

# Power-Aware Temporal Isolation with Variable-Bandwidth Servers

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University of Salzburg





# Process Model

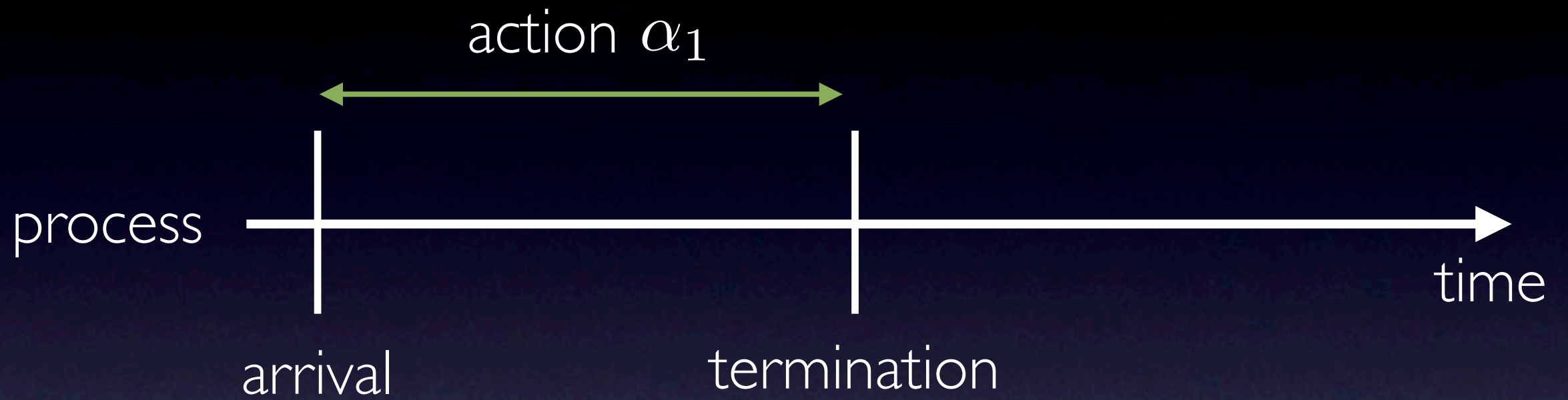
process



time



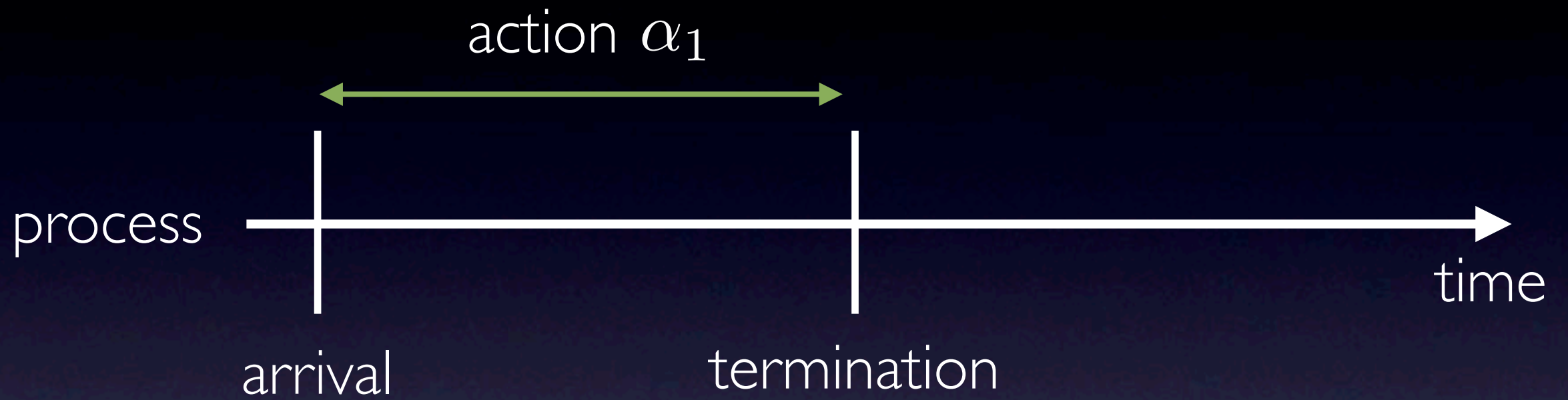
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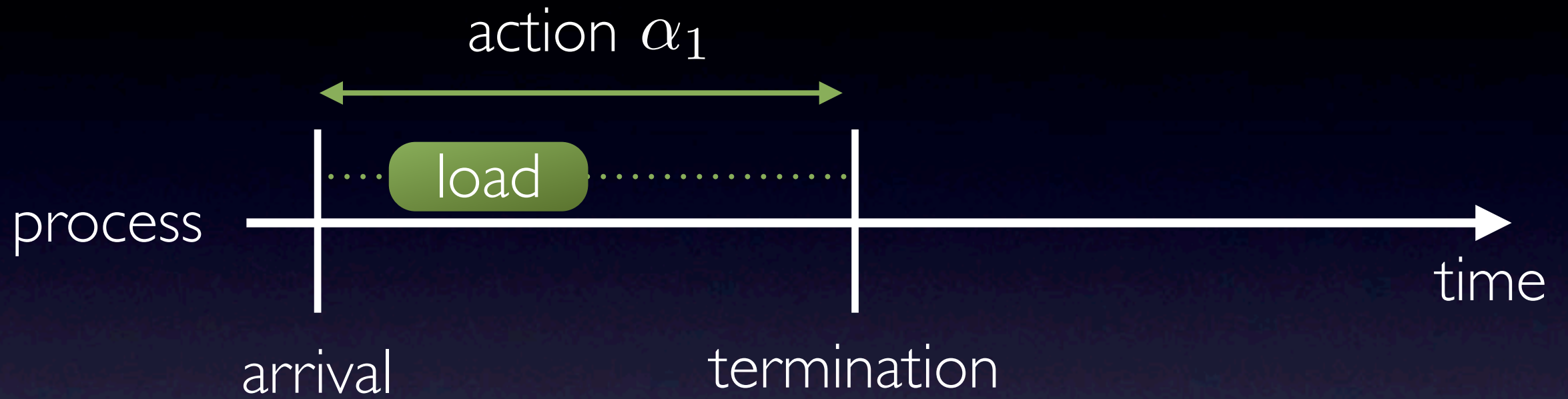
# Process Model



- action is a piece of code



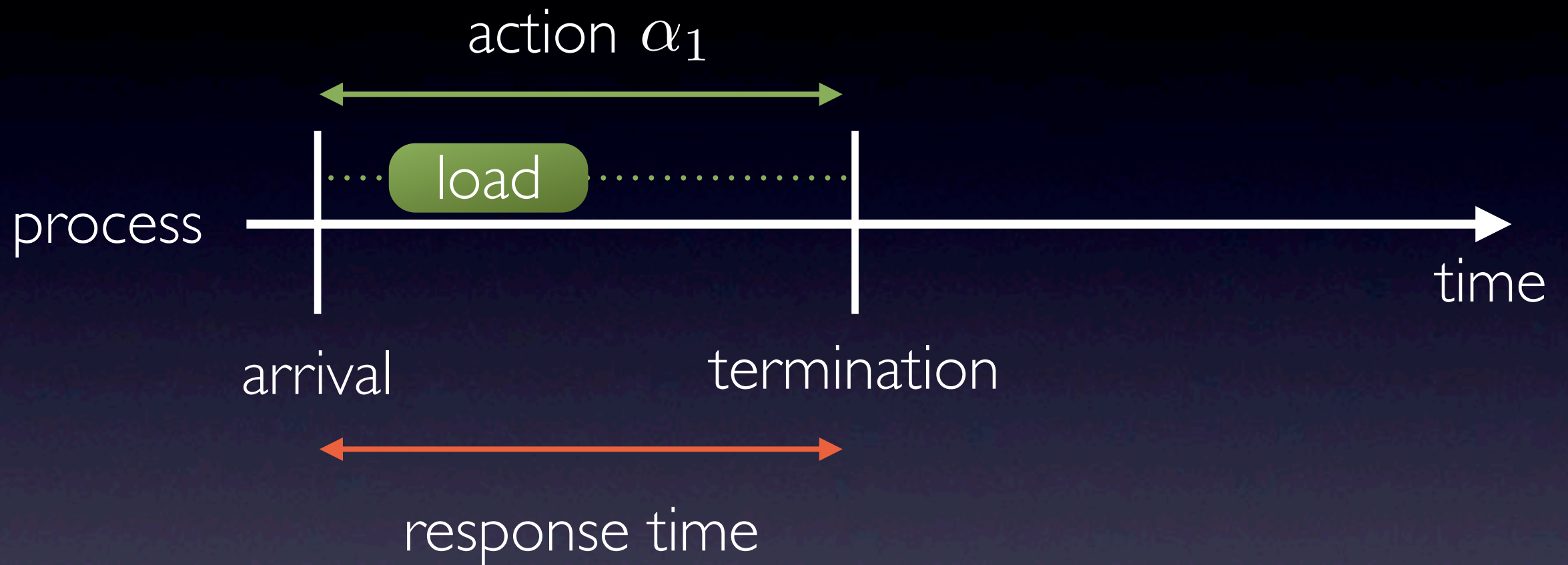
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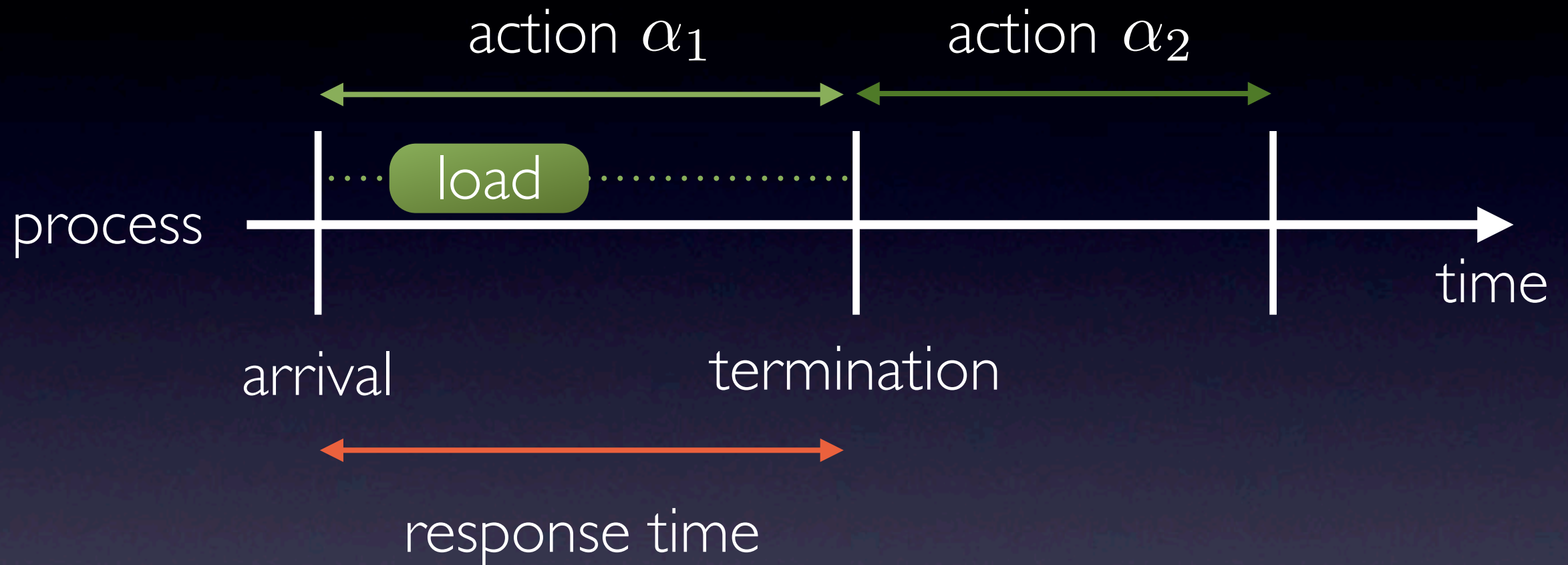


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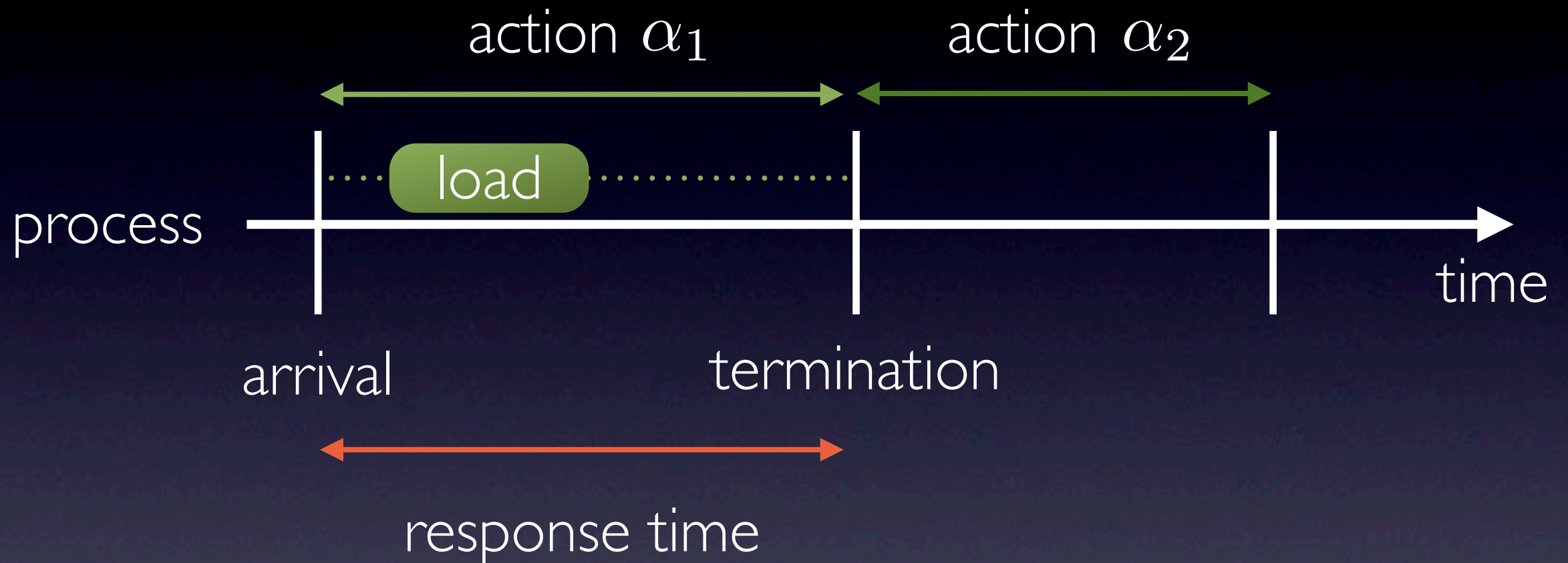
# Process Model



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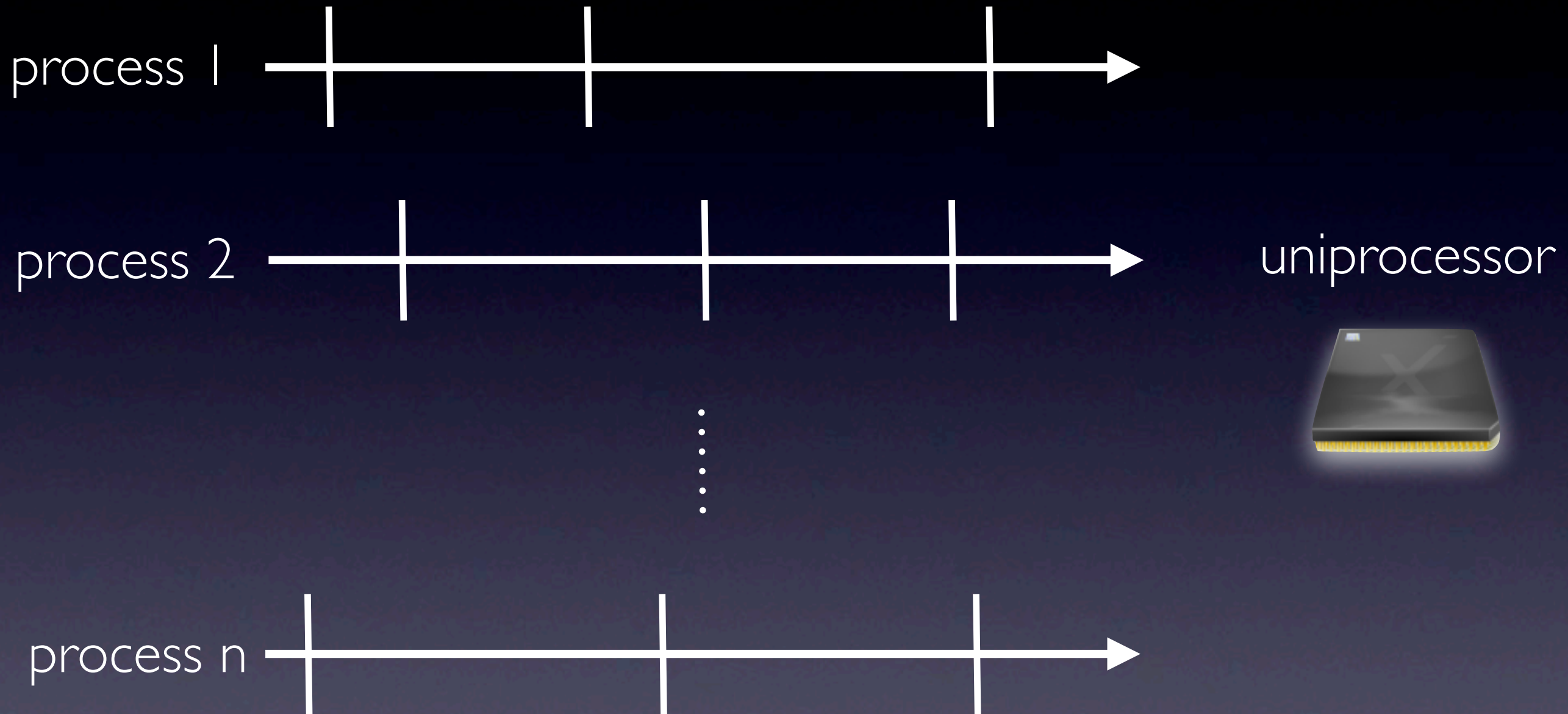


- action is a piece of code
- process is a sequence of actions
- throughput vs latency of process execution





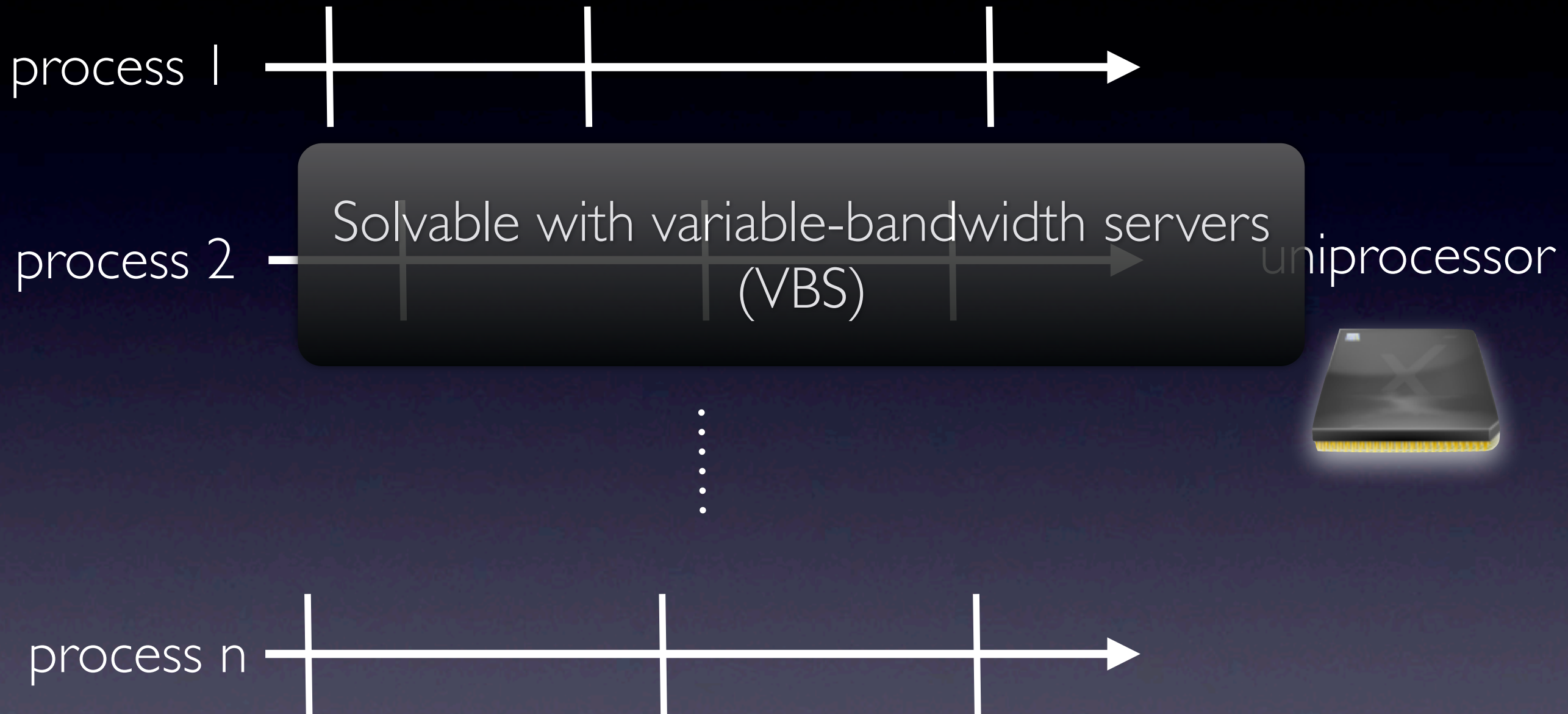
# Scheduling Problem



schedule the processes so that each of their actions maintains its response time



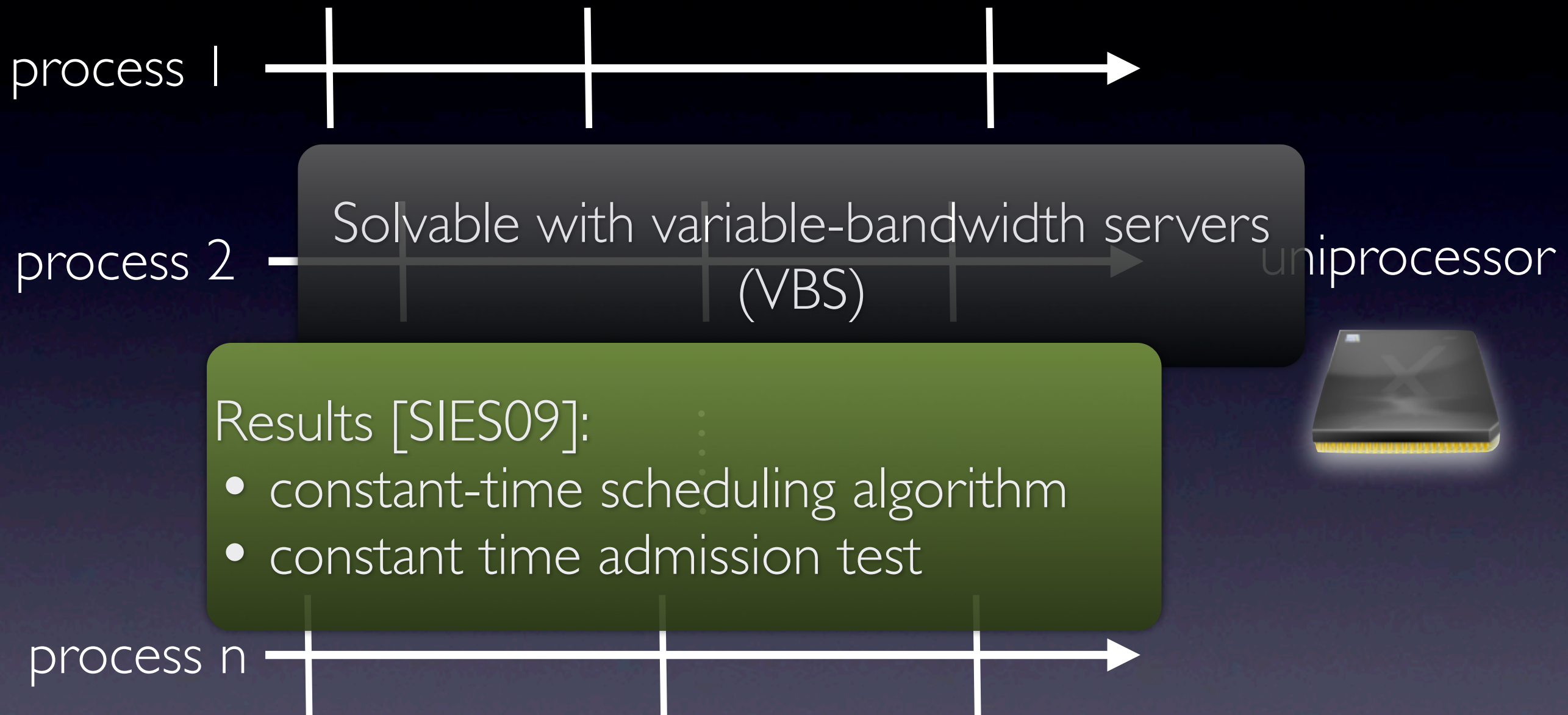
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# Resources and VBS

virtual periodic resources

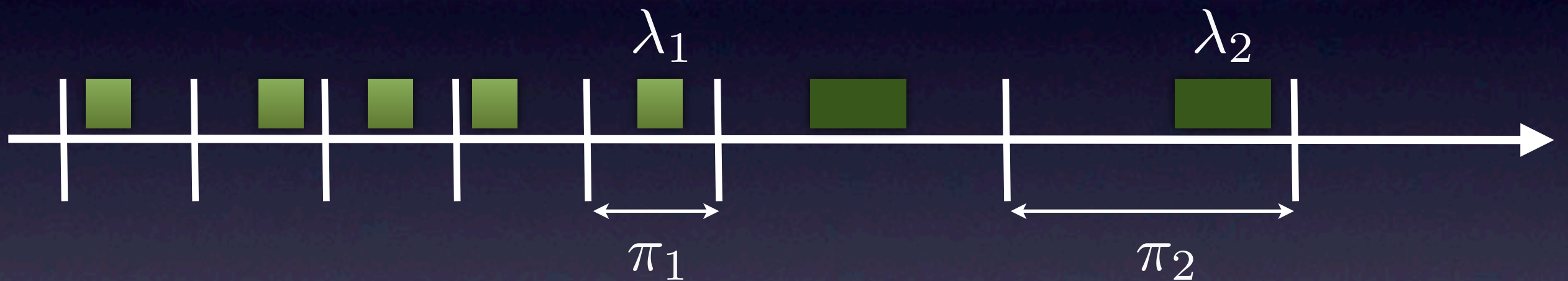
period  $\pi$     limit  $\lambda$     utilization  $\frac{\lambda}{\pi}$



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virtual periodic resources

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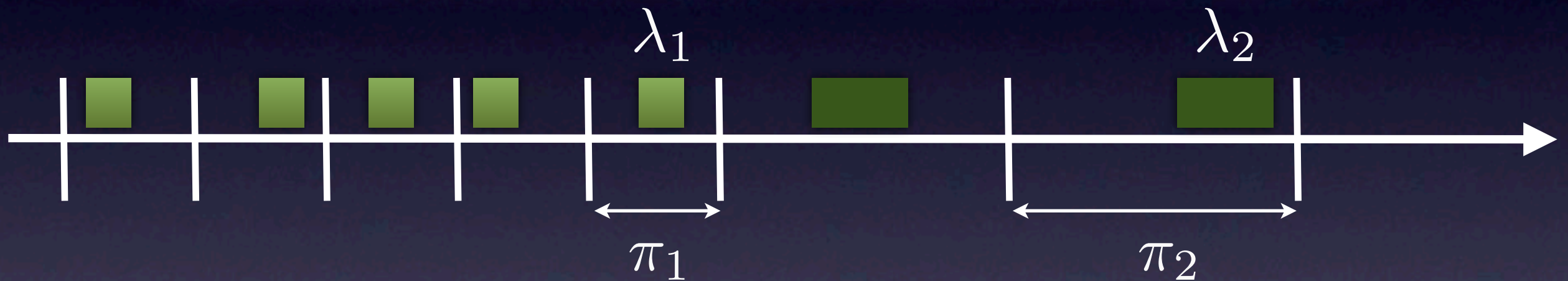




# Resources and VBS

virtual periodic resources

period  $\pi$     limit  $\lambda$     utilization  $\frac{\lambda}{\pi}$



- VBS is determined by a bandwidth cap ( $u$ )
- VBS processes dynamically adjust speed (change resources)

$$\frac{\lambda_1}{\pi_1} \leq u \qquad \frac{\lambda_2}{\pi_2} \leq u$$

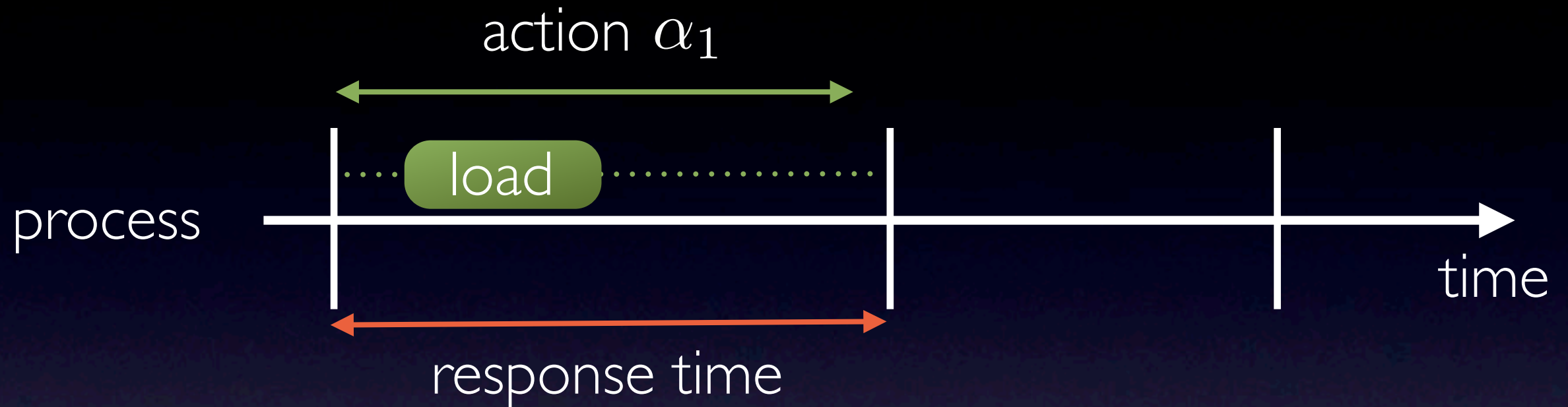
- generalization of constant bandwidth servers (CBS)

[Abeni and Buttazzo 2004]



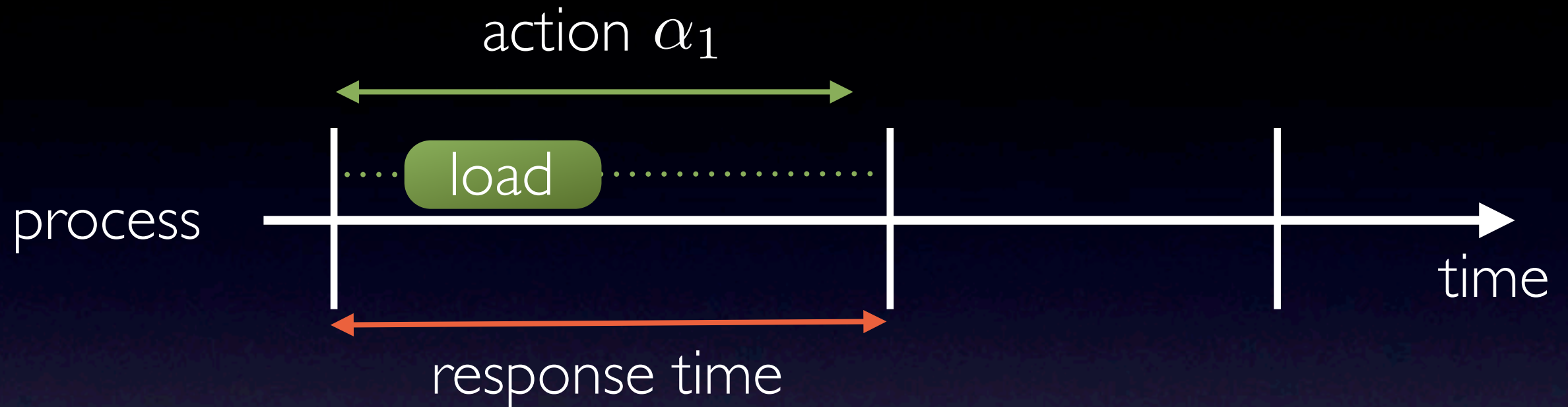


# One Process on a VBS



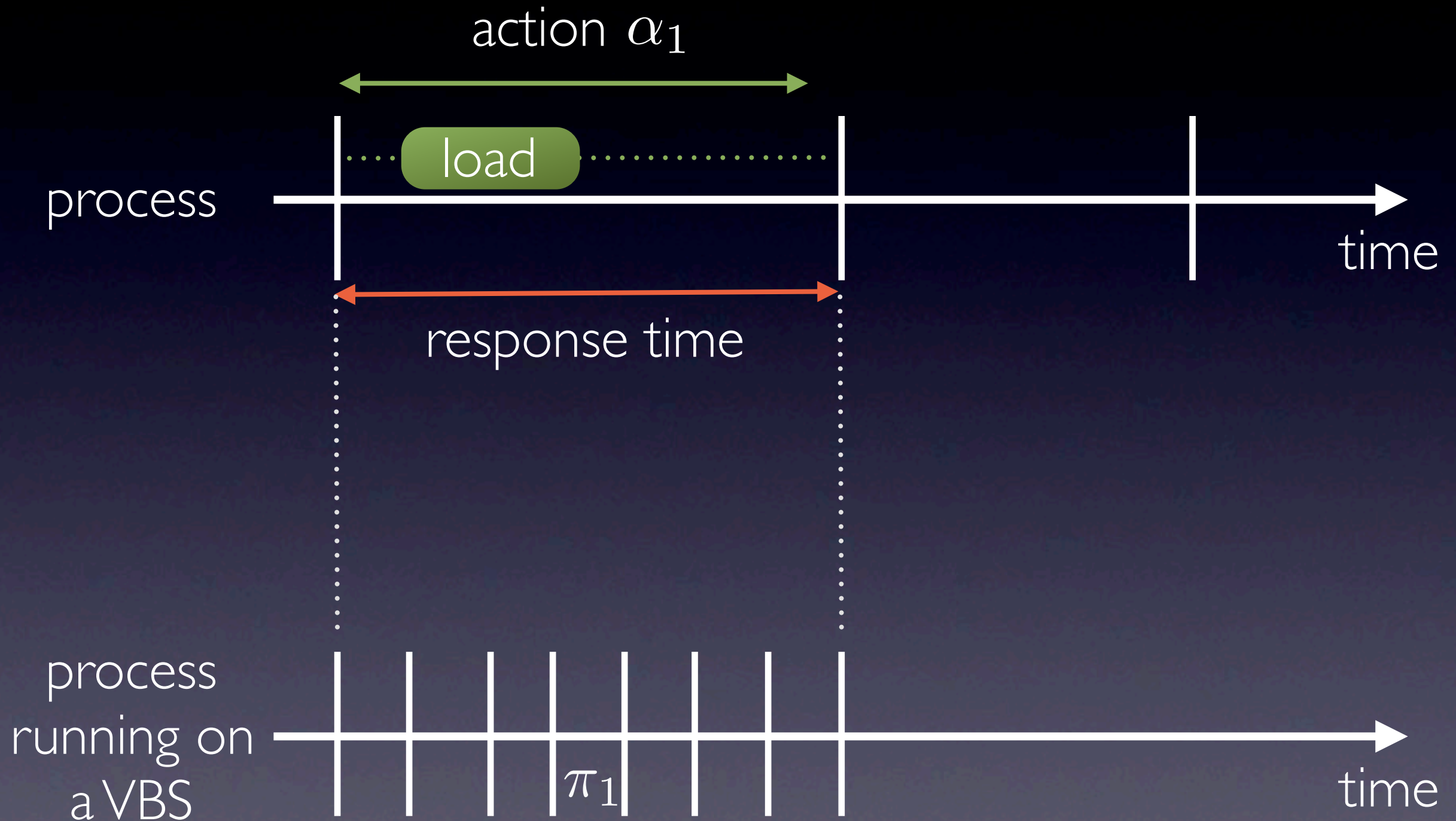


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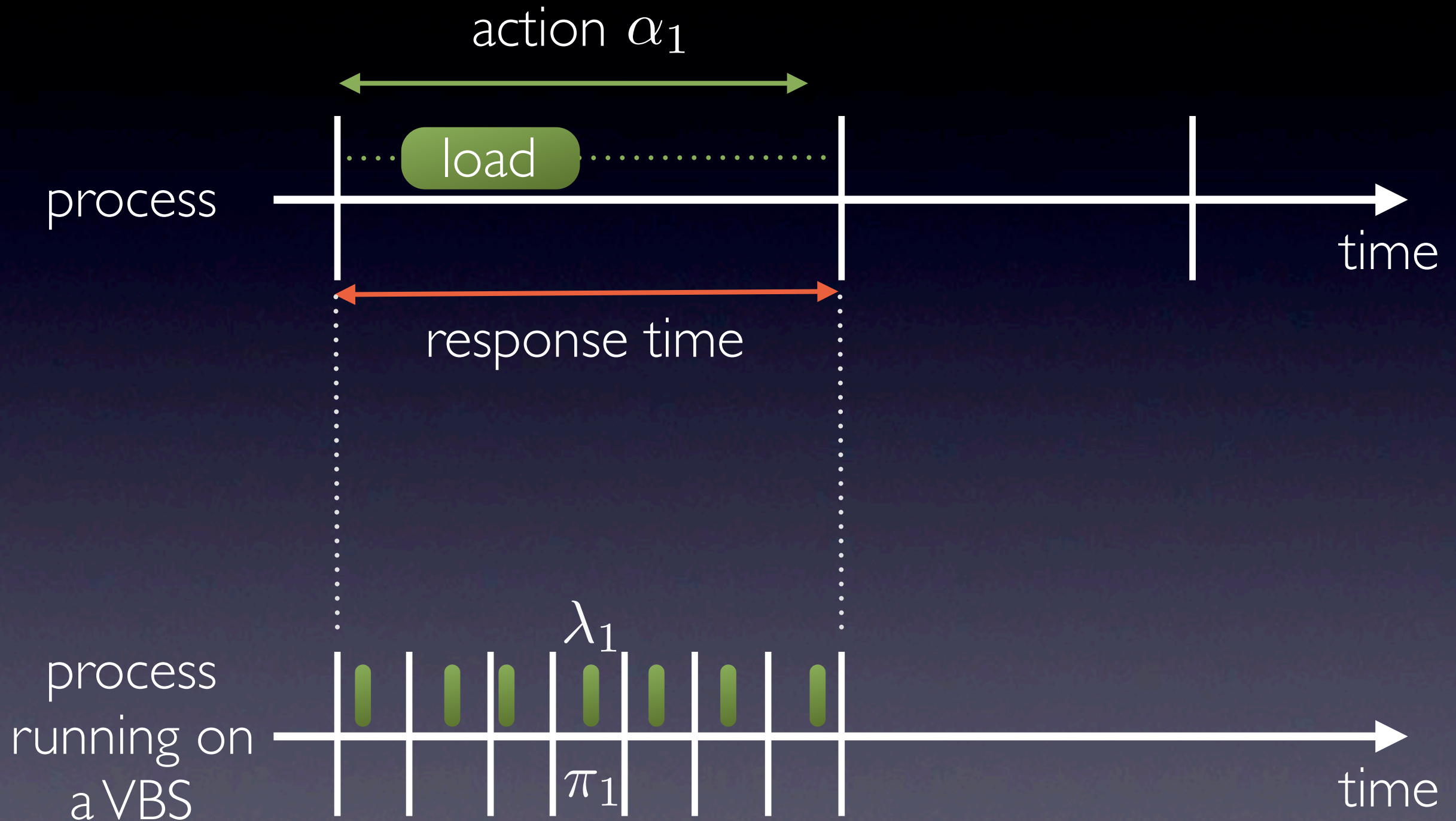
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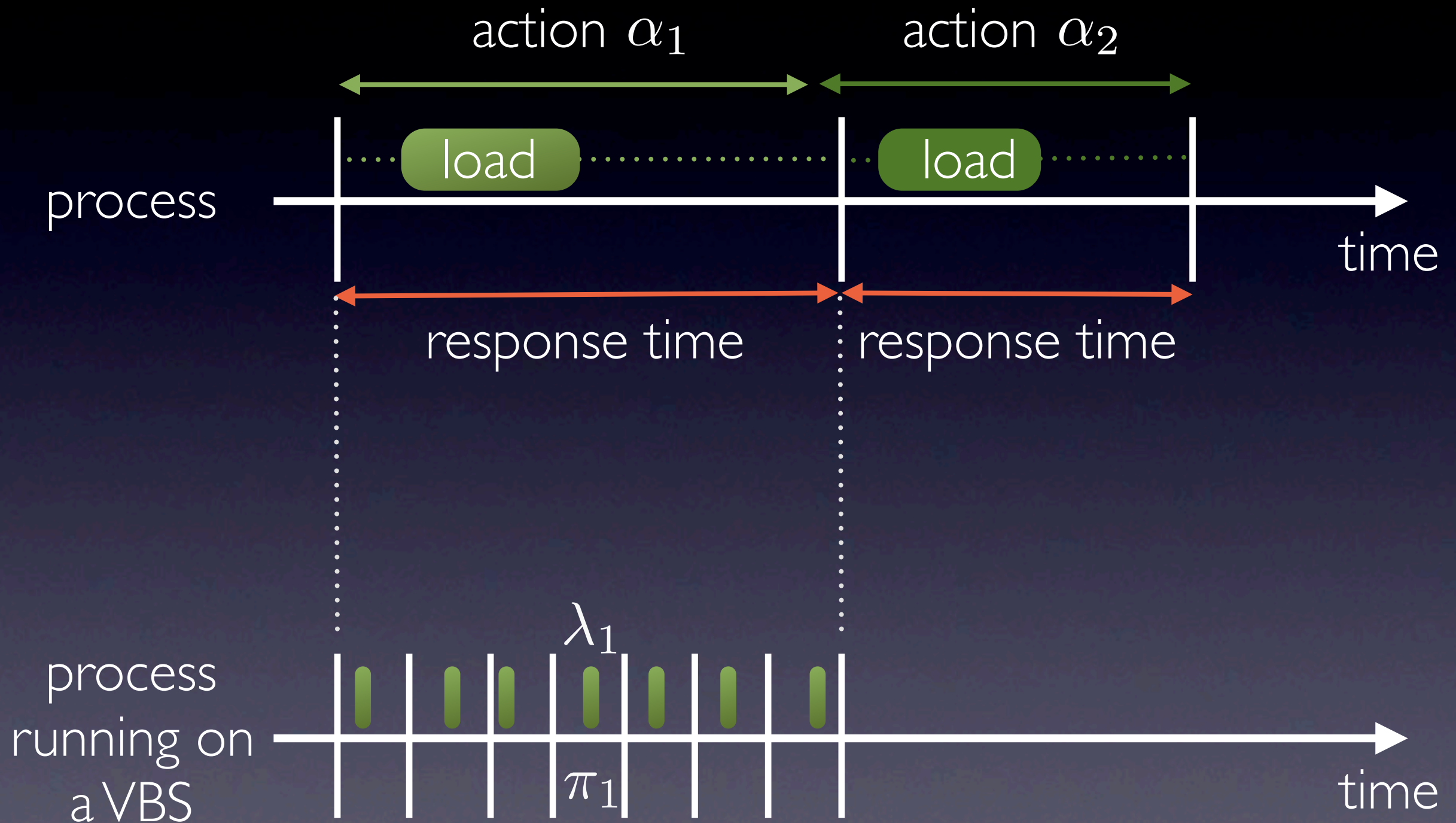


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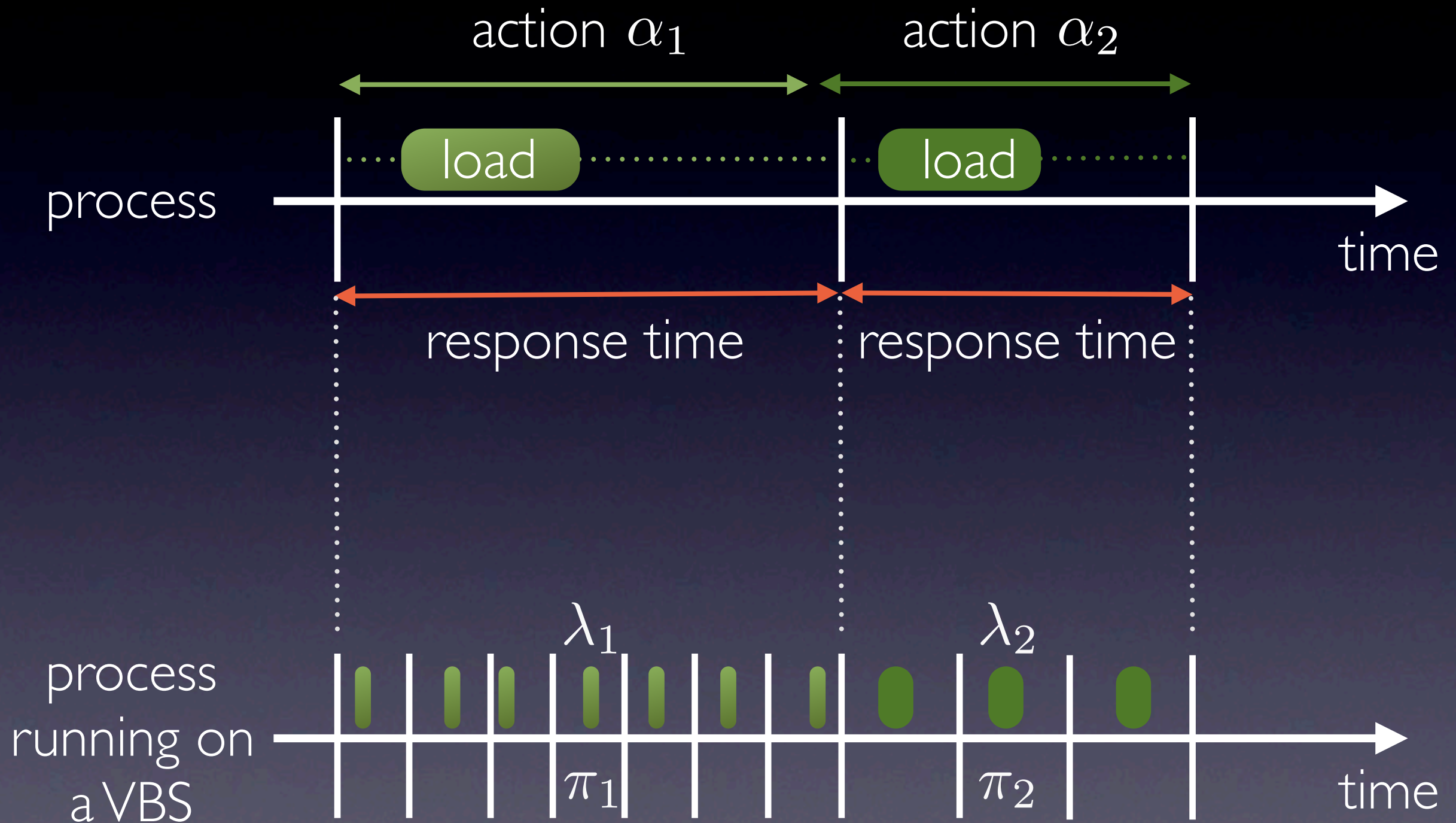


# One Process on a VBS





# One Process on a VBS







# VBS

process  
running on  
a VBS



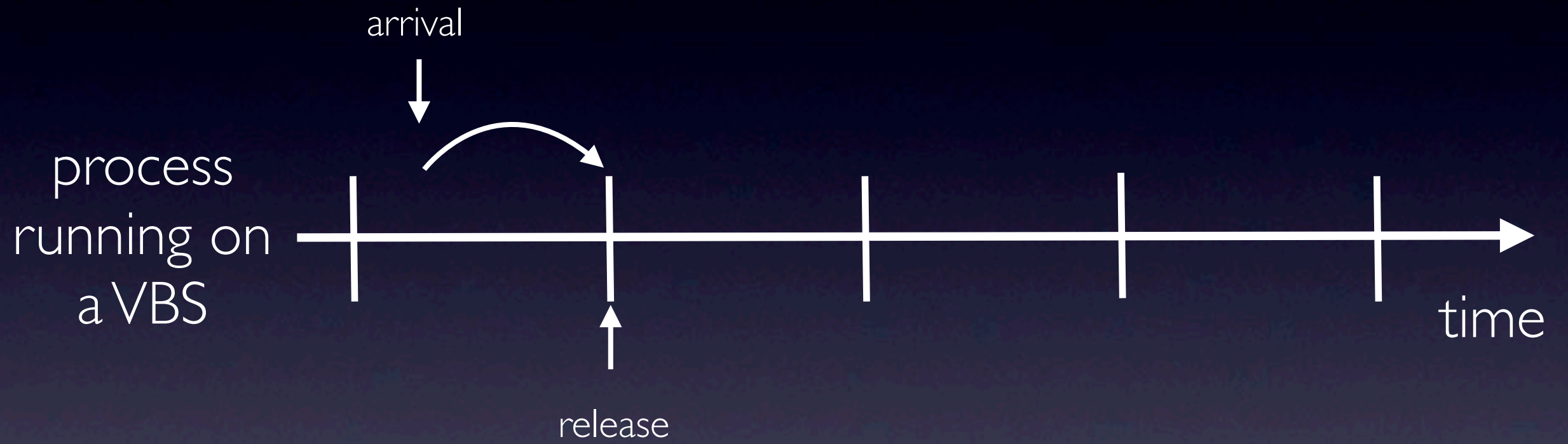


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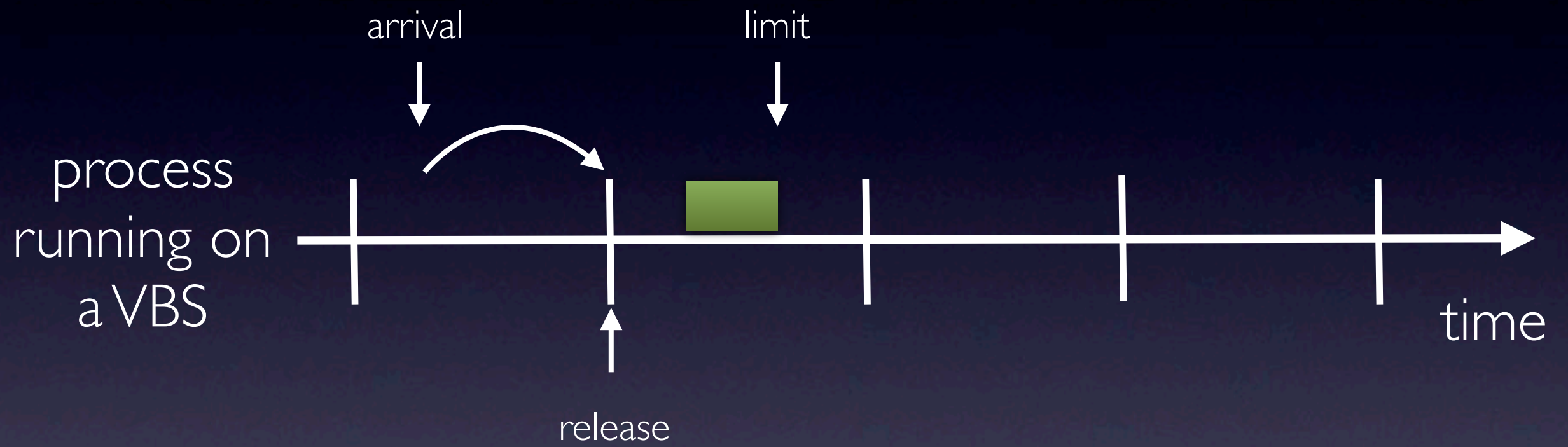
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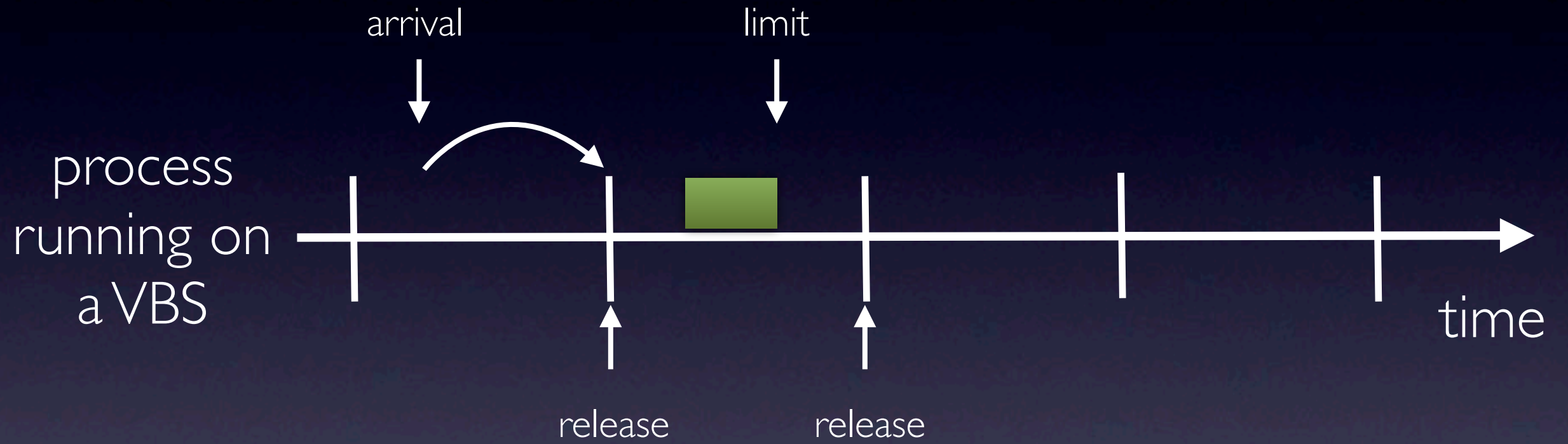


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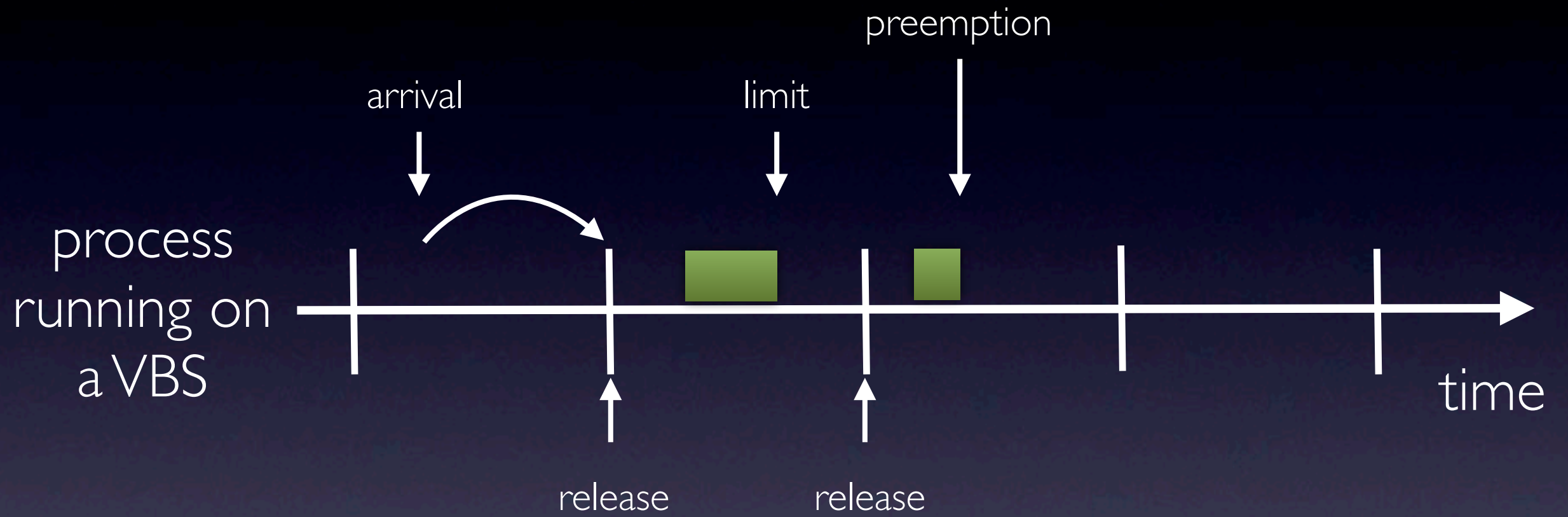


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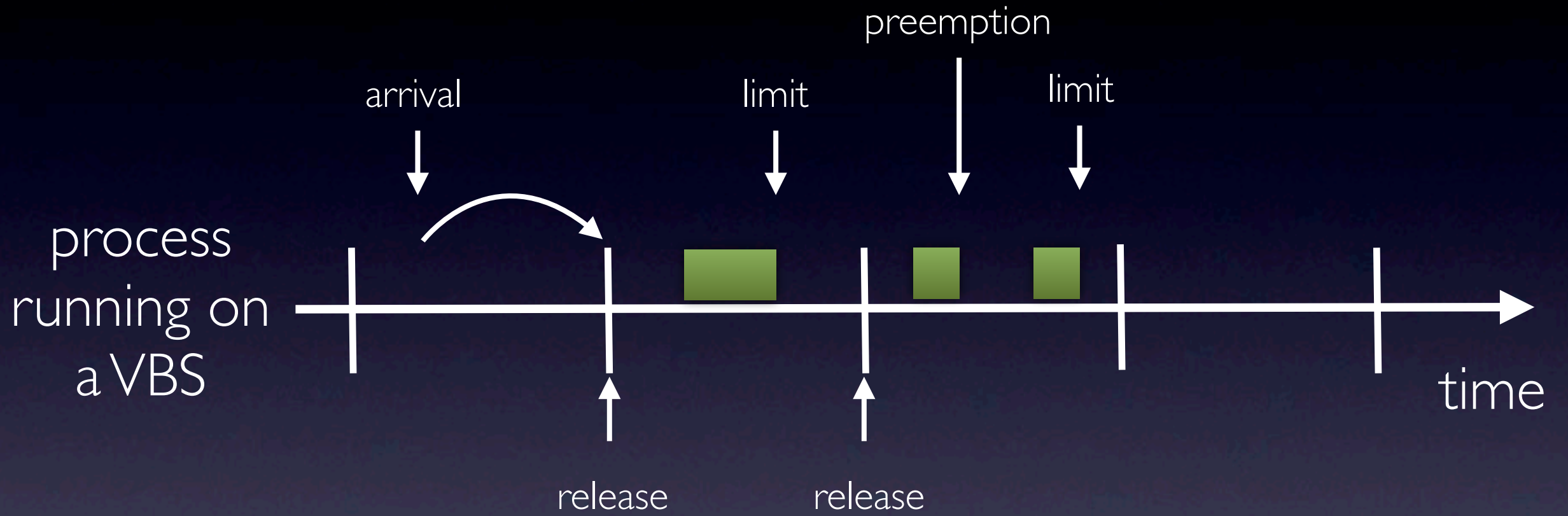
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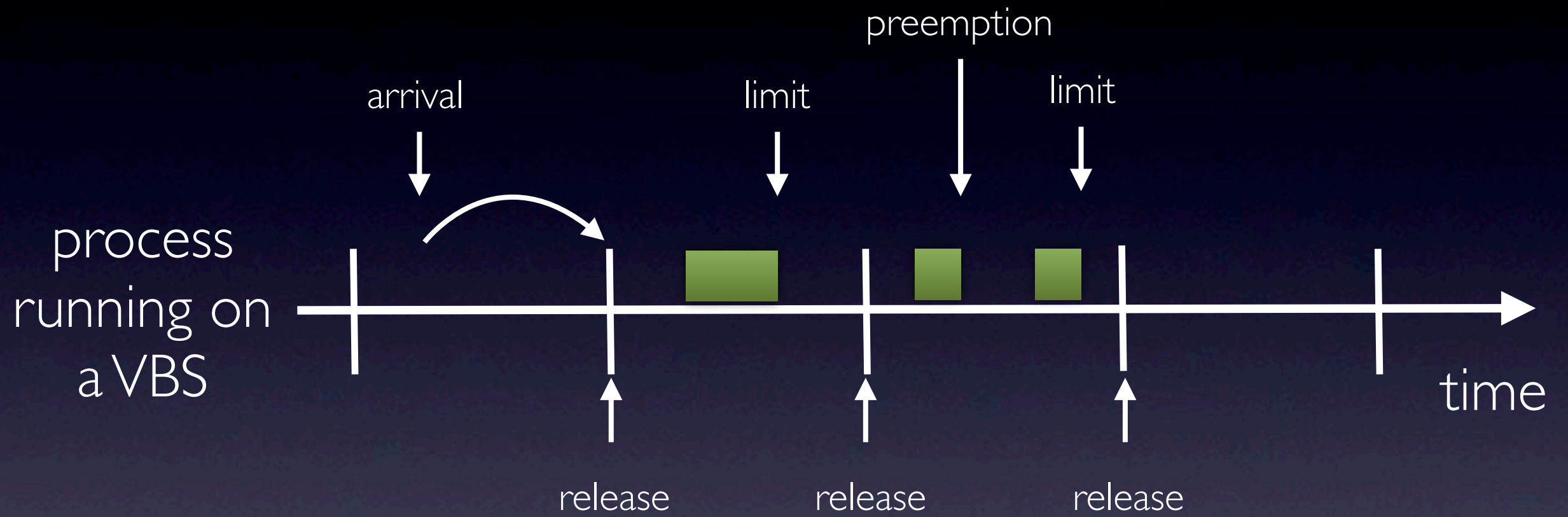


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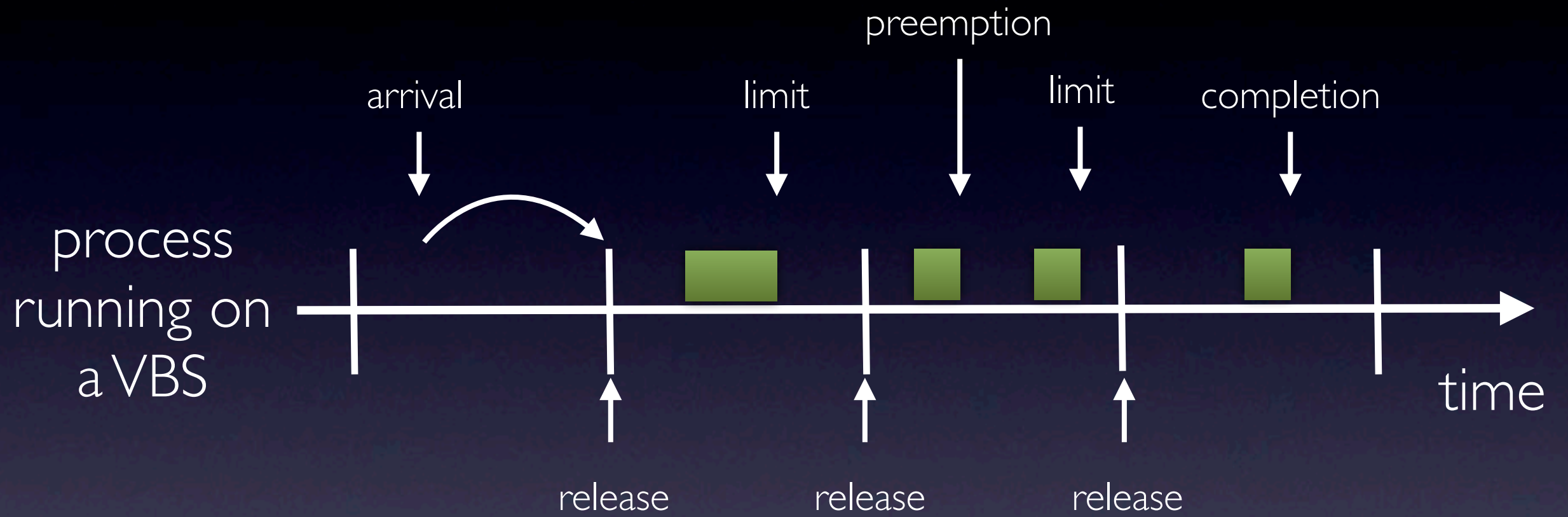


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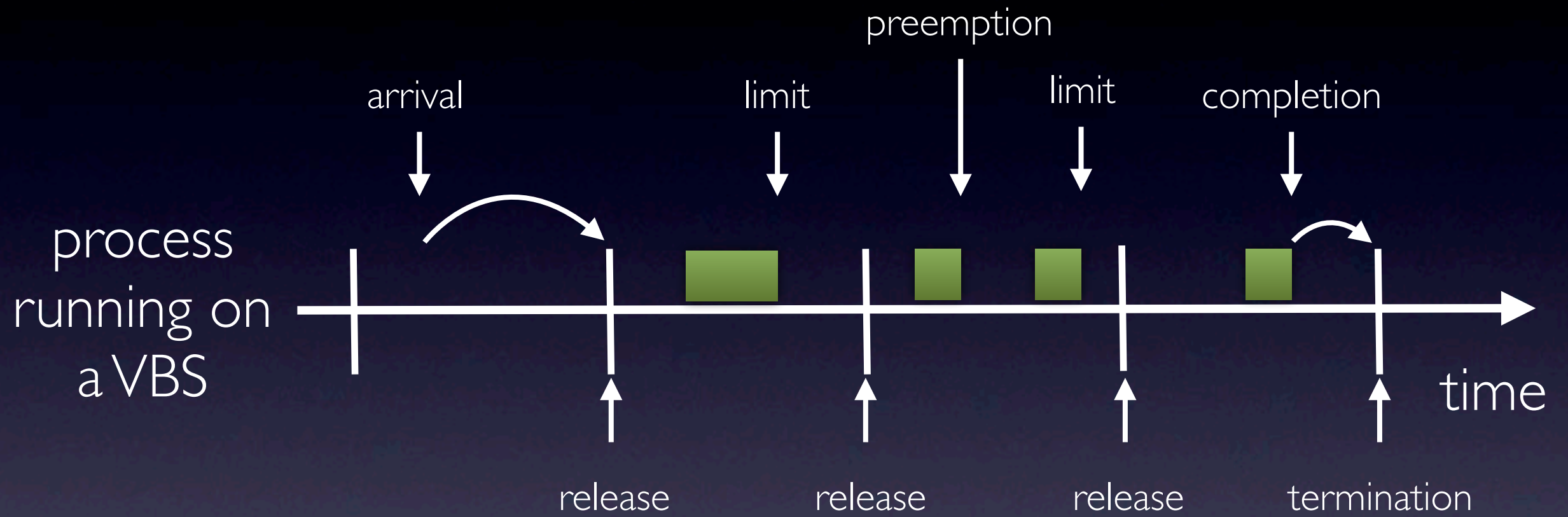
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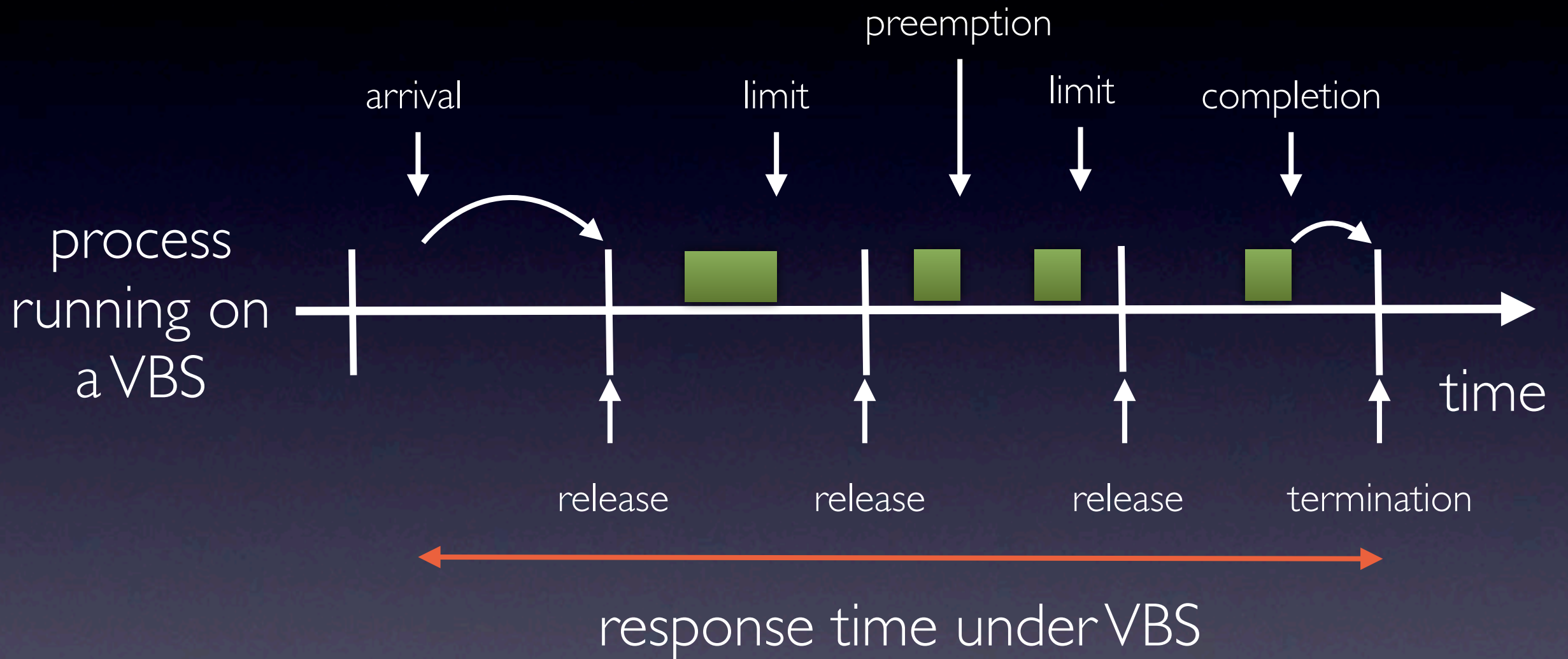


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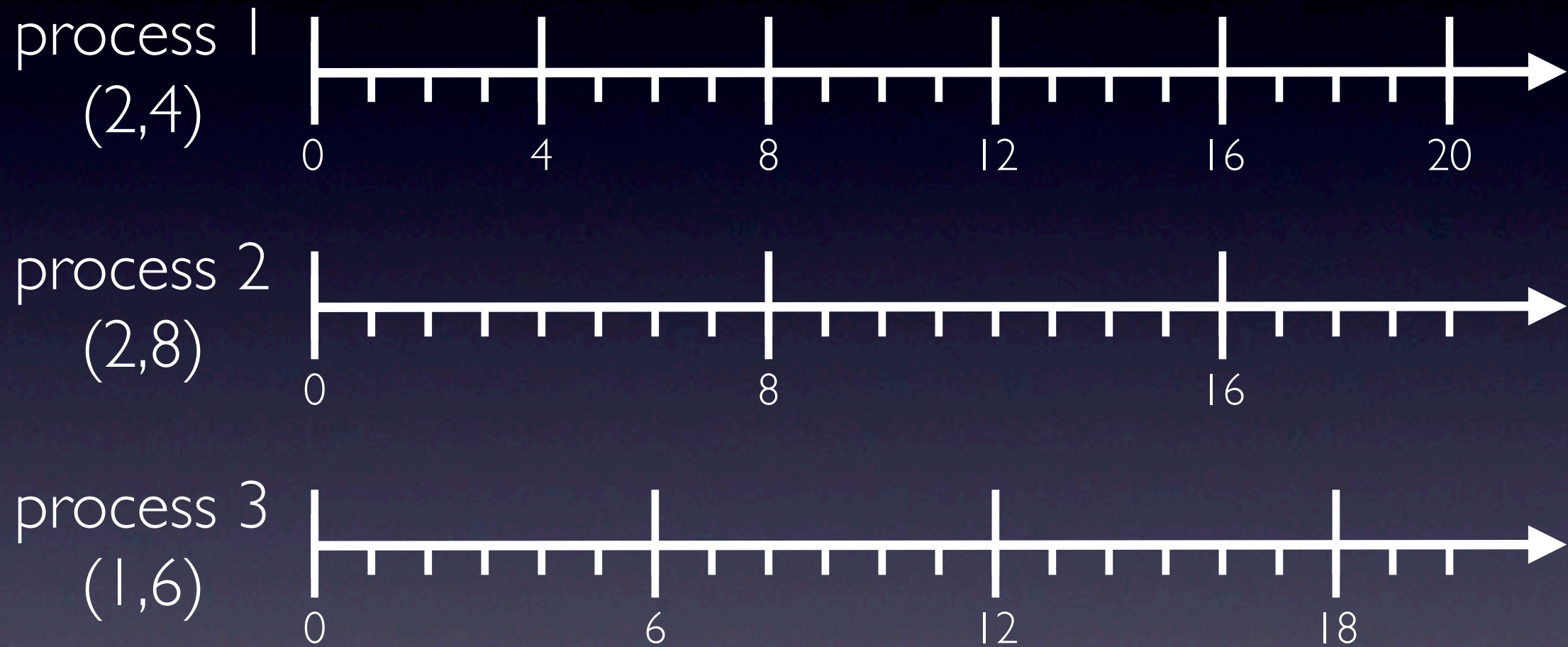


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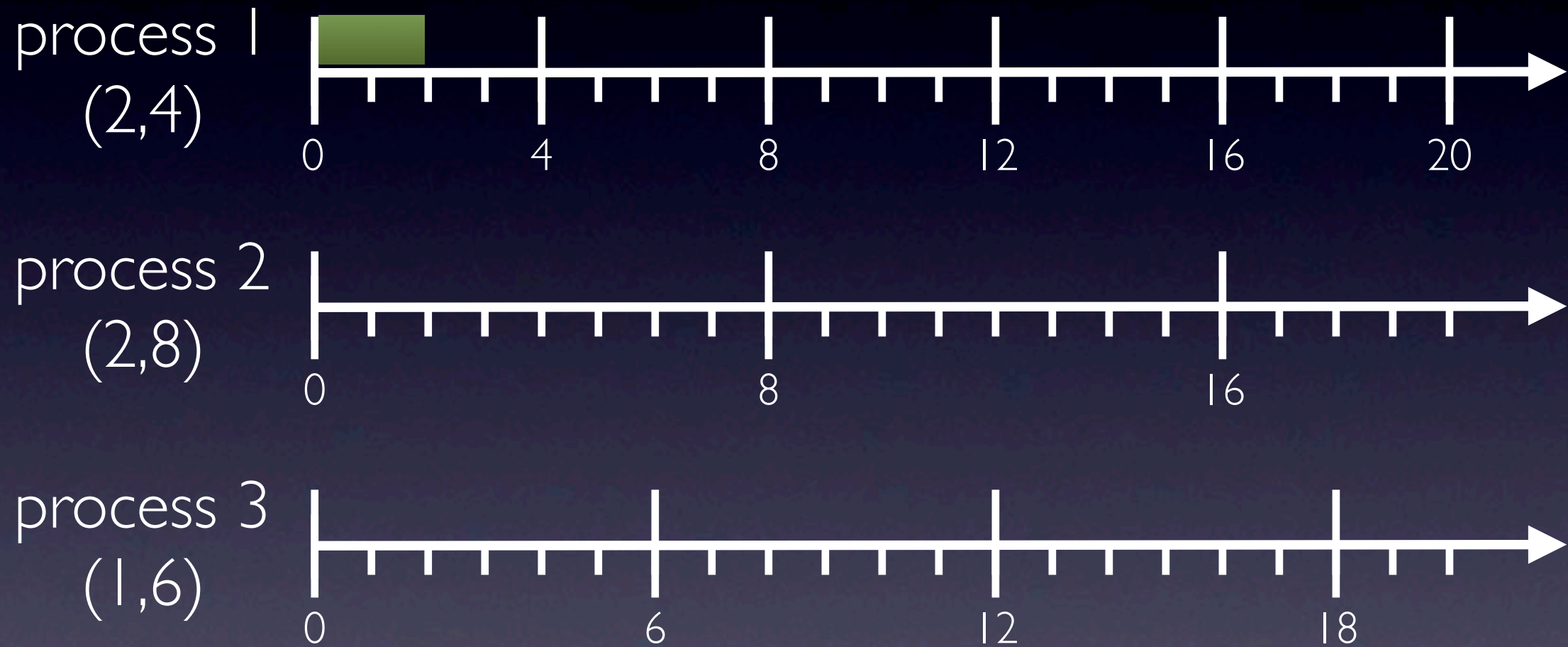


multiple processes are EDF-scheduled





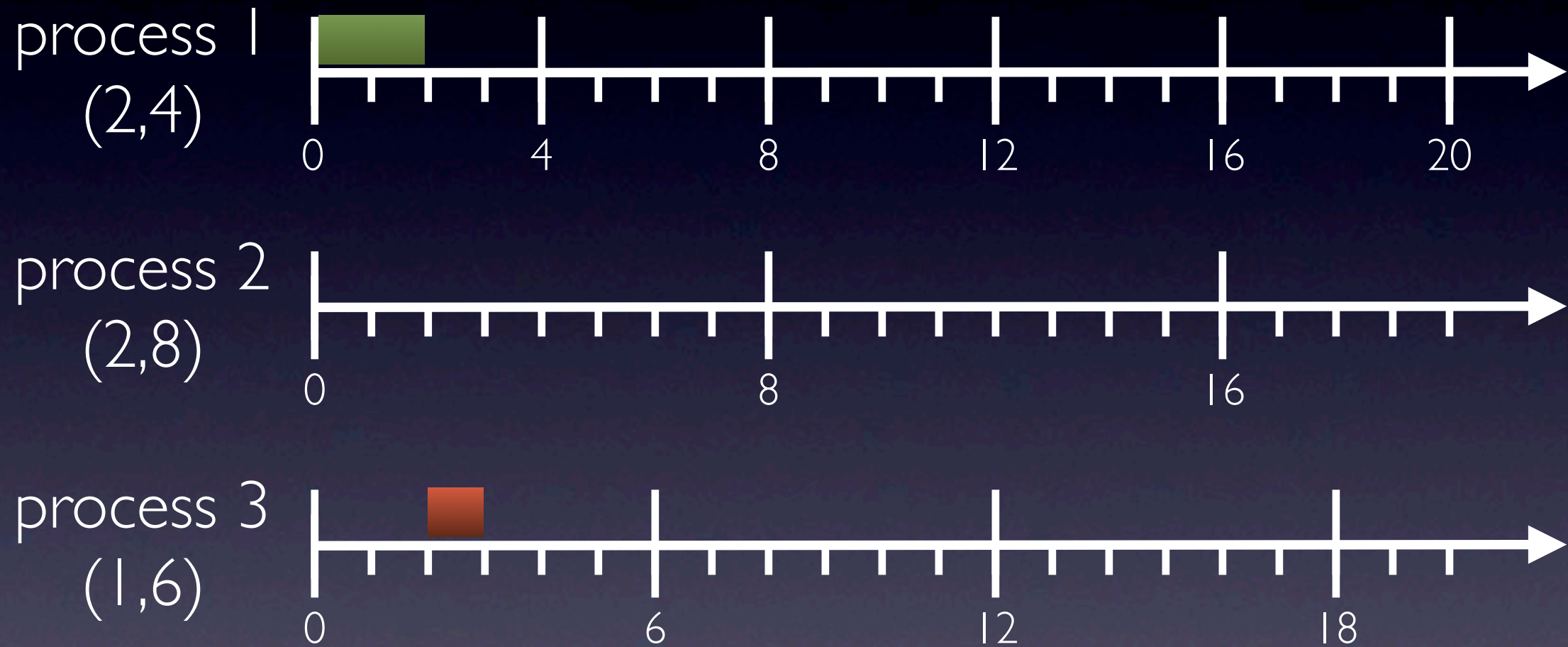
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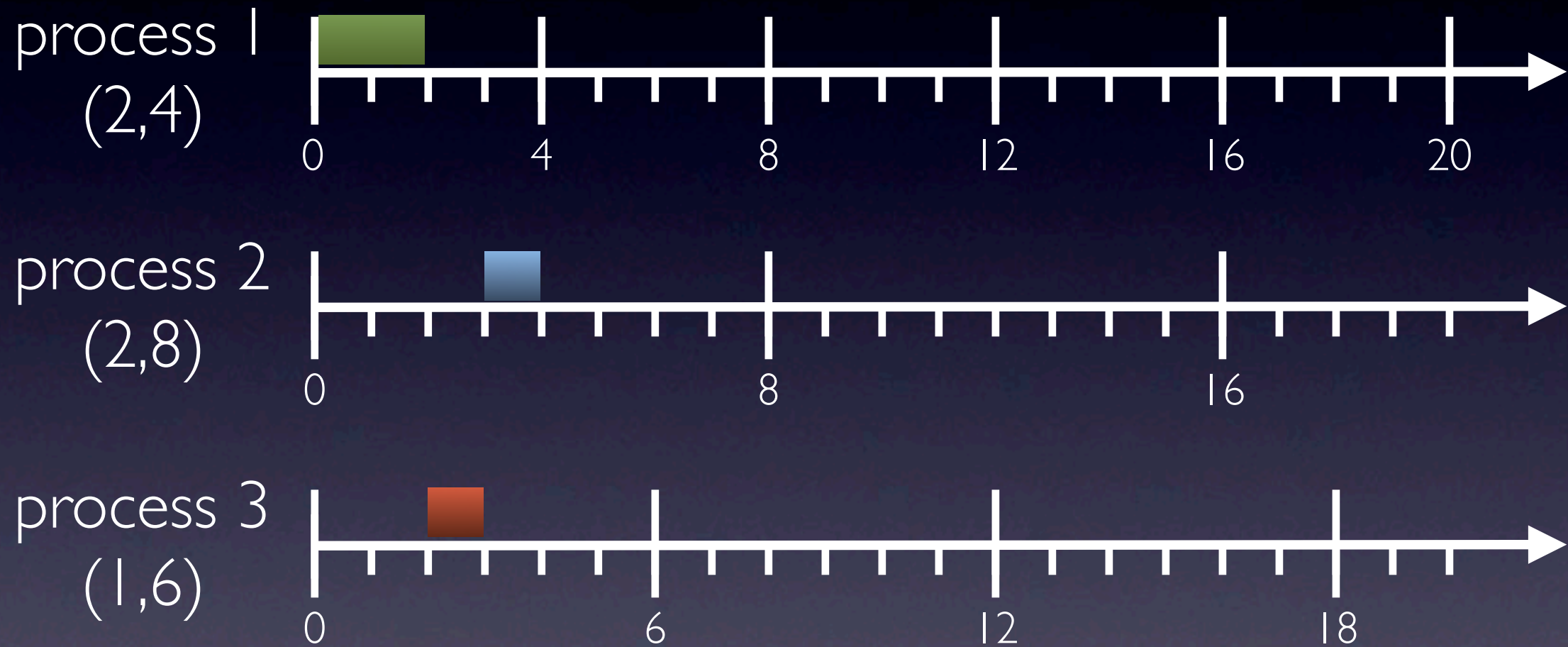
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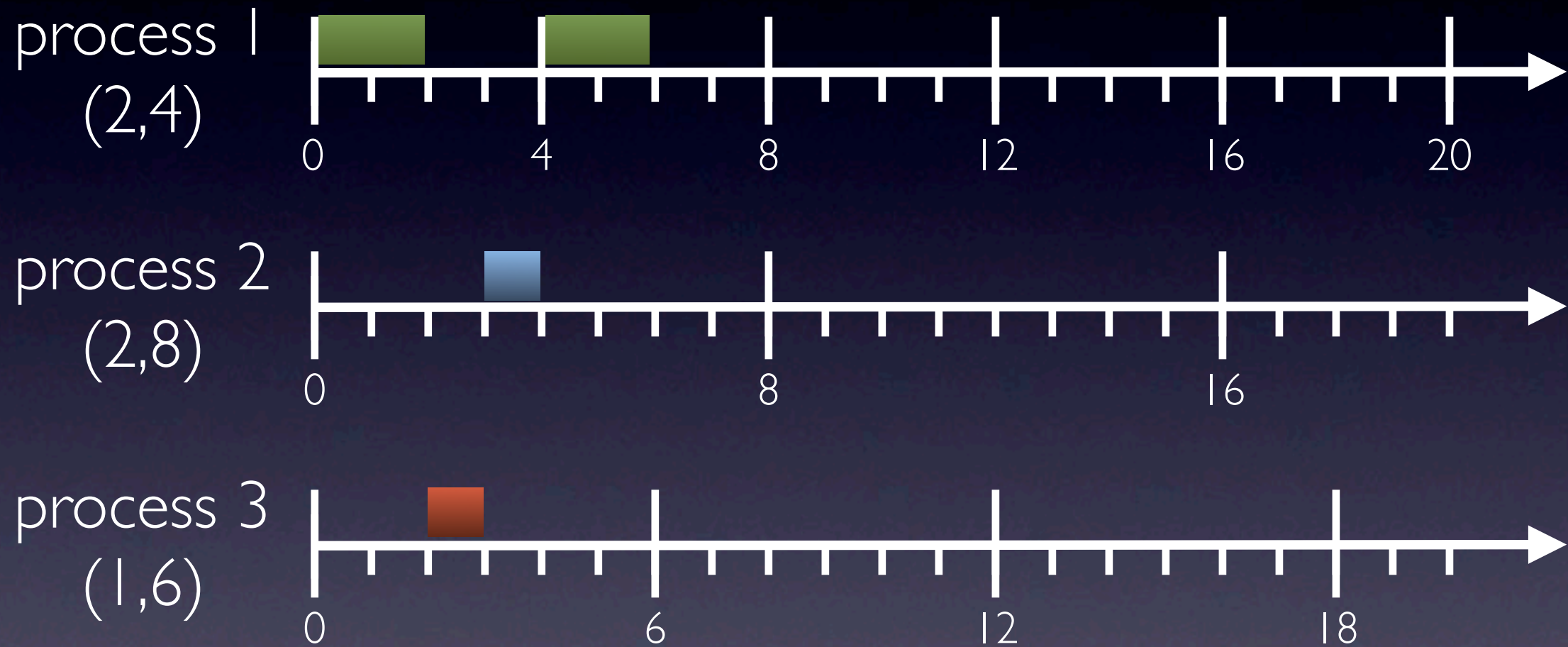


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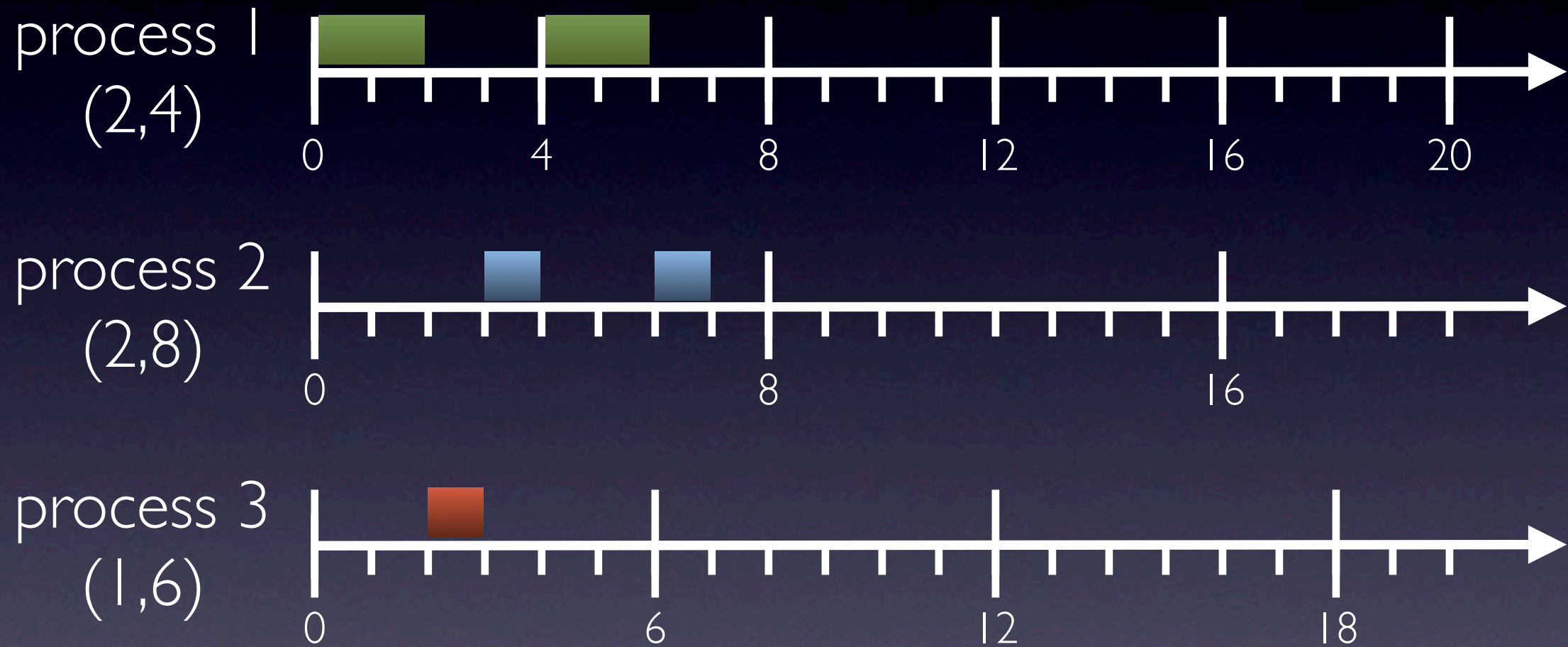
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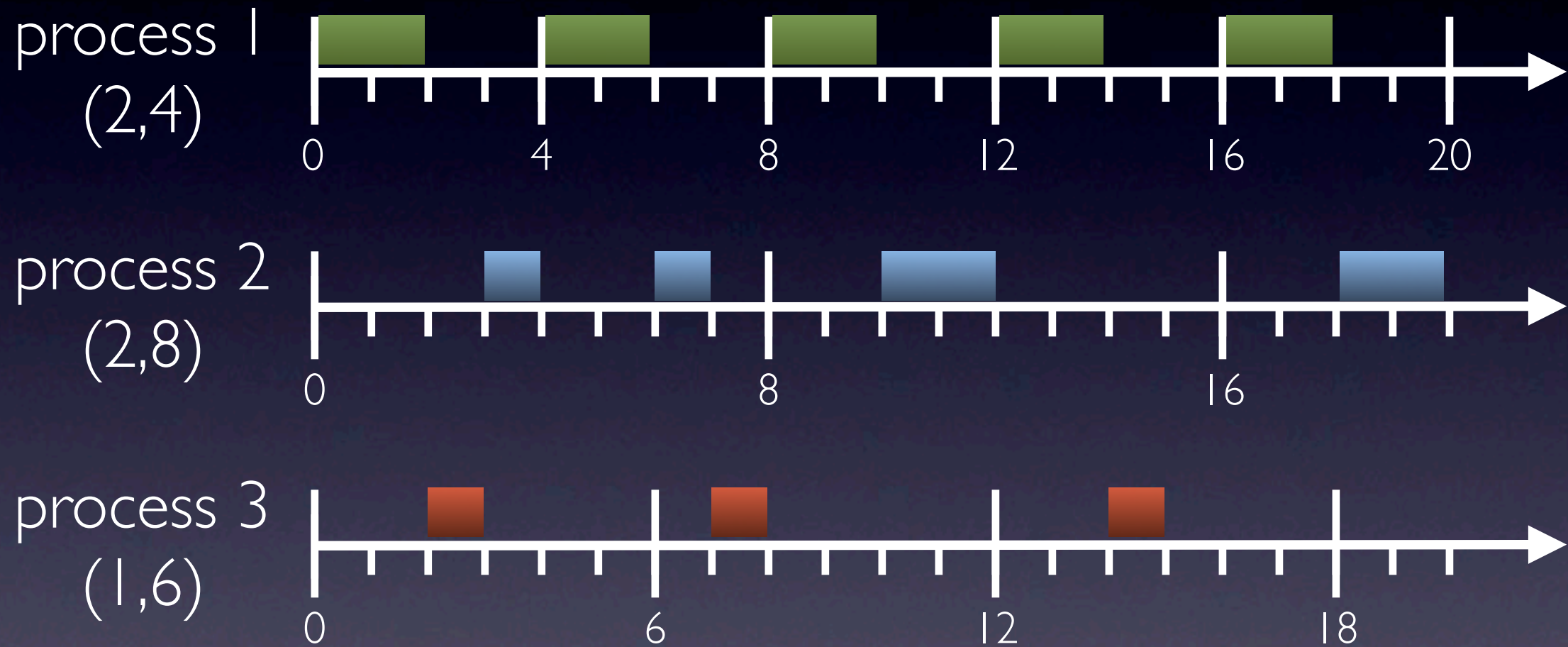
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# Scheduling Result and Bounds

[SIES09]

Processes  $P_1, P_2, \dots, P_n$  on VBSs  $u_1, u_2, \dots, u_n$   
are schedulable if  $\sum_{i=1}^n u_i \leq 1$



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For any action  $\alpha$  on a resource  $(\lambda, \pi)$  we have:

- upper response-time bound  $\lceil \frac{load}{\lambda} \rceil \pi + \pi - 1$
- lower response-time bound  $\lceil \frac{load}{\lambda} \rceil \pi$
- jitter  $\pi - 1$



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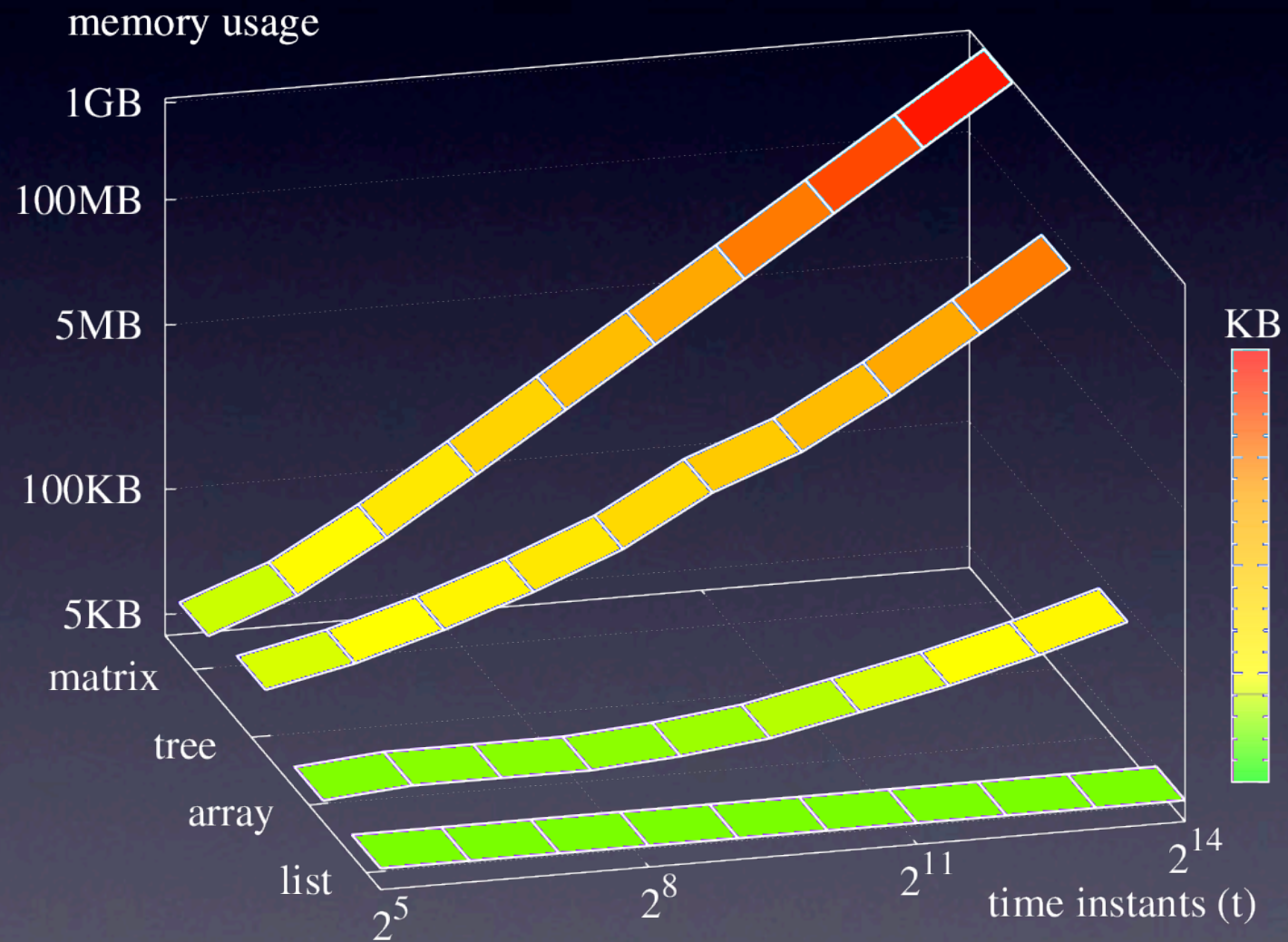
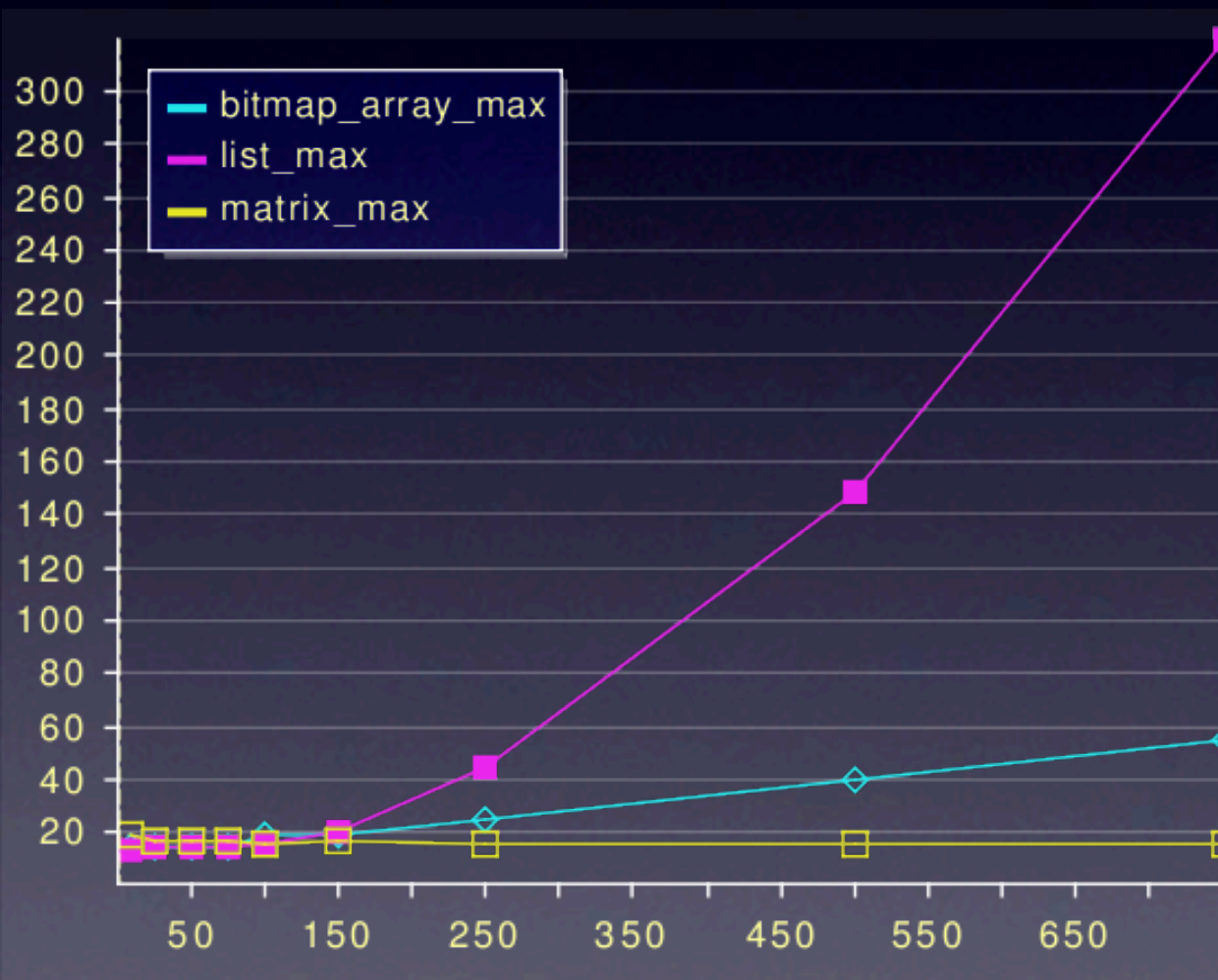
temporal isolation





# Scheduler Overhead

[SIES09]





# Power-Aware VBS

Dynamic Voltage and Frequency Scaling



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Dynamic Voltage and Frequency Scaling

Maintain VBS properties (temporal isolation, bounds)

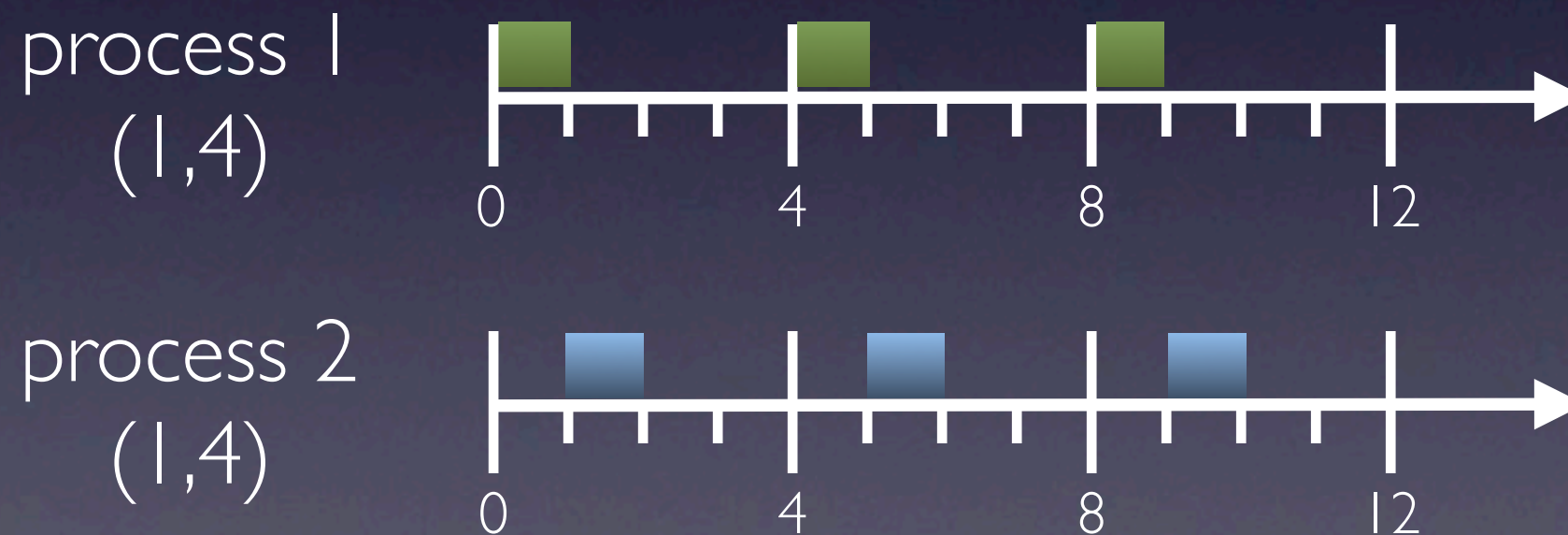




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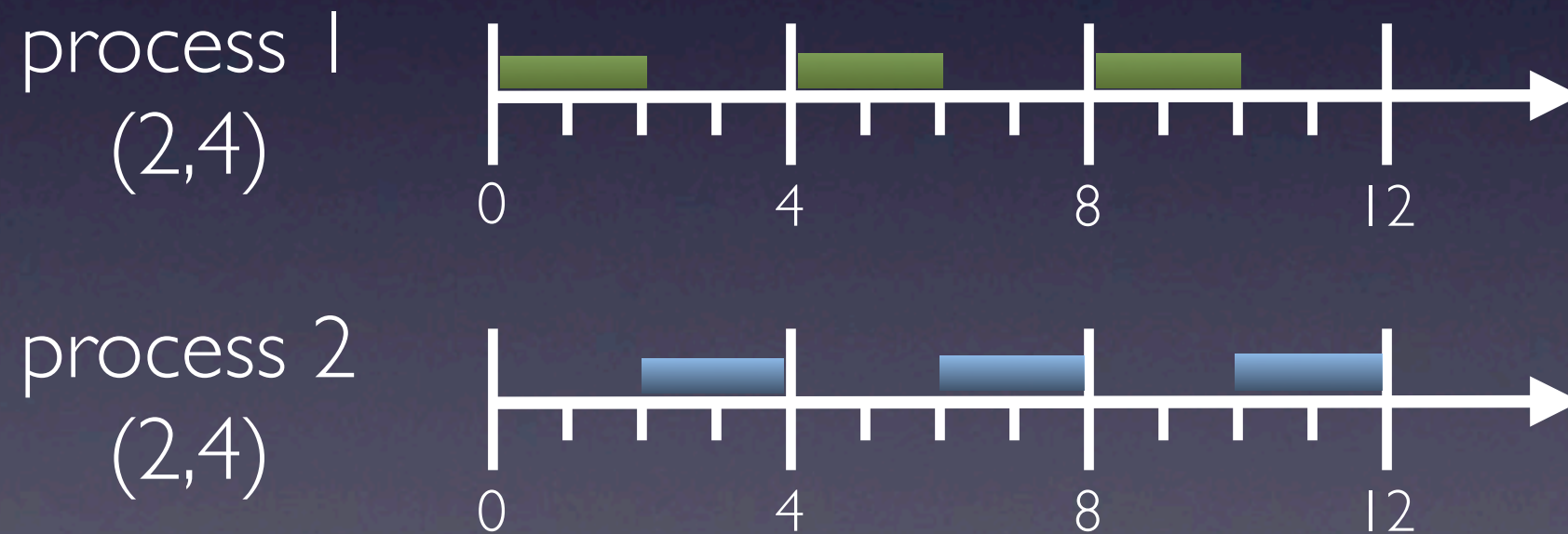




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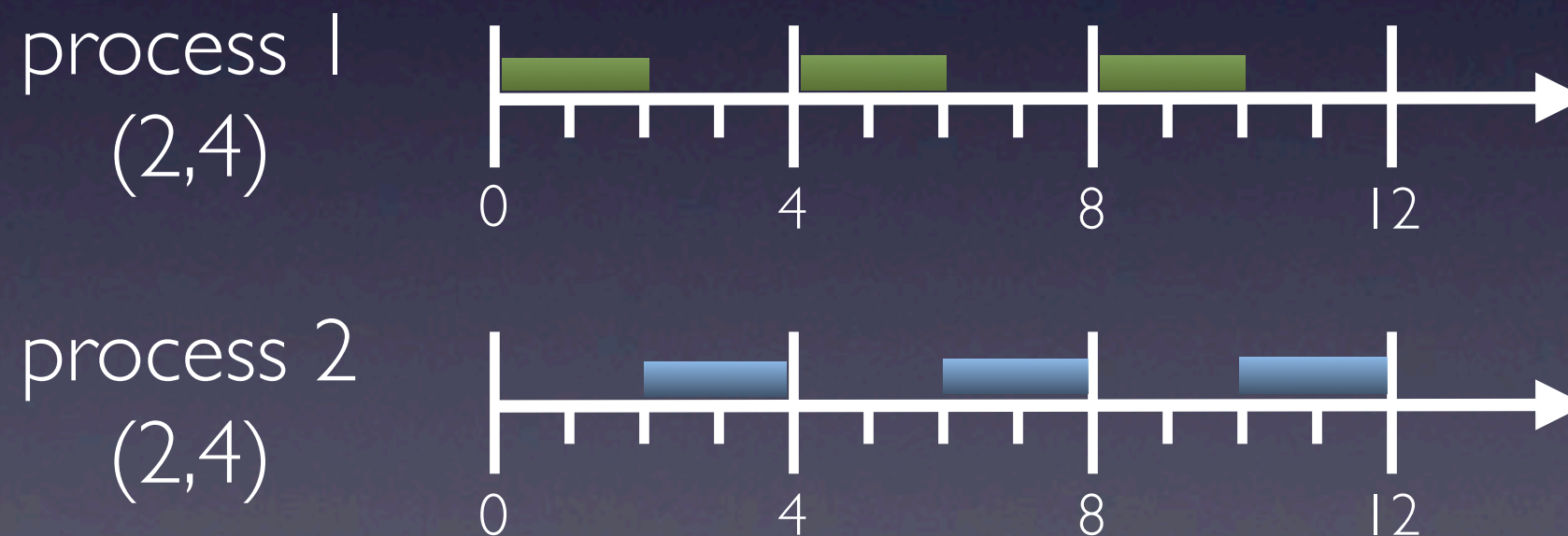




# Power-Aware VBS

## Dynamic Voltage and Frequency Scaling

Maintain VBS properties (temporal isolation, bounds)



Possible whenever there is slack in the system





# Power-Aware VBS

EDF frequency scaling result:

An EDF-schedulable set of tasks is still schedulable if the processor frequency in between any two release times is set to at least

$$U_c \cdot f_{\max}$$

current total utilization of all released tasks in the considered interval of time between two releases



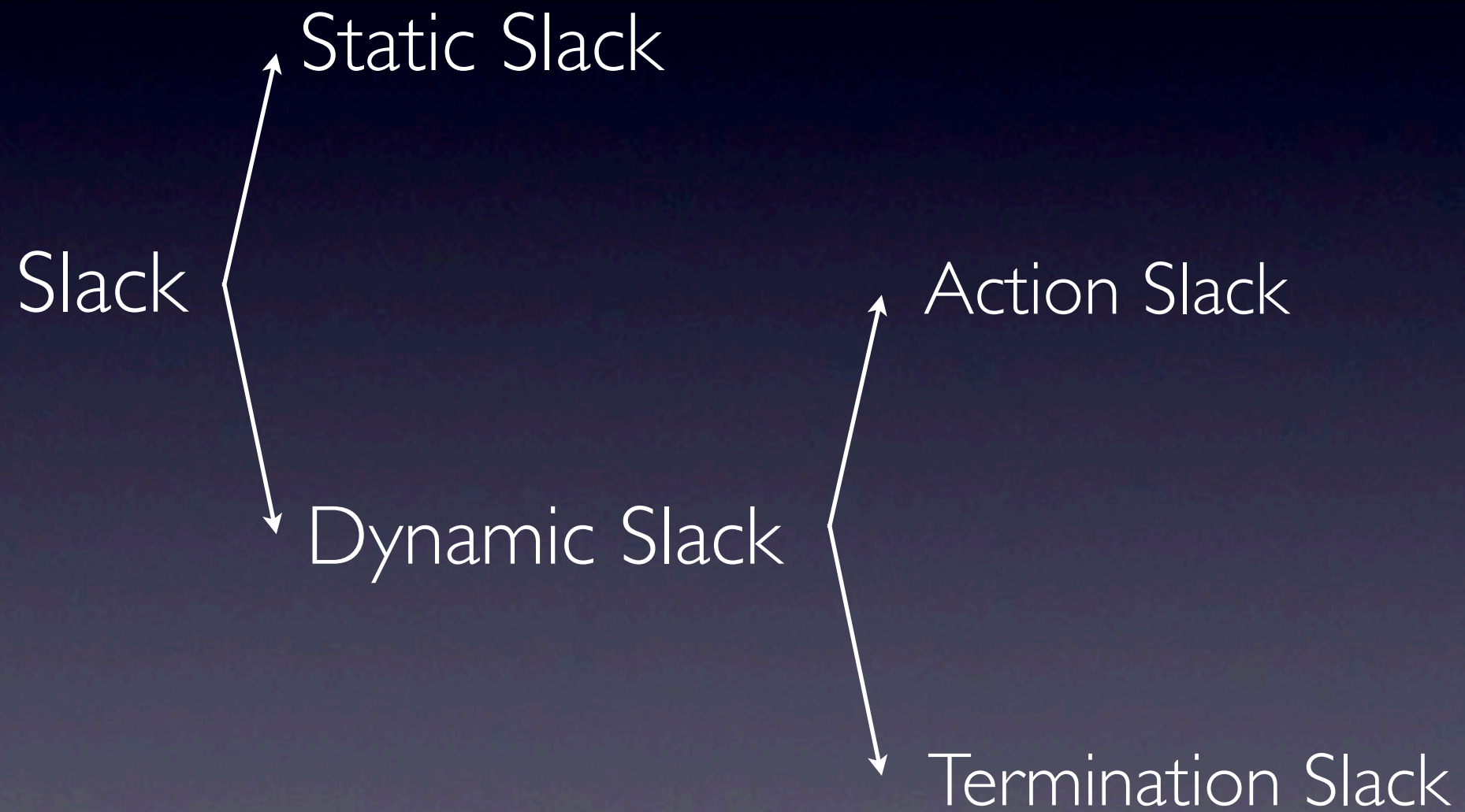


# Frequency-scaling VBS

Slack



# Frequency-scaling VBS

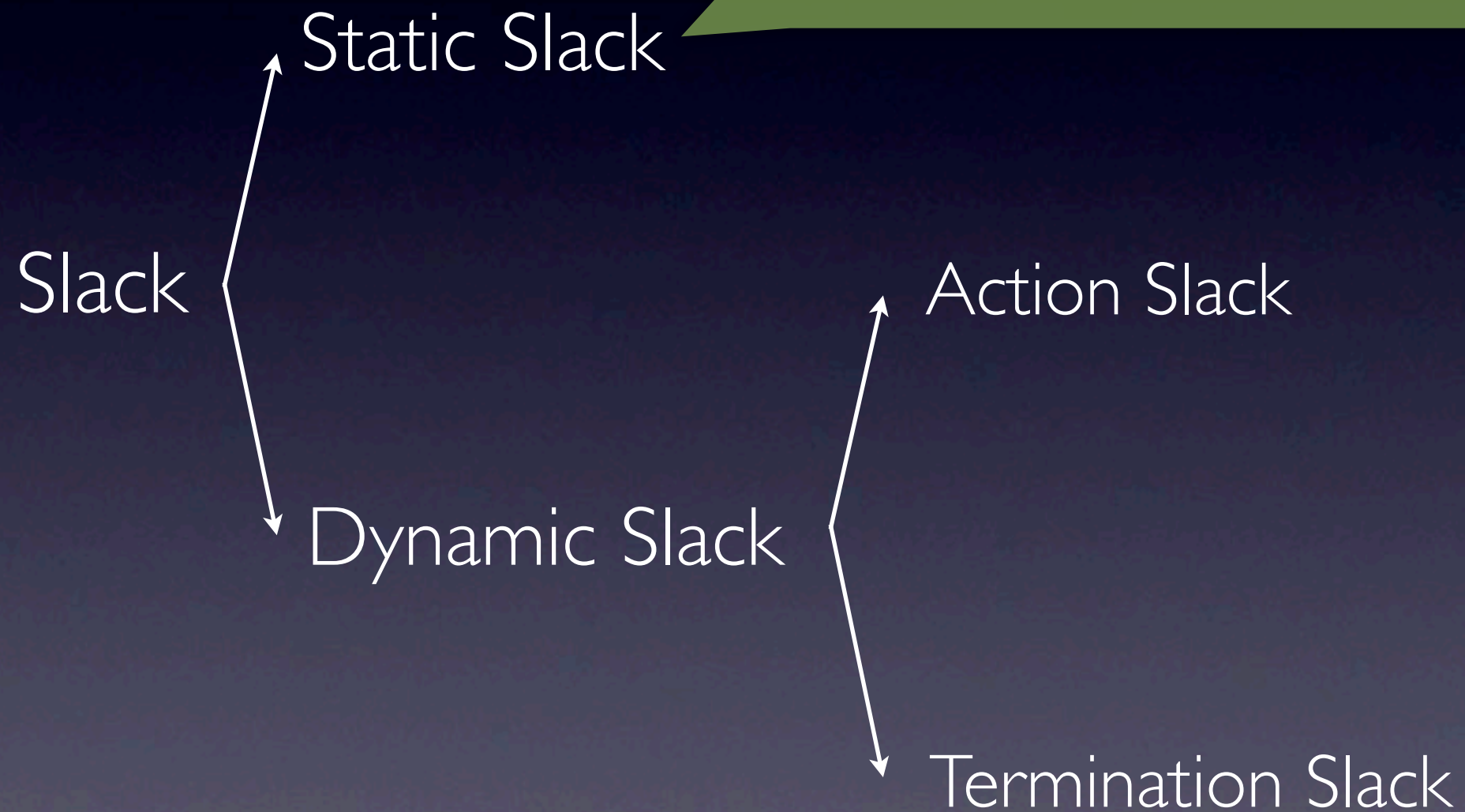






# Frequency-scaling VBS

Frequency is scaled to the sum of the bandwidth caps and not changed at runtime





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Frequency is scaled at release time to the sum of the utilizations of the released actions

Action Slack

Dynamic Slack

Termination Slack



# Frequency-scaling VBS

Frequency is scaled to the sum of the bandwidth caps and not changed at runtime

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Frequency is scaled at release time to the sum of the utilizations of the released actions

Action Slack

Dynamic Slack

New limits are computed for each action such that the upper response-time bound is maintained

Termination Slack





# Frequency-scaling VBS



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$$f = \sum_{i=1}^n u_i \cdot f_{max}$$



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$$f = \sum_{i=1}^n \frac{\lambda_{i,j}}{\pi_{i,j}} \cdot f_{max}$$

Termination slack

$$f = \sum_{i=1}^n \frac{\lambda_{i,j}^*}{\pi_{i,j}} \cdot f_{max} \quad \lambda_{i,j}^* = \left[ \frac{l_{i,j}}{n_{i,j}} \right] \quad n_{i,j} = \left[ \frac{l_{i,j}}{\lambda_{i,j}} \right]$$



# Frequency-scaling VBS

Static slack

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Termination slack

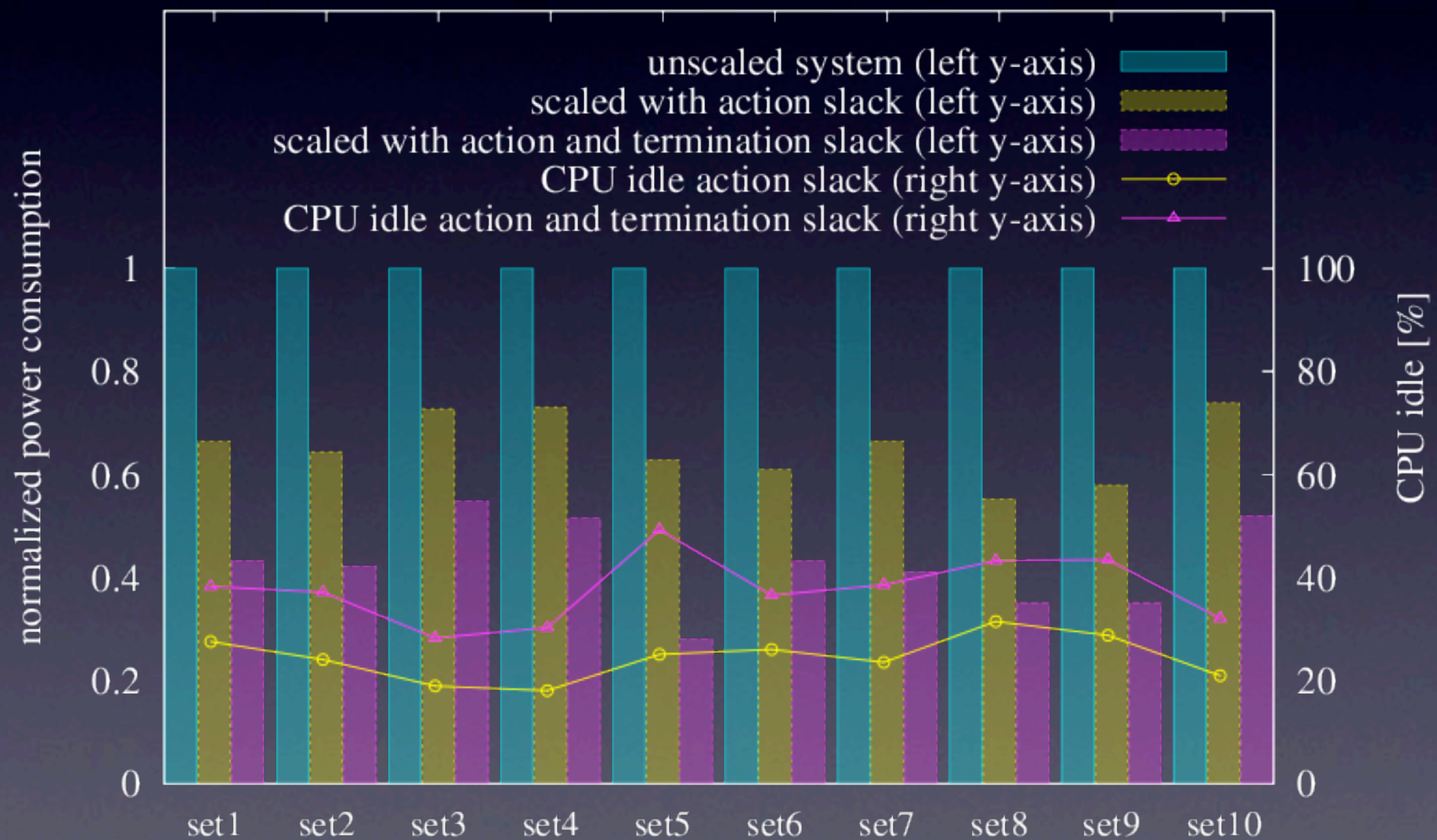
$$f = \sum_{i=1}^n \frac{\lambda_{i,j}^*}{\pi_{i,j}} \cdot f_{max} \quad \lambda_{i,j}^* = \left\lceil \frac{l_{i,j}}{n_{i,j}} \right\rceil \quad n_{i,j} = \left\lceil \frac{l_{i,j}}{\lambda_{i,j}} \right\rceil$$

Termination and action slack can be used separately or together



# Power-Aware VBS

Assuming a simple power model ( $P \propto V^2$ )







# Look-ahead FS-VBS



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With knowledge of future events:

redistribute computation time between periods



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optimal offline method





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May help to handle:

more complex power models



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May help to handle:

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frequency switching cost (time and power)





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With knowledge of future events:

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May help to handle:

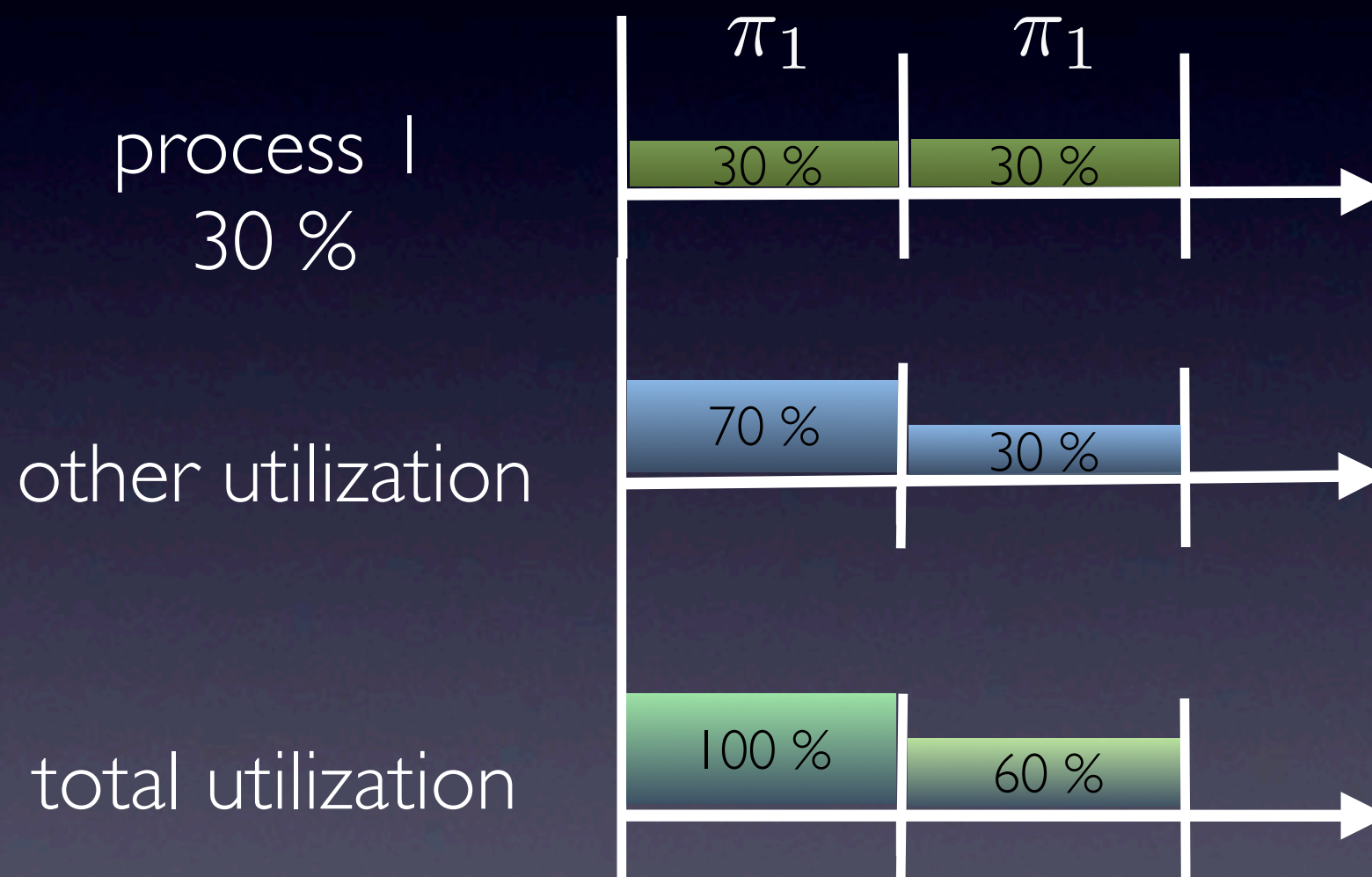
more complex power models

frequency switching cost (time and power)

time overhead included using overhead accounting [RTAS10]

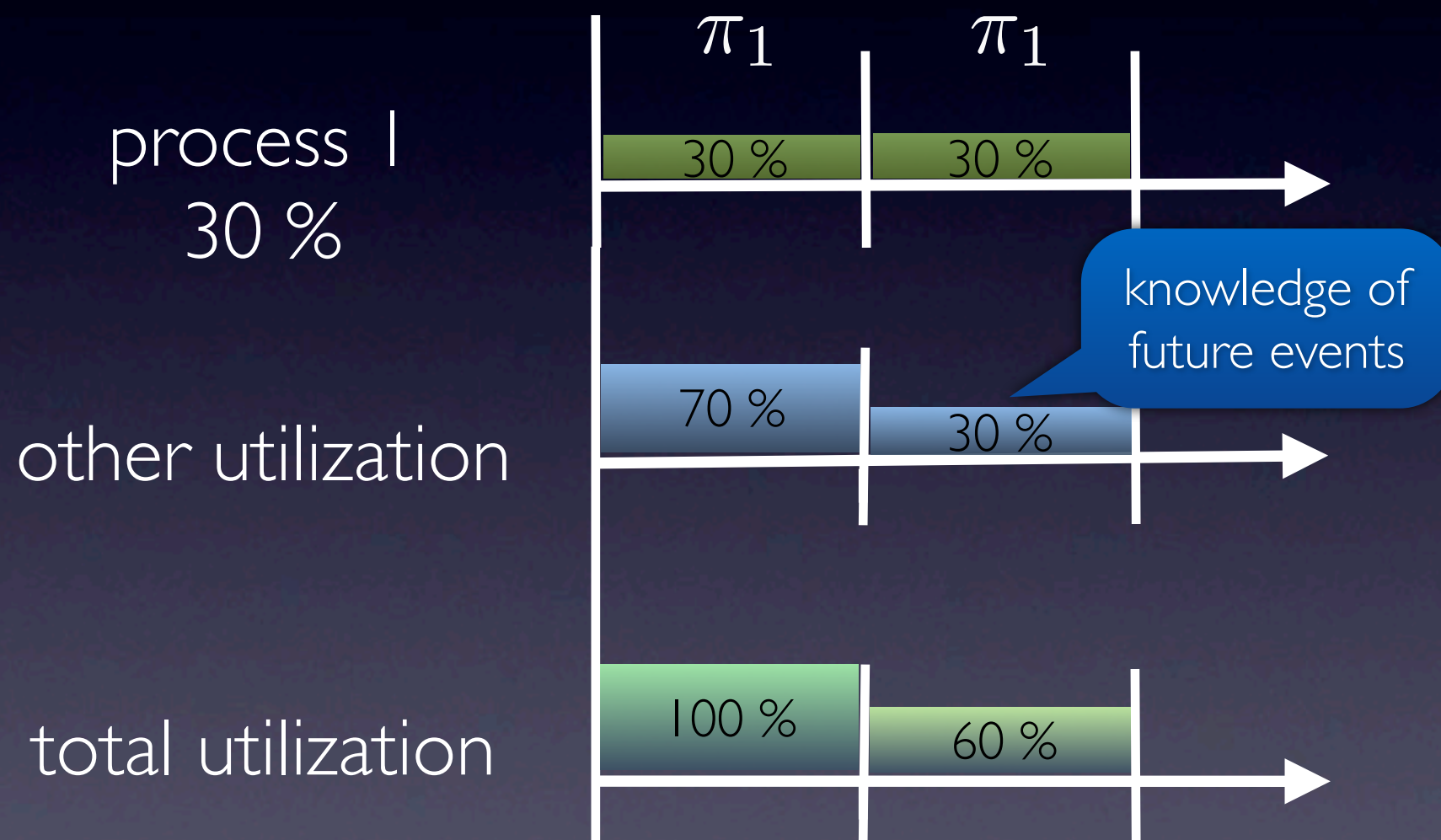


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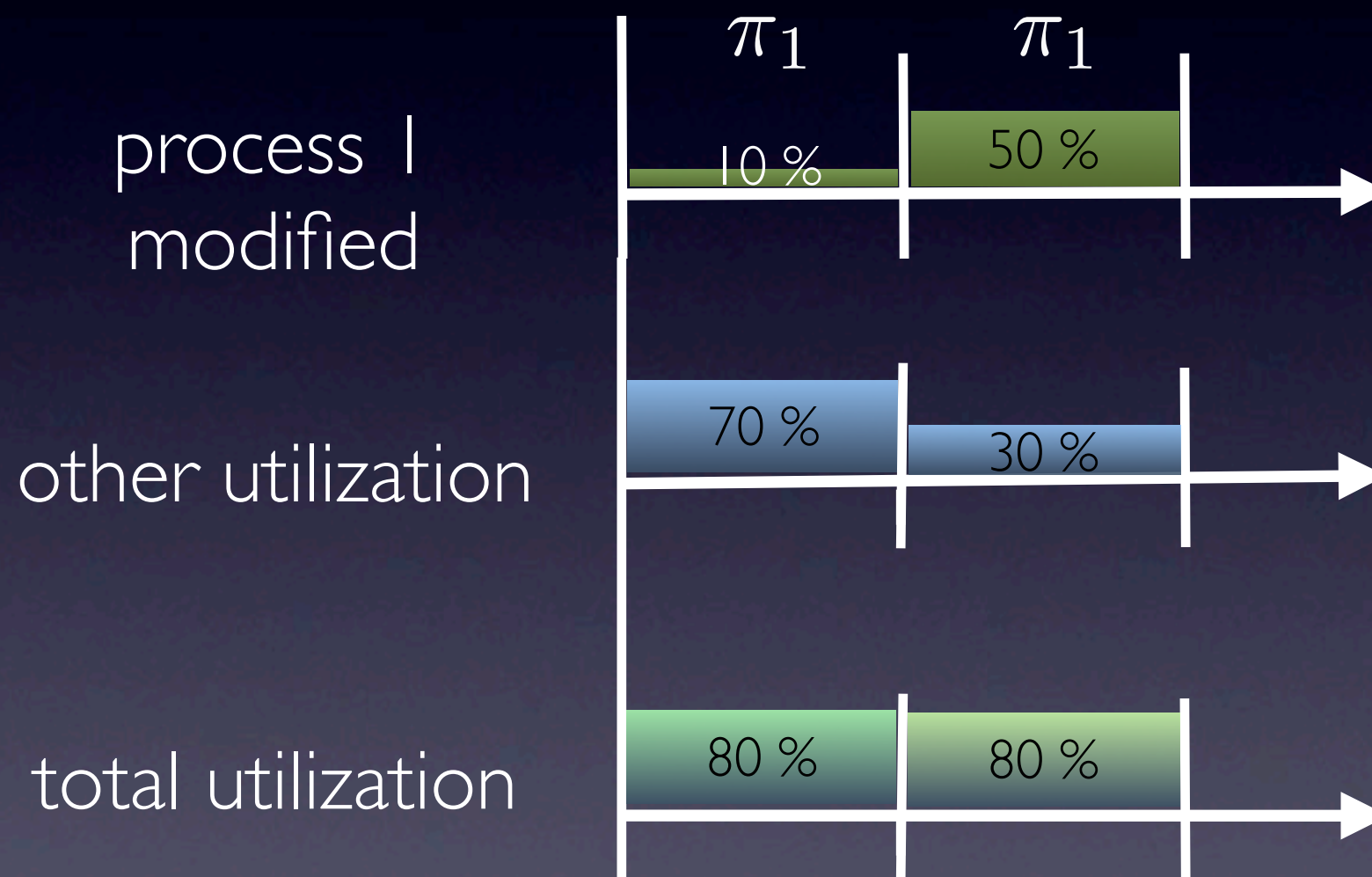
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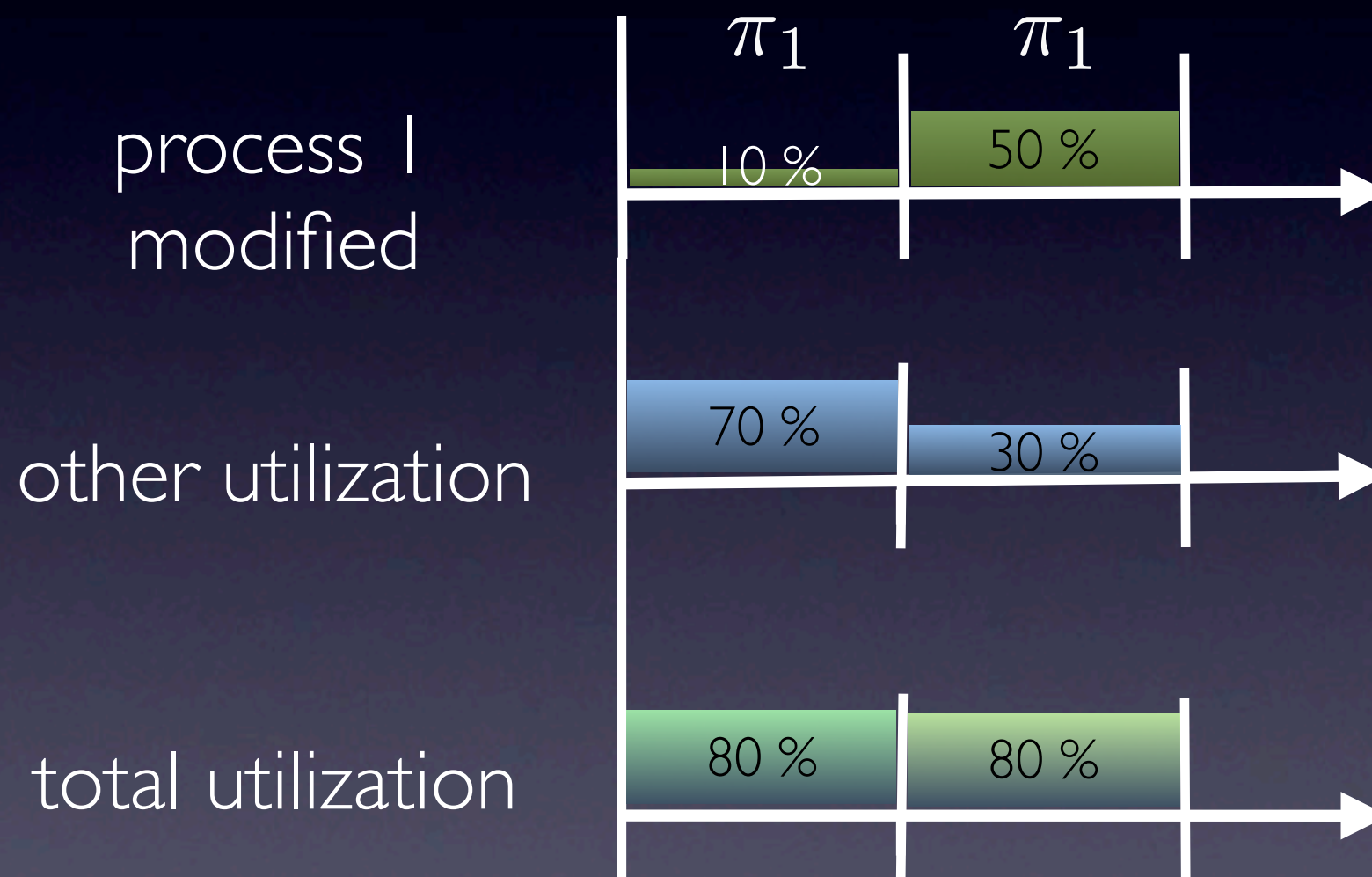


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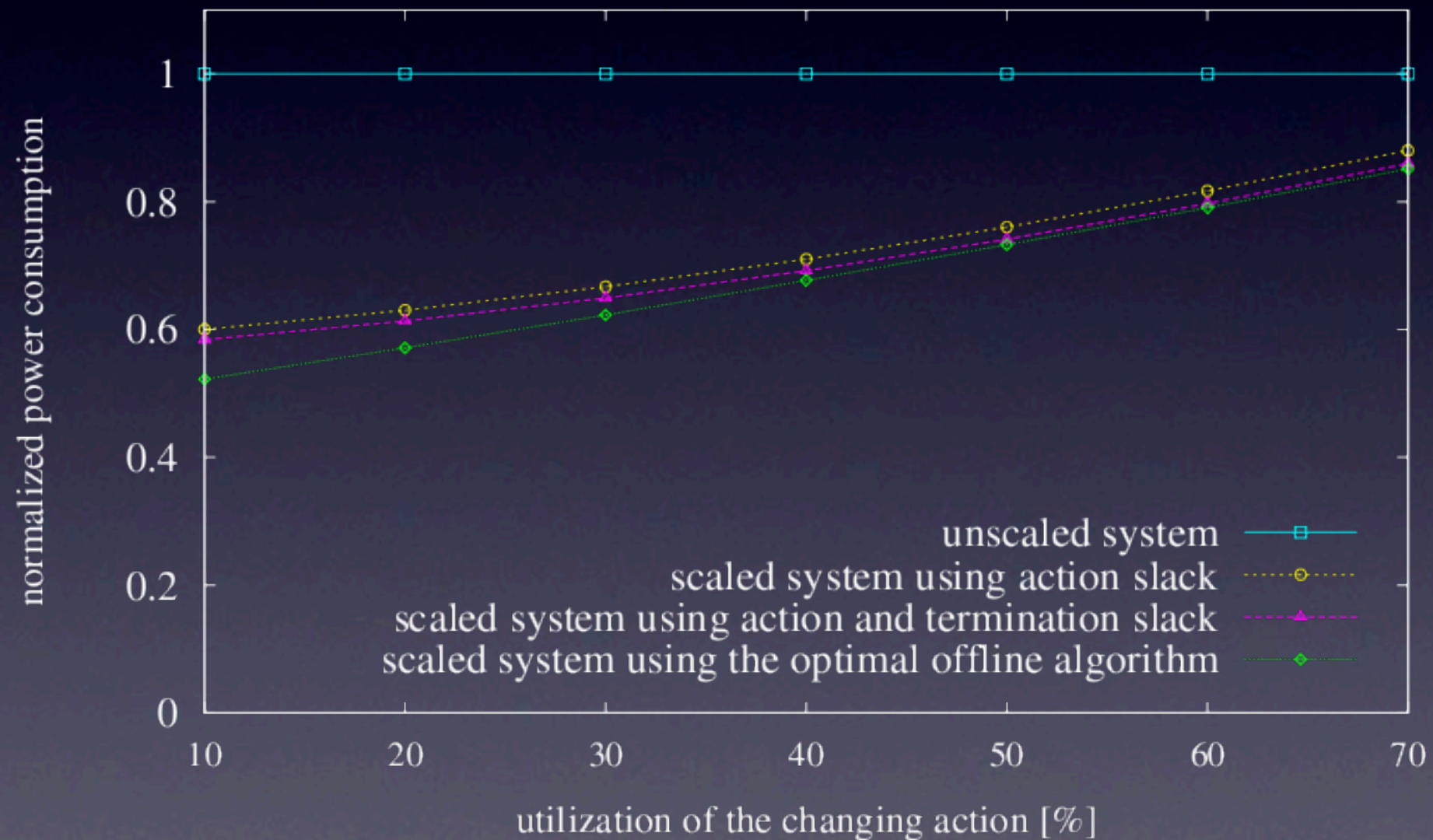


actual improvement depends on the power model



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Assuming a simple power model ( $P \propto V^2$ )





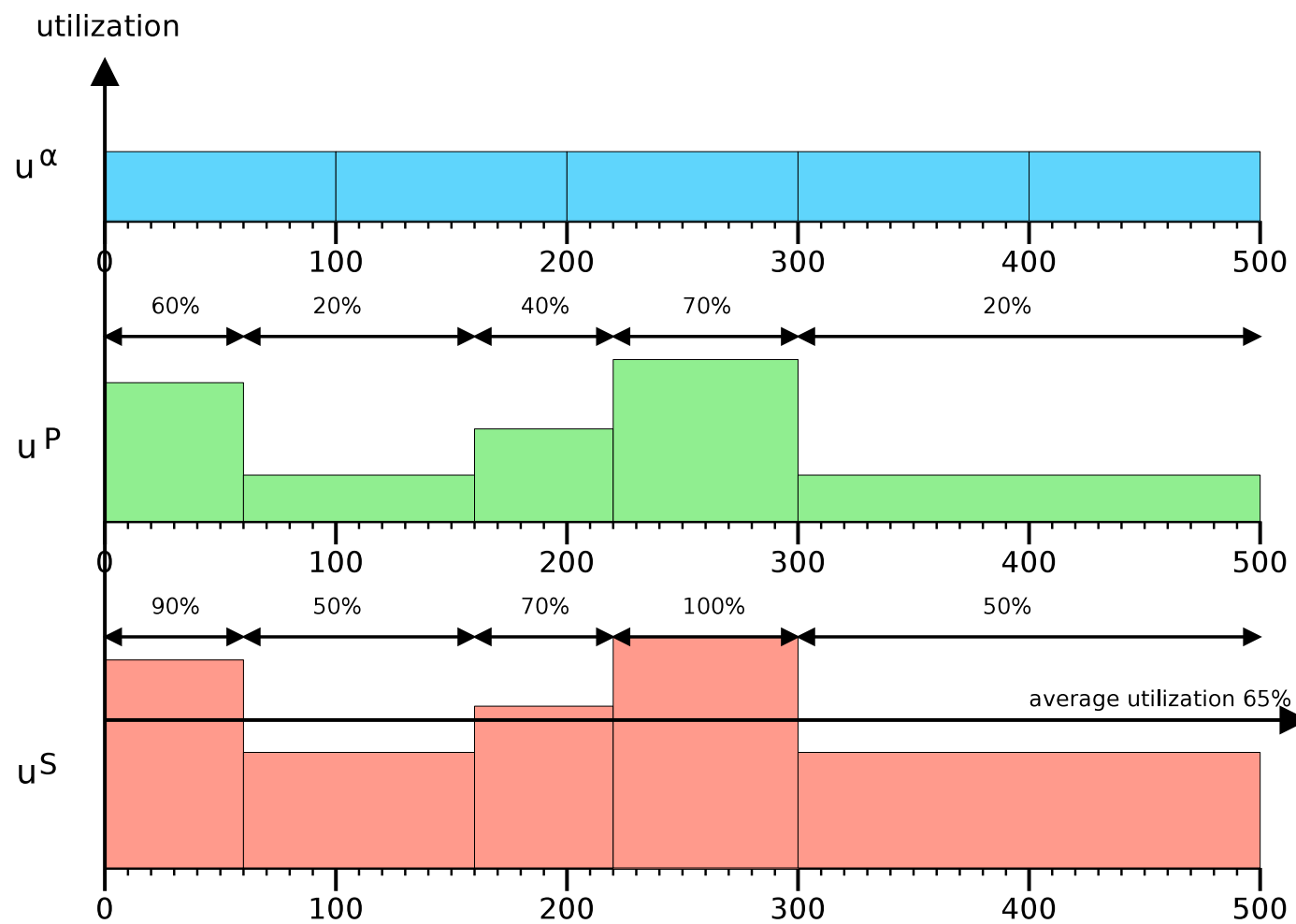


# Look-ahead online FS-VBS



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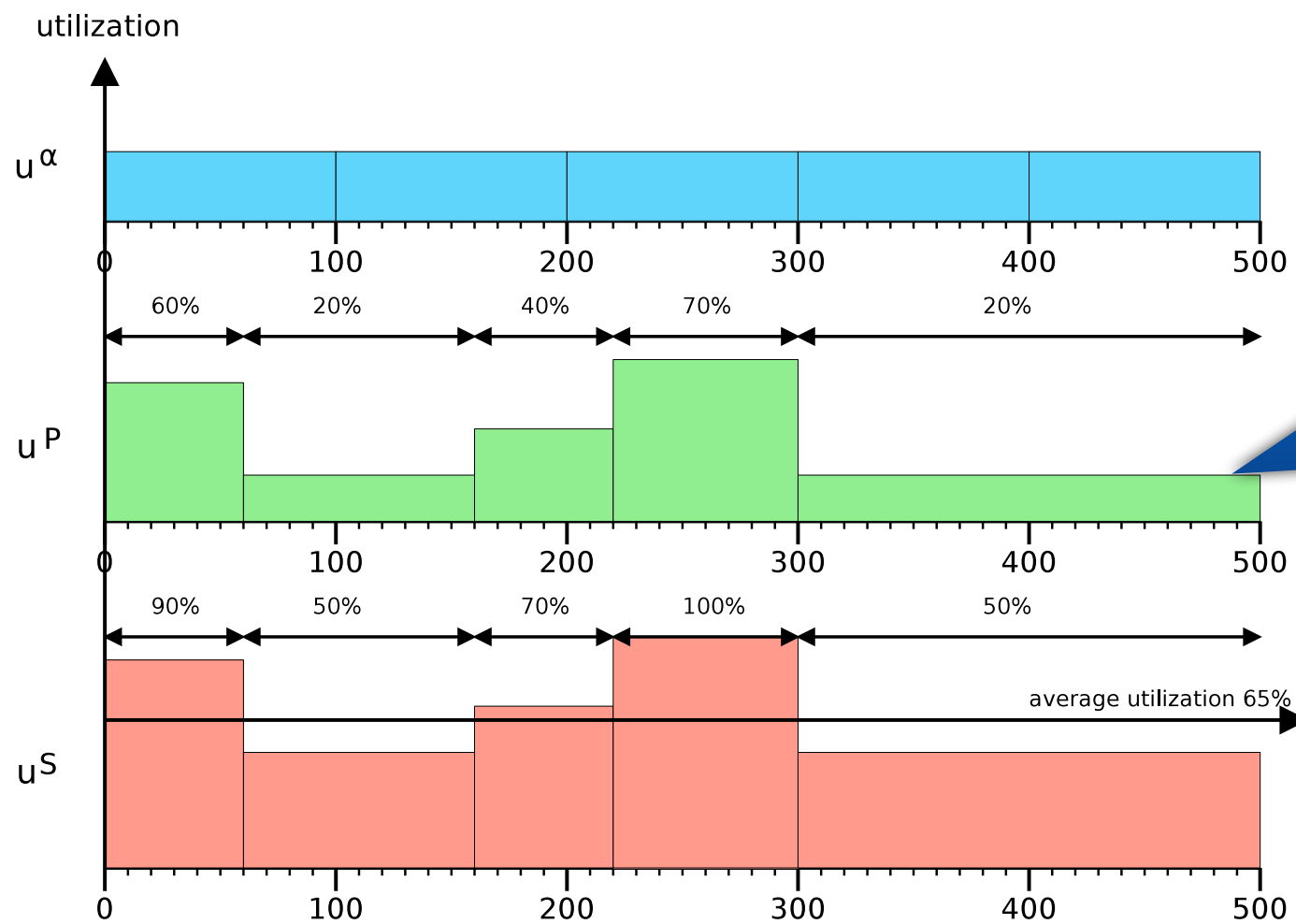
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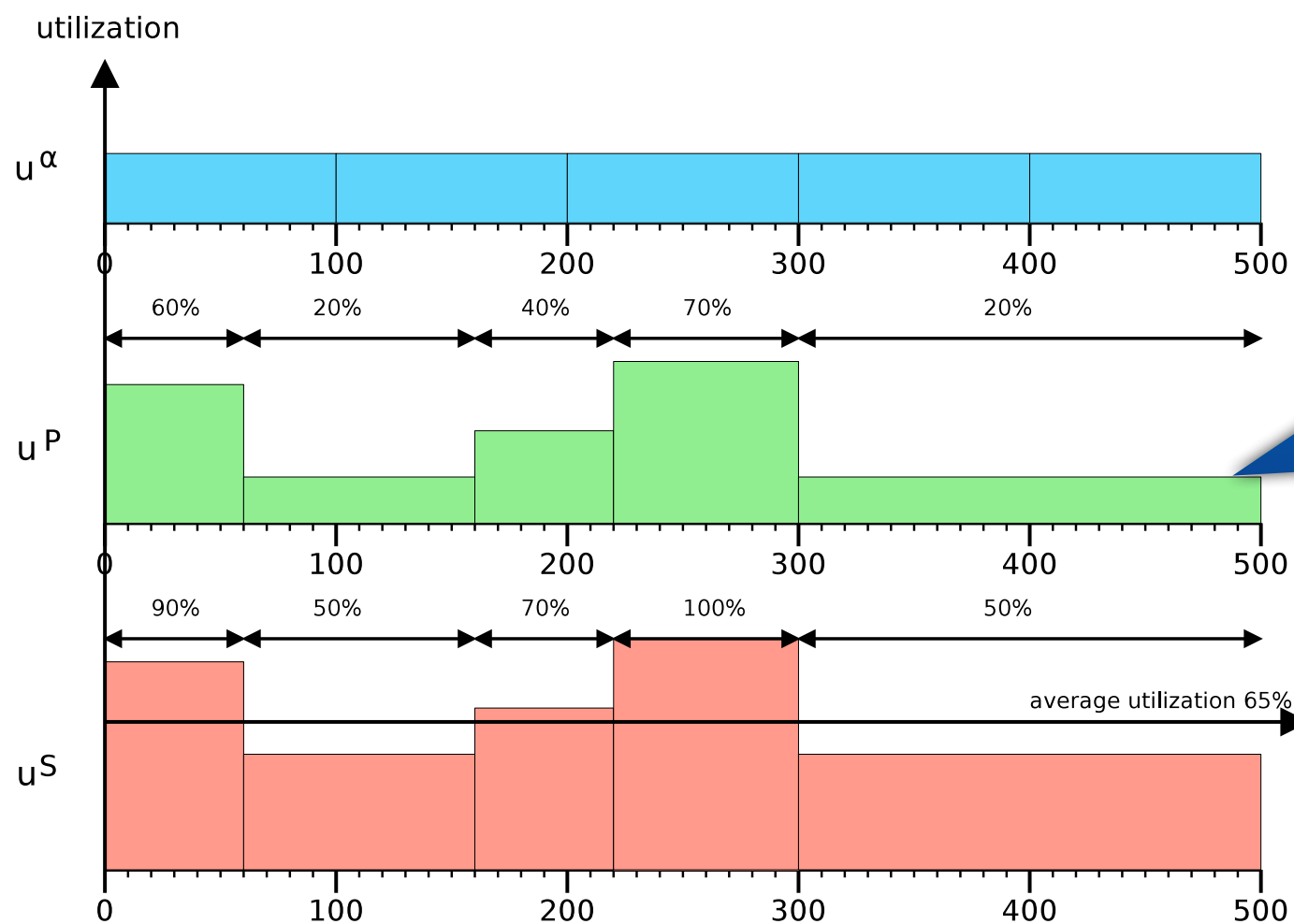
knowledge of future events





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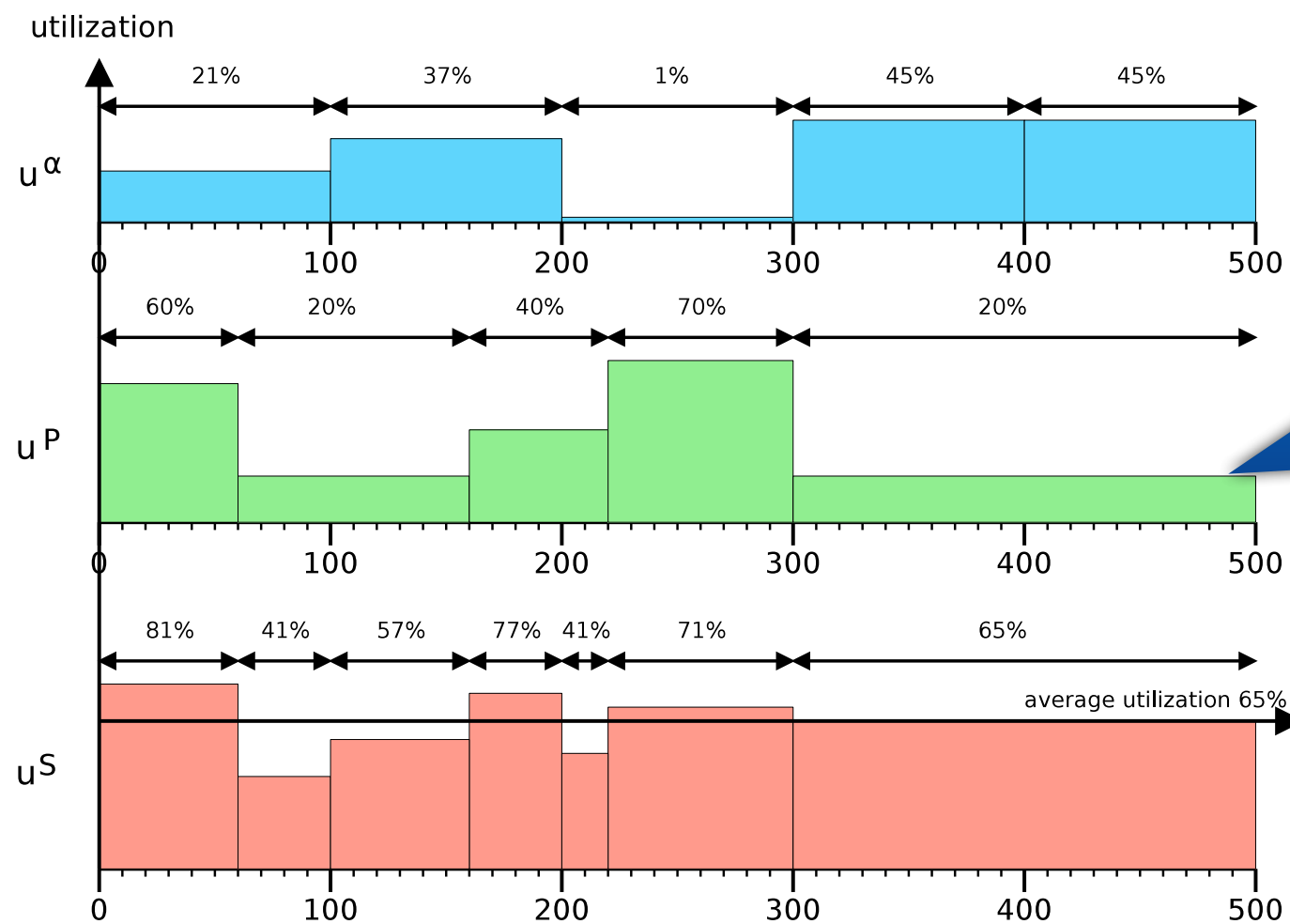


Modify the limits in each period (whenever possible)  
s.t. the utilization approximates the average utilization



# Look-ahead online FS-VBS

Assume a simple power model ( $P \propto V^2$ )



knowledge of future events

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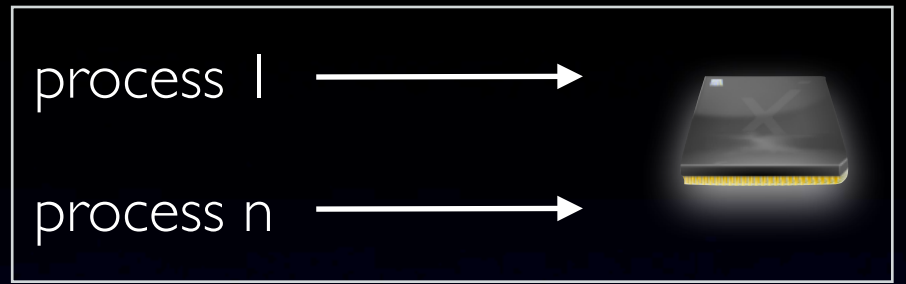
# Conclusions





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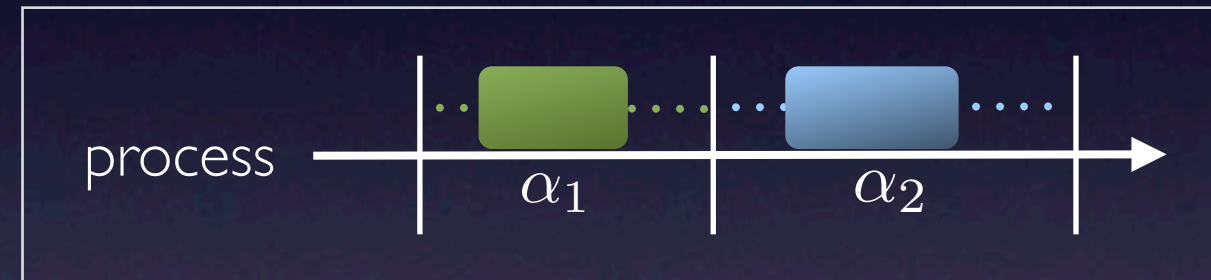
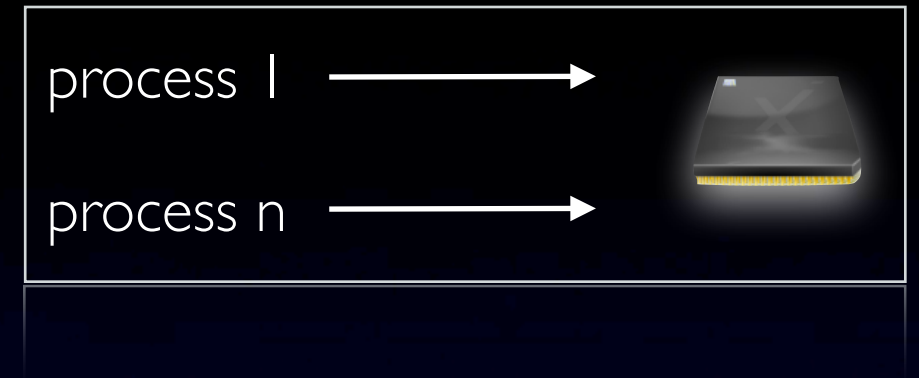
- Server-based scheduling for temporal isolation





# Conclusions

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- VBS for variable execution speed





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- VBS for variable execution speed
- Power-aware VBS

