

Periodic Resource Model for Compositional Real-Time Guarantees

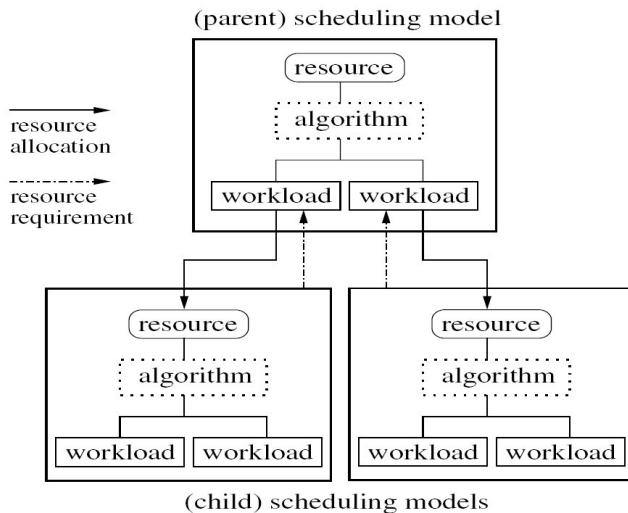
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- 1 Introduction
- 2 Periodic Resource Model
- 3 Schedulability Analysis
- 4 Schedulability Bounds
- 5 Compositional Real-Time Guarantees



- Scheduling Model $M = (W, R, A)$
 - W the workload model set
 - R the resource model
 - A the scheduling algorithm
- Limitations:
 - Periodic tasks, i.e., $T(p, e)$
 - Tasks are independent and preemptive
 - Scheduling algorithms are limited to EDF and RM

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Definition

A scheduling model $M(W, R, A)$ is *schedulable* if a set of periodic workloads W is schedulable under a scheduling algorithm A with a partitioned resource R .

Existing Resource Models

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Bounded-delay resource partition model $R_B(U_B, D_B)$: resource R is available at its full capacity at some times but not available at the other times. U_B is the availability factor (rate), and D_B measures the largest deviation of a partition on any time interval.

Two periodic tasks

- Two periodic tasks $T_1(7, 3)$ and $T_2(21, 1)$
- EDF scheduling algorithm
- Partitioned resource R is available 3 time units every 5 time units
- From Definitions 4 and 7 in [5], $R_B(U_B, D_B)$ has $U_B = 0.6$ and $D_B = 4$
- Scheduling model is $M(\{T_1, T_2\}, R_B(0.6, 4), EDF)$.

Example

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Schedulability of M according to [5]

Over the fractional resource $U_B = 0.6$, T_1 and T_2 finish their execution at least 2 time units earlier than their deadlines. According to Theorem 1 in [5] the schedulability of M is inconclusive, because $2 < 4 = D_B$.

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- 3 Utilization bound: given Γ and A find the largest possible utilization bound UB such that $M(W, \Gamma, A)$ is schedulable if $\sum_{T_i \in W} \frac{e_i}{p_i} \leq UB$

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- 4 Algorithm set: given W and Γ find a set of algorithms \mathcal{A} such that $M(W, \Gamma, A)$ is schedulable if $A \in \mathcal{A}$.
- 5 Compositional guarantee: given n scheduling models, derive a new parent scheduling model from the n scheduling models such that the new scheduling model is schedulable if and only if, the n child models are schedulable.

Periodic Resource Model

- Periodic resource model $\Gamma(\Pi, \Theta)$ characterizes a partitioned resource that guarantees allocations of Θ time units every Π time units.
- In the previous example we had $\Gamma(5, 3)$.

Definition

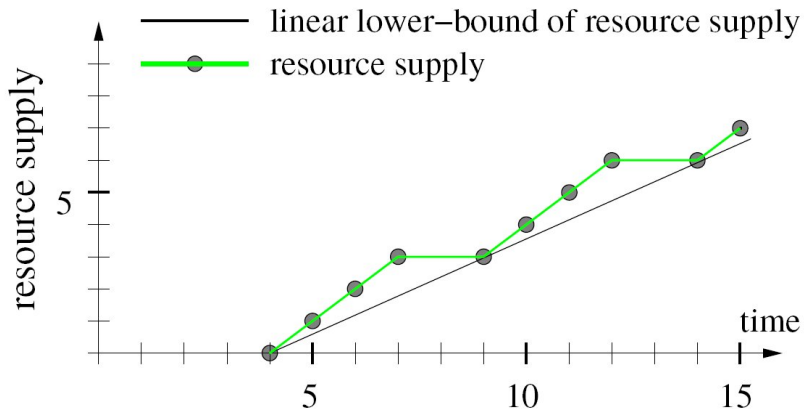
The *resource supply* of a resource is defined as the amount of resource allocation that the resource provides

Definition

For a periodic resource $\Gamma(\Pi, \Theta)$ a resource supply bound function $sbf_{\Gamma}(t)$ of a time interval length t calculates the minimum resource supply of Γ during t times units. (exact math in the paper)

- sbf_{Γ} is a non-decreasing step function
- Introduce a linear lower bound function as $lsbf_{\Gamma}$ such that $lsbf_{\Gamma}(t) \leq sbf_{\Gamma}(t)$. (exact math in the paper)

Resource supply



Definition

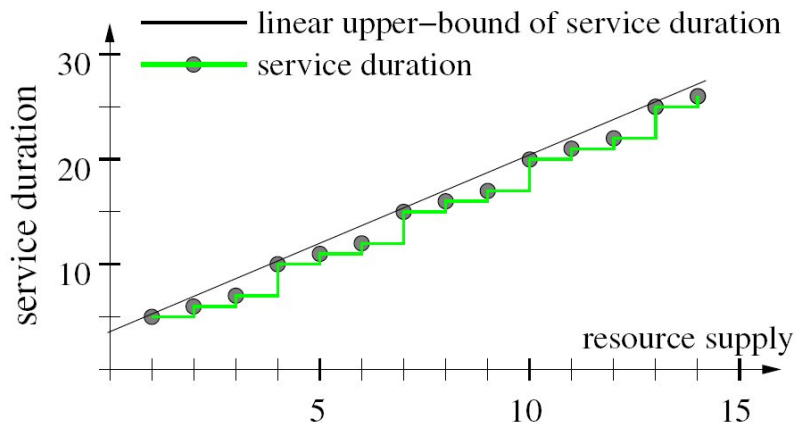
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- For a periodic resource $\Gamma(\Pi, \Theta)$, the service time bound function $tbf_{\Gamma}(t)$ calculates the maximum service time of Γ for a t -time-unit resource supply.
- tbf_{Γ} is a non-decreasing step function
- $ltbf_{\Gamma}(t)$ is a linear service time bound function that upper-bounds $tbf_{\Gamma}(t)$

Service time



Definition

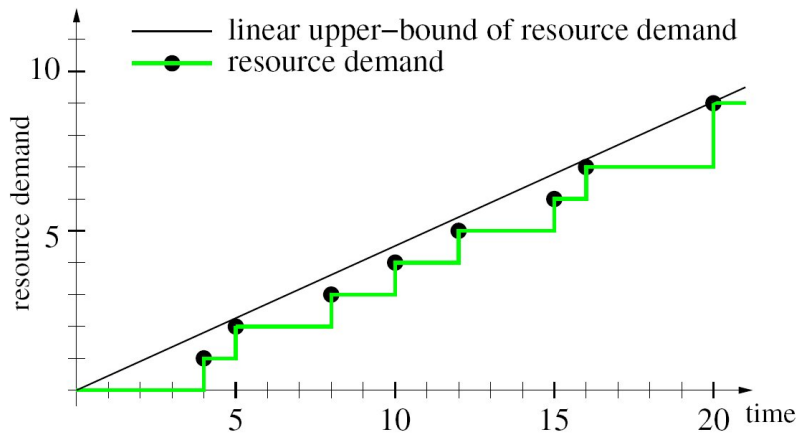
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- For a periodic workload set W the resource demand bound function $dbf_W(t)$ of a time interval length t calculates the maximum resource demand of W during t time units.
- $dbf_W(t)$ is a discrete step function.
- A linear demand bound function $ldb_W(t)$ upper-bounds $dbf_W(t)$.

Resource Demand



Theorem

For a given scheduling model $M(W, \Gamma, EDF)$, M is schedulable if and only if the resource demand of W during a time interval is no greater than the resource supply of Γ during the same time interval for all time intervals during a hyperperiod, i.e.,

$$\forall 0 < t \leq 2 \cdot LCM_W : dbf_W(t) \leq sbf_{\Gamma}(t)$$

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- Proof in the paper.

Example

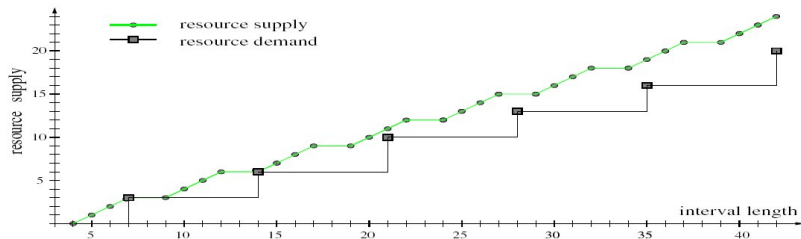
Example

- Scheduling model $M(W, \Gamma(5, 3), EDF)$
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- M is schedulable, because $dbf_W(t) \leq sbf_\Gamma(t), 0 < t \leq 42$

Schedulability Bounds

- Scheduling model $M(W, \Gamma, A)$ provides only two of its elements, but not the other element
- Find a bound for the missing element such that M is schedulable
 - *Periodic capacity bound (PCB)*: $M(W, \Gamma, A)$ provides W and A , calculate a bound for Γ .
 - *Utilization bound (UB)*: $M(W, \Gamma, A)$ provides Γ and A , calculate a bound for W .

Periodic Capacity Bounds

Definition

The *periodic capacity bound* $PCB_W(\Pi)$ of a resource period Π is a number such that a scheduling model $M(W, \Gamma(\Pi, \Theta), A)$ is schedulable if

$$PCB_W(\Pi) \leq \frac{\Theta}{\Pi}$$

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- Resource capacity:
 - Capacity of a periodic resource $\Gamma(\Pi, \Theta)$ is $\frac{\Theta}{\Pi}$
- How to get the optimal PCB_W ?
 - Assume period Π is given, and $PCB_W(\Pi, EDF) = \frac{\Theta}{\Pi}$.
 - Find the smallest possible Θ such that
$$\forall 0 < t \leq 2 \cdot LCM_W : dbf_W(t) \leq sbf_{\Gamma}(t).$$
- Use the $lsbf_{\Gamma}(t)$ function to find a PCB_W numerically. (formula in the paper)

Definition

The *utilization bound* UB_{Γ} of a given resource Γ is a number such that a scheduling model $M(W, \Gamma, A)$ is schedulable if

$$\sum_{T_i \in W} \frac{e_i}{p_i} \leq UB_{\Gamma}$$

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- Used to perform admission tests of a periodic workload set W over a given periodic resource Γ .
- Details of the formula and the proof are in the paper

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 - derive $PCB_{W_P}(\Pi_P, A_P)$

Compositional Real-Time Guarantees

- Given multiple scheduling models M_1, \dots, M_n derive a parent scheduling model $M_P(W_P, \Gamma_P, A_P)$ from M_1, \dots, M_n as follows:
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 - derive $PCB_{W_P}(\Pi_P, A_P)$
 - compute Θ_P such that $\Theta_P = \Pi_P \cdot PCB_{W_P}(\Pi_P, A_P)$.

Theorem

M_P is schedulable if and only if M_1, \dots, M_n are schedulable.

Conclusion

