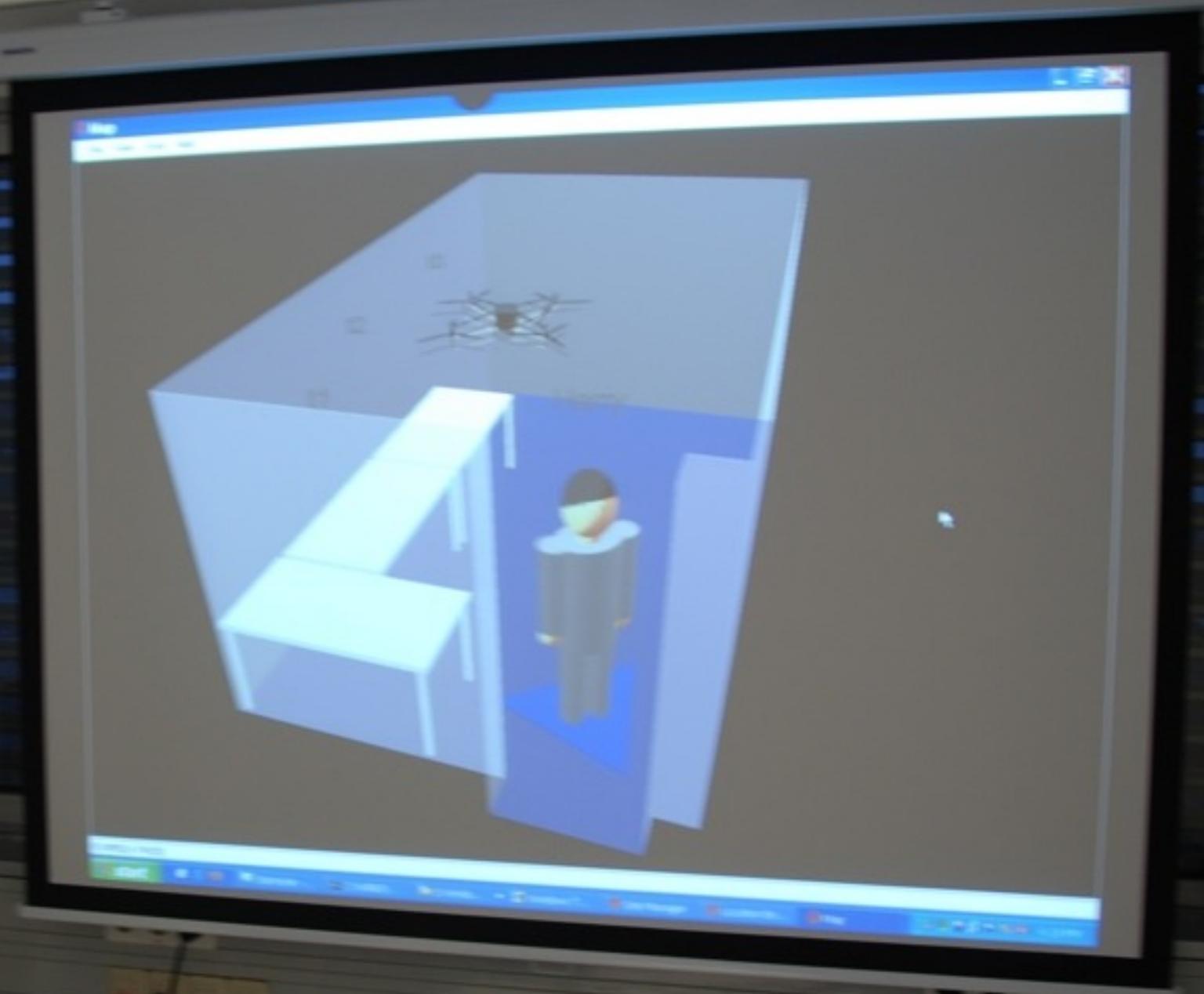
What's next?

- Autonomous single-vehicle flights
 - position controller
 - waypoint controller

What's next?

- Autonomous single-vehicle flights
 - position controller
 - waypoint controller
- Autonomous multi-vehicle flights
 - mission controller

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Salzburg Soft Walls Controller on JJ

Salzburg Soft Walls Controller on JJ

