## Embedded Software Engineering

3 Unit Course, Winter 2004 CS Department, Univ. of Salzburg

Christoph Kirsch

www.cs.uni-salzburg.at/~ck/teaching/ESE-Winter-2004

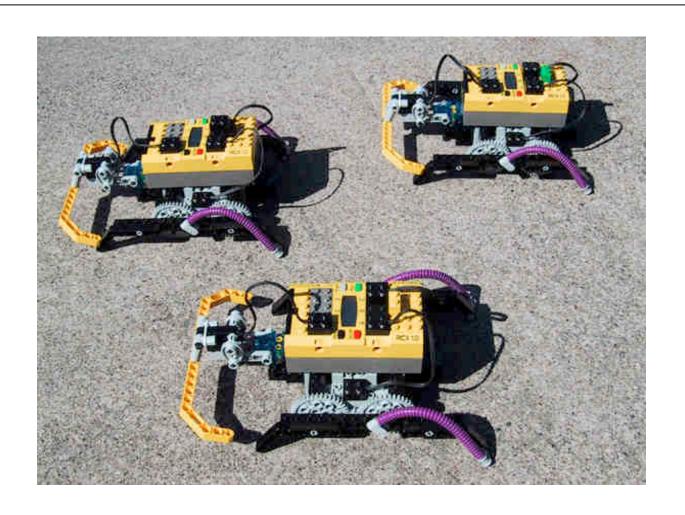
# It's significant



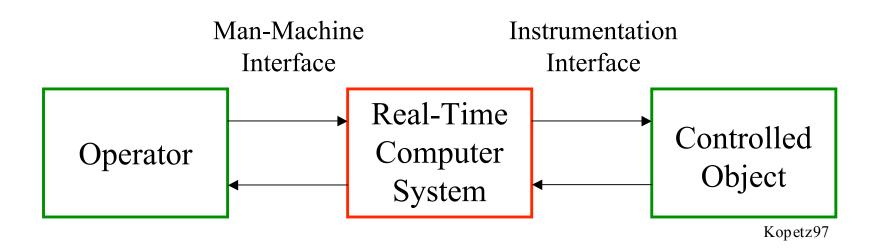
# It's risky



## It's fun



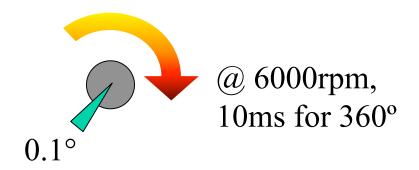
#### Problem



Methodologies for the implementation of embedded real-time applications

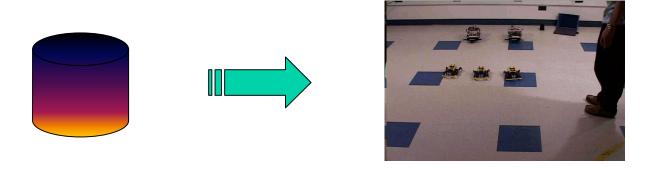
- Methodology: tool-supported, abstract, compositional
- Implementation: compositional, scalable, dependable

### Engine Controller



- Temporal accuracy of 3μsec
- Up to 100 concurrent software tasks
- Hard real-time: no missed deadlines

### Video Streaming



- 25 frames/sec
- Dynamic resource allocation
- Soft real-time: degraded QoS

# Real-Time Systems

Characteristics	Hard	Soft
Response time	Hard-required	Soft-desired
Peak-load performance	Predictable	Degraded
Control of pace	Environment	Computer
Redundancy	Active	Checkpoint
Error detection	Autonomous	User assisted

Kopetz97

#### Mechatronics

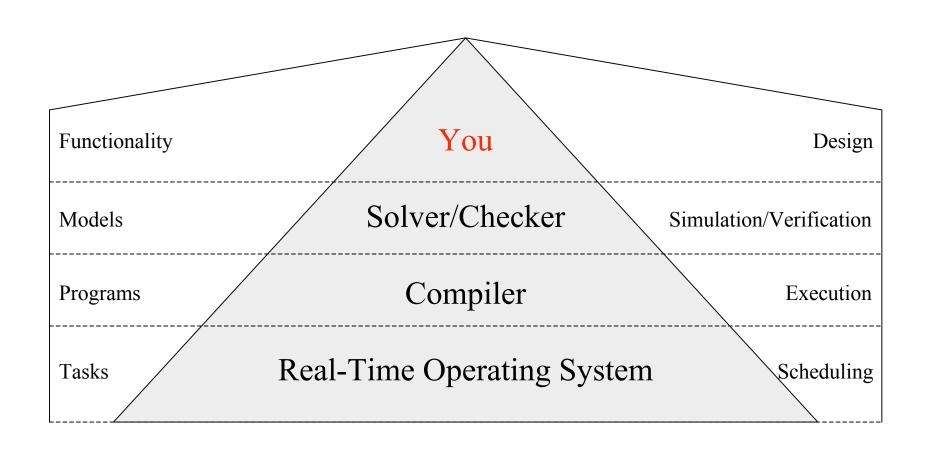


Fly-by-wire

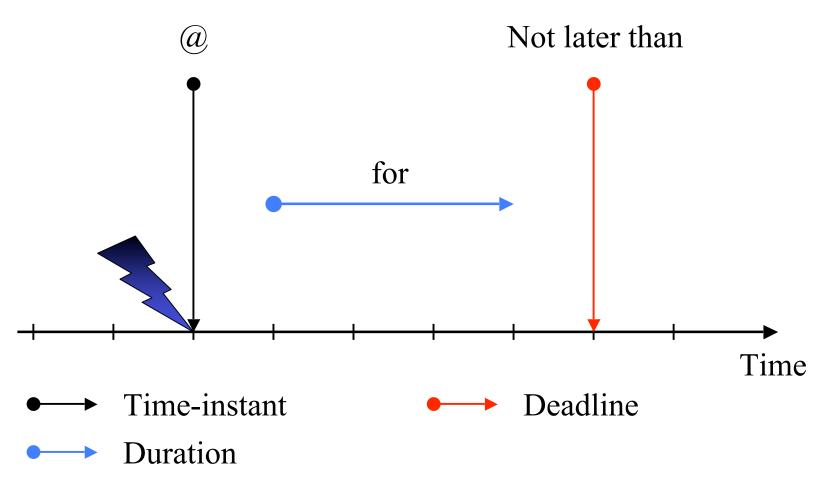


Drive-by-wire

### Embedded Software Engineering



#### Real-Time



#### Concurrency

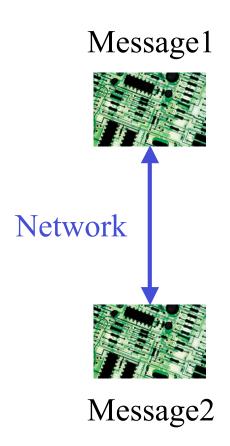
Task1 Task2



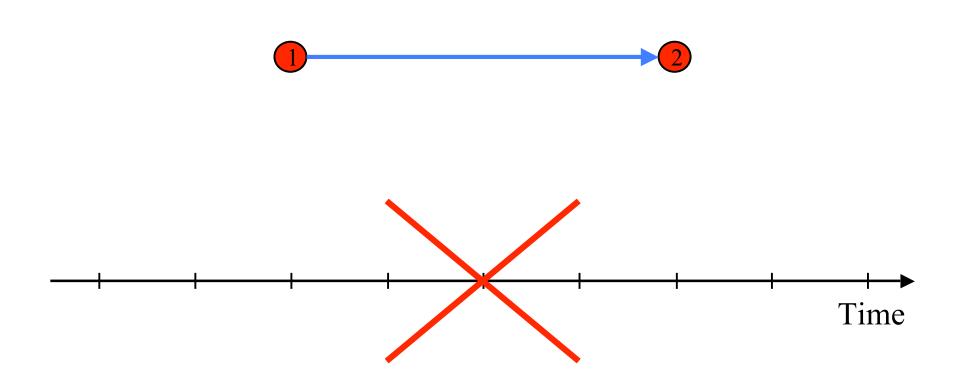
Host

In addition:

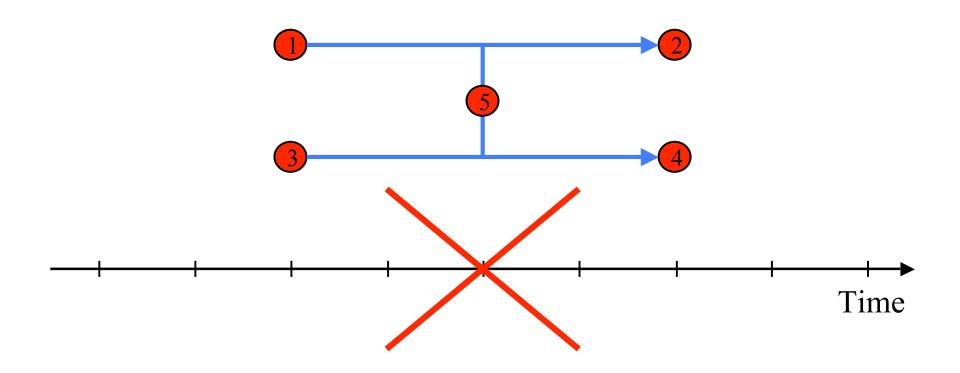
- Other resource constraints
- Time constraints



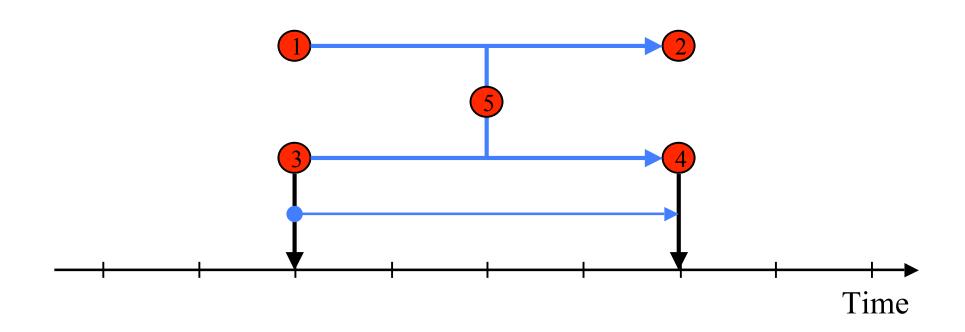
# Sequential Programming



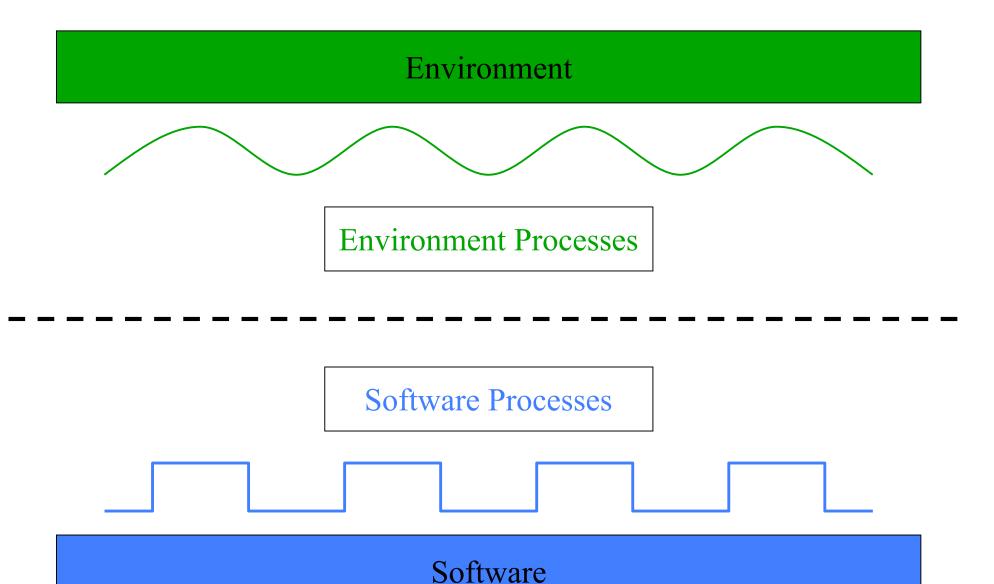
# Multiprogramming



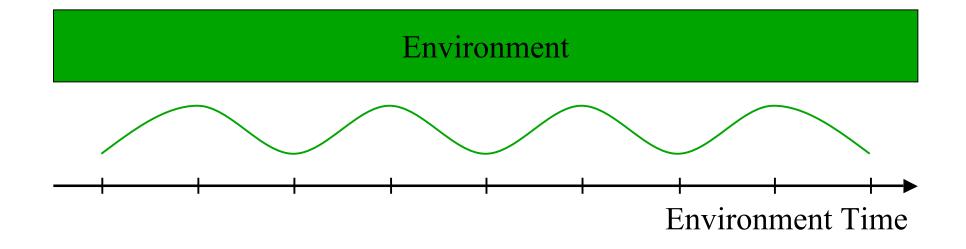
## Real-Time Programming

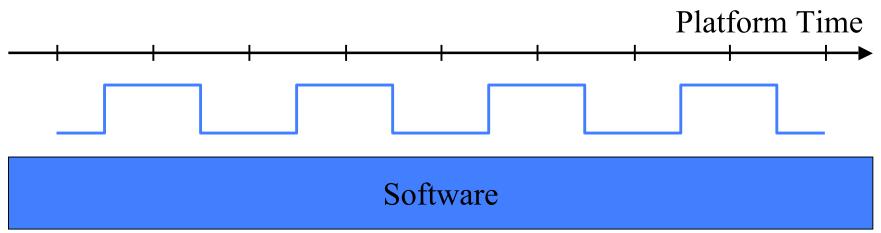


#### **Embedded Software**



#### Environment vs. Platform Time





#### The Art of Embedded Programming

