

Incremental Schedulability Analysis of Hierarchical Real- Time Components

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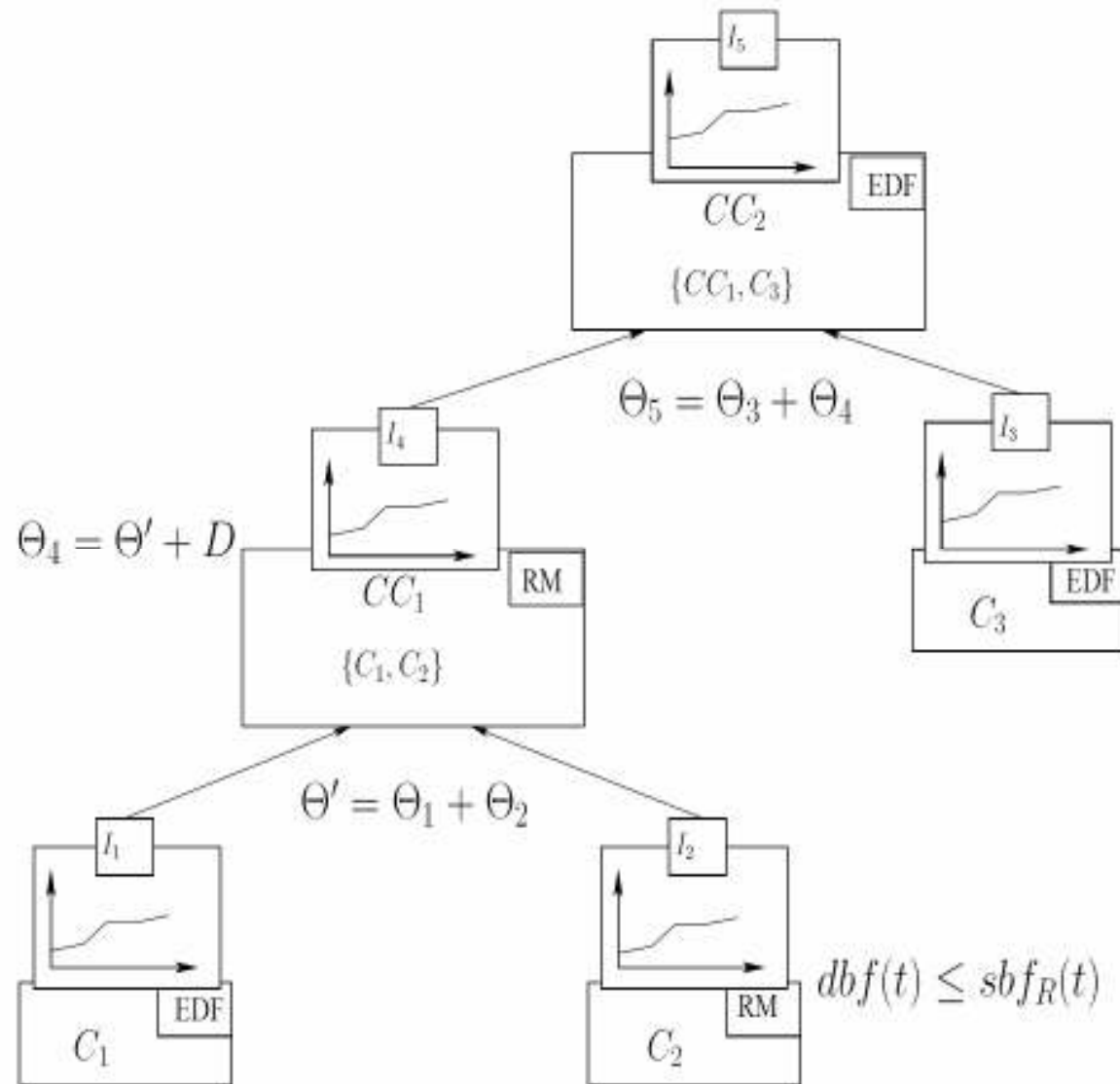
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Goals

- Compositional schedulability analysis
 - i.e. achieve system level schedulability analysis by combining component interfaces that abstract component-level timing requirements
- Minimize resource demand of components

Hierarchical Real-Time System with Interfaces



Problem Statement (1)

Given a hierarchical real-time system,

1. Generate interfaces for each real-time component such that
 - schedulability of the interface guarantees schedulability of the component
 - interface takes into consideration component context switch overhead

Problem Statement (2)

2. Compose interfaces such that
 - schedulability of the composed interface guarantees schedulability of the individual interfaces
 - composition is associative

3. Minimize the abstracted resource demand for the hierarchical system

Components

- Simple Component

$C = \langle \{T_1, \dots, T_n\}, RM / EDF \rangle$ where $T_i = (p_i, e_i)$ is a real-time task with period p_i and WCET e_i .
Deadline of T_i is assumed to be same as p_i .

- Complex Component

$C = \langle \{C_1, \dots, C_n\}, RM / EDF \rangle$ where C_i is either a simple component or another complex component.

Demand Bound Function

- Gives maximum resource demand of a component within a given time interval t

Example for EDF:

$$dbf(t) = \sum_{i=1}^n \left\lfloor \frac{t}{p_i} \right\rfloor e_i$$

$$T_i = (\text{period } p_i, \text{wcet } e_i)$$

Periodic Resource Model

- Periodic resource model

$R = (\Pi, \Theta)$ guarantees a minimum resource supply of Θ units in an time interval consisting of Π units.

- Supply bound function

$sbf_R(t)$ gives the minimum resource supply that the resource model R is guaranteed to supply within a given time period interval t .

$lsbf_R(t)$ gives the linear lower bound of $sbf_R(t)$

Schedulability

- Component C is schedulable under EDF using resource model R if (only sufficient)

$$\forall t \in (0, LCM], dbf(t) \leq lsbf_R(t)$$

- For a period Π a minimum resource capacity Θ can be computed so that C is schedulable

Interface

- Consists of set of periodic resource models R for different values of period Π

$$I = \{(\Pi, \Theta) \mid 1 \leq \Pi \leq P^*\}$$

- This allows the selection of a periodic resource model that minimizes the collective real-time requirements of an component (minimize utilization Θ/Π)

Compact Interface Representation

- Compact interface representation of a component C gives for a range of period Π a value for time instant and for the demand bound at that time instant.

$$RI = \left\{ RI_j = \langle \Pi, t_j, dbf(t_j) \rangle \mid j_{\min} \leq \Pi \leq j_{\max}, 1 \leq j \leq k \right\}$$

where, $l_{\min} = 1, k_{\max} = P^*$ and $\forall j, j_{\min} = (j-1)_{\max} + 1$

- Algorithm computes RI for component C

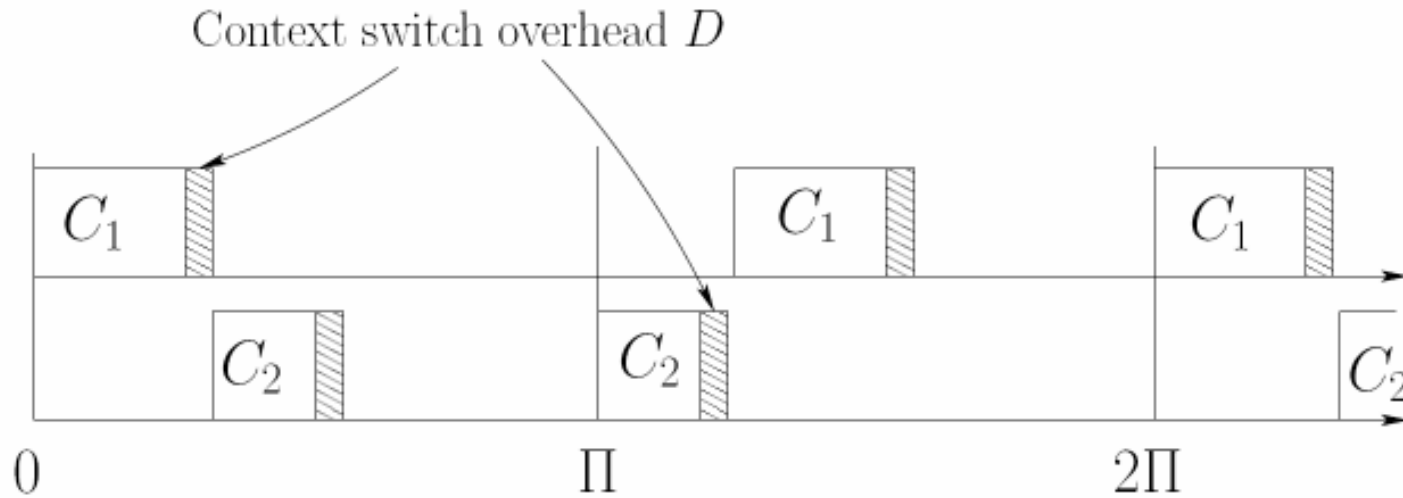
Interface Composition

- Simple addition of resource capacities Θ of individual interfaces for each value of period Π
- Take into account context switch overhead D

$$I_4 = \left\{ (\Pi, \Theta_1 + \Theta_2 + D) \mid (\Pi, \Theta_1) \in I_1, (\Pi, \Theta_2) \in I_2, 1 \leq \Pi \leq P^* \right\}$$

- Addition is associative and so composition is associative

Context Switches

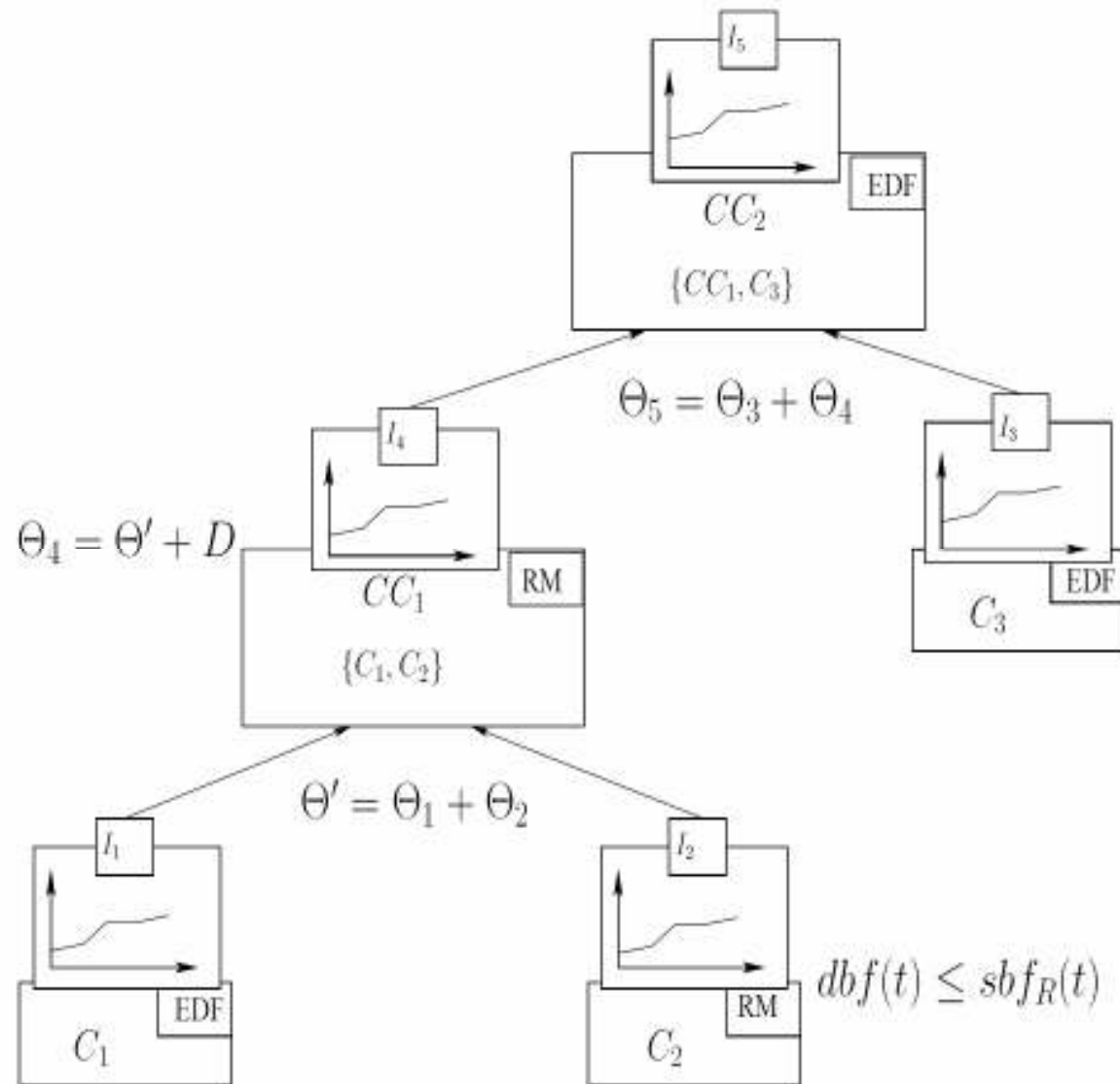


modified linear lower bound function $lsbf_R(t)$
takes context switches into account

Resource Demand Minimization

- Generate single interface I for the entire system, select value for period Π which minimizes resource demand Θ/Π .
- Export this single period to the OS for scheduling
- All interfaces have the same priority – so the OS can assign arbitrary priorities

Hierarchical Real-Time System with Interfaces



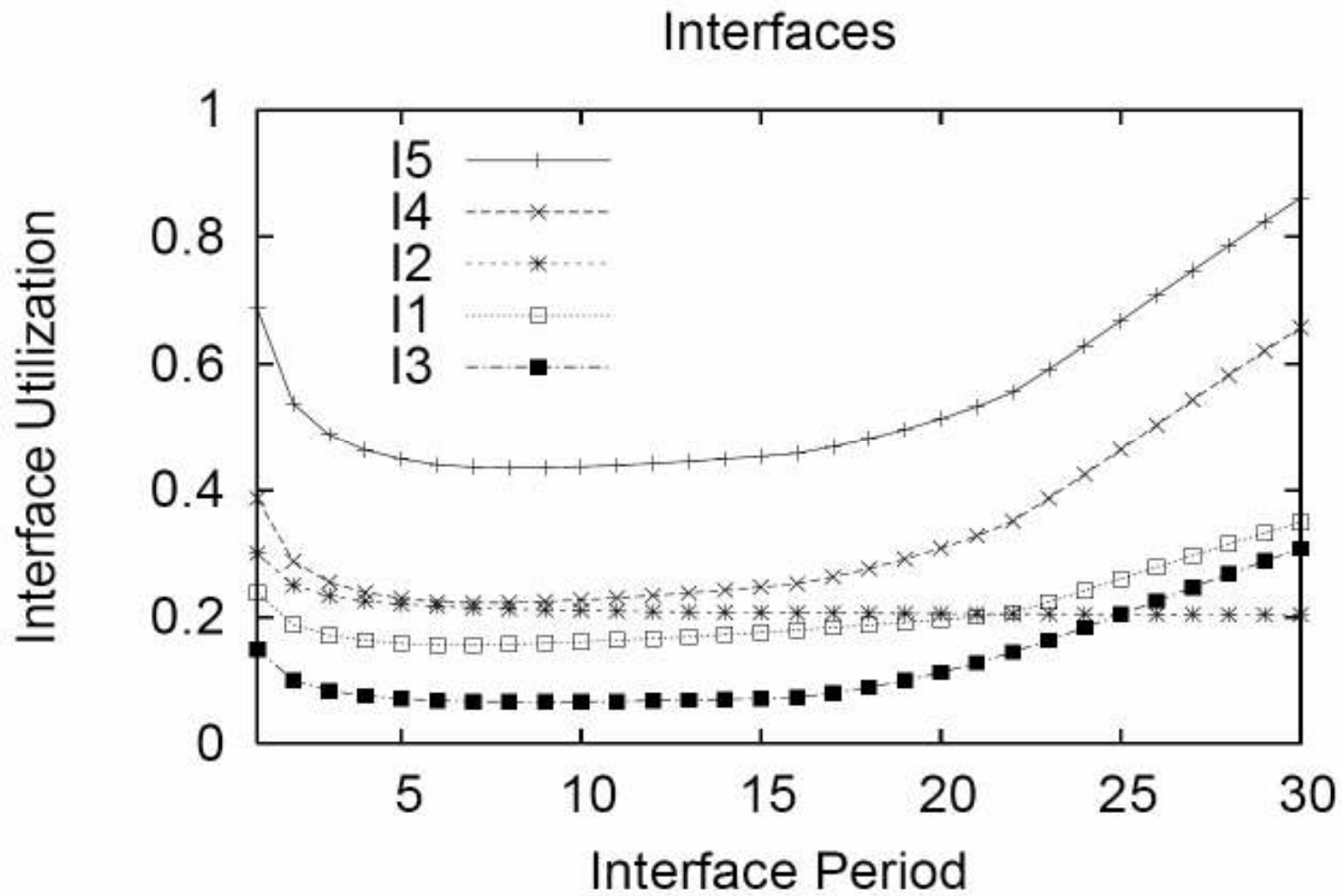
Example

$$C_1 : T_1 = (45,2), T_2 = (65,3), T_3 = (85,4)$$

$$C_2 : T_1 = (45,1), T_2 = (75,2)$$

Interface I_1			Interface I_3		
Π	t	$\text{dbf}(t)$	Π	t	$\text{dbf}(t)$
[1,1]	9945	1369	[1,1]	675	33
[2,4]	2210	304	[2,6]	225	11
[5, 6]	270	117	[7,16]	90	4
[7,21]	90	11	[17, ∞]	45	1
[22, ∞]	45	2			

Example



Example

I' : approach from previous paper

	Π	Θ	Θ/Π
$I_5 = (I_1 I_2) I_3$	8	3.4808	0.435
I'_1	6	0.932	0.155
I'_2	148	29.8	0.201
I'_3	9	0.593	0.066
$I'_4 = I'_1 ' I'_2$	4	1.563	0.391
$I'_5 = I'_3 ' I'_4$	2	1.100	0.550
$I''_5 = I'_1 ' I'_2 ' I'_3$	5	2.248	0.450

Open problem

- Whether incremental schedulability analysis (requiring associative composition) can be done with periodic resource models with varying periods