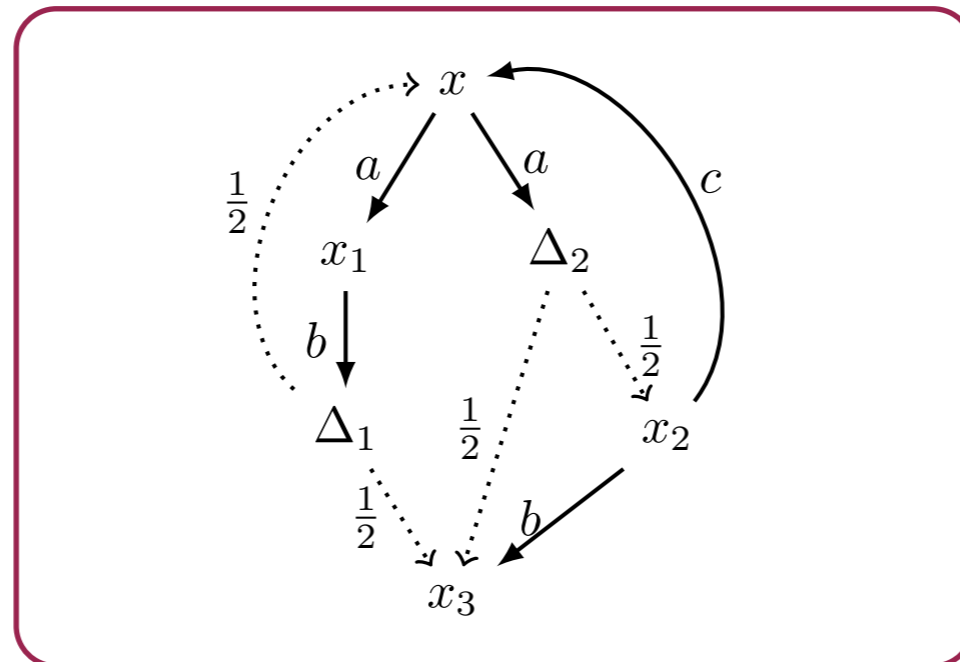


The Theory of Traces for Nondeterminism and Probability

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It's all about leaving
a trace...



Joint work with



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Valeria Vignudelli
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I will tell you about:

Mathematical framework
based on category theory
for state-based
systems semantics

1. The absolute basics of coalgebra
2. Trace semantics via determinisation
3. ...enabled by algebraic structure

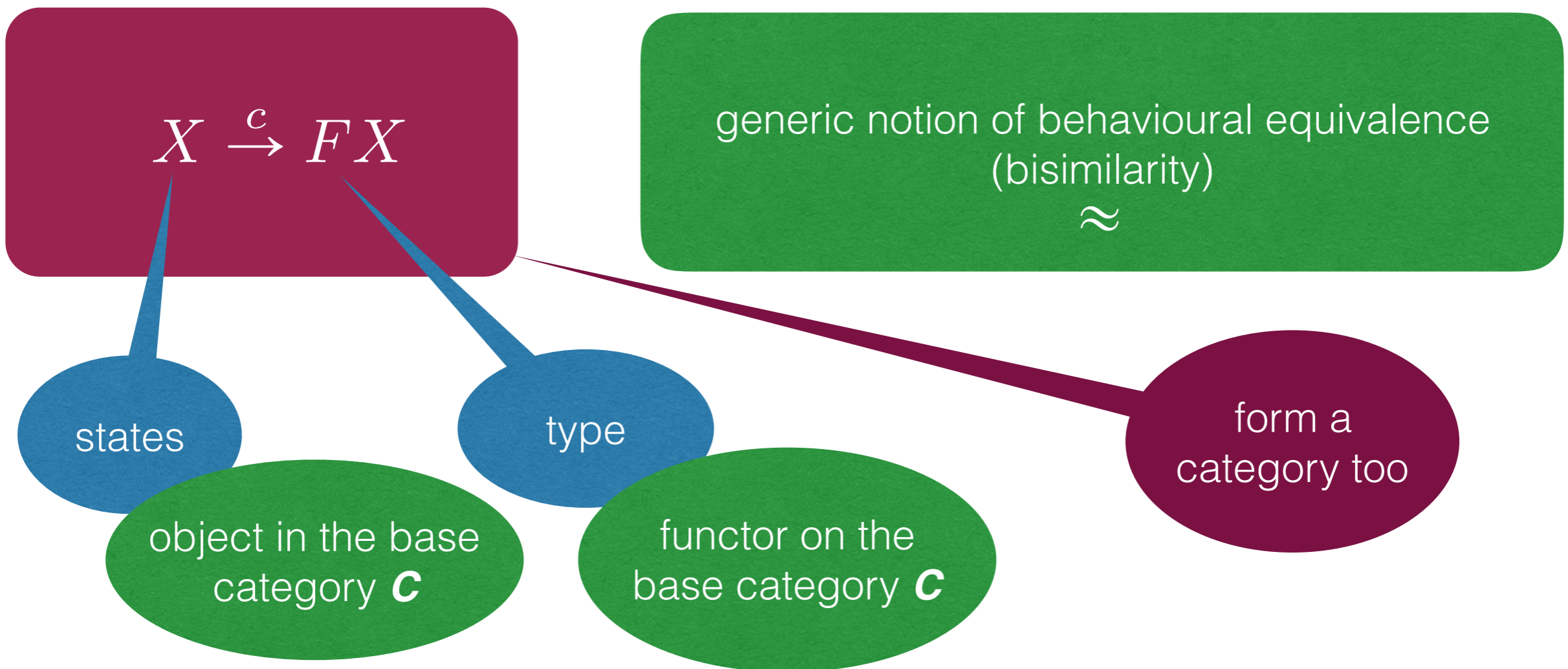
for
nondeterministic/
probabilistic
systems

systems with
algebraic effects



Coalgebras

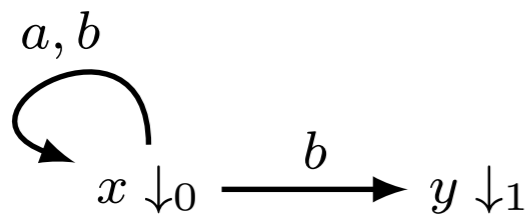
Uniform framework for dynamic transition systems, based on category theory.



Examples

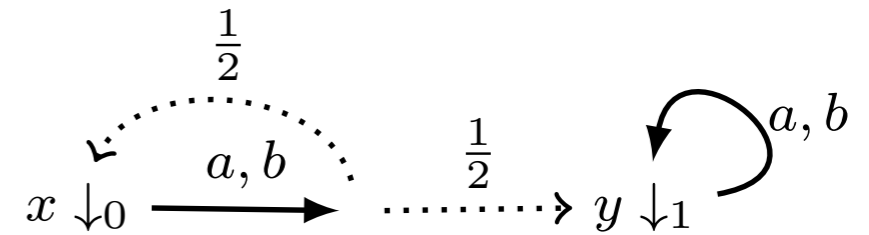
NFA

$$X \rightarrow 2 \times (\mathcal{P}X)^A$$



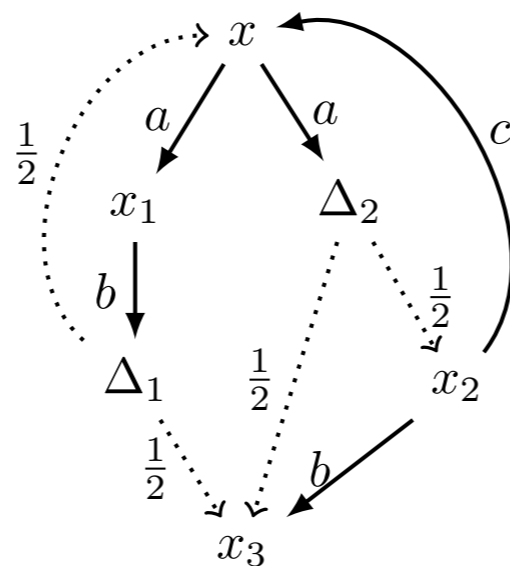
Rabin PA

$$X \rightarrow [0,1] \times (\mathcal{D}_{\leq 1}X)^A$$



Simple NPA

$$X \rightarrow ? \times (\mathcal{PD}X)^A$$

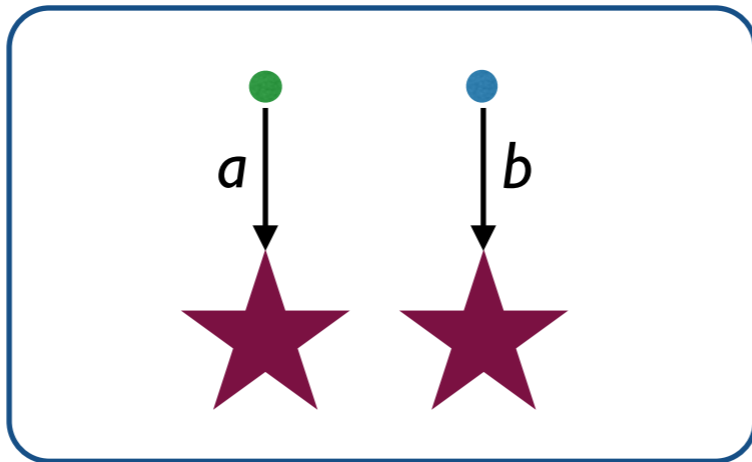


systems with
nondeterminism
and
probability

In general

Automata

$$X \rightarrow O \times (MX)^A$$



with observations in O

and M -effects

for a monad M

$$\begin{aligned} \mu: MM &\Rightarrow M \\ \eta: Id &\Rightarrow M \end{aligned}$$

providing algebraic effects

we write

$$x \downarrow O, x \xrightarrow{a} t_x$$

In our examples

NFA

$$X \rightarrow 2 \times (\mathcal{P}X)^A$$

$M = \mathcal{P}$
for nondeterminism

Powerset, subsets

Rabin PA

$$X \rightarrow [0, 1] \times (\mathcal{D}_{\leq 1}X)^A$$

$M = \mathcal{D}_{\leq 1}$
for probability

Subdistributions

Simple PA

$$X \rightarrow ? \times (\mathcal{PD}X)^A$$

$M = \mathcal{PD} ???$
for nondeterminism
and probability

In our examples

NFA

$$X \rightarrow 2 \times (\mathcal{P}X)^A$$

$M = \mathcal{P}$
for nondeterminism

Powerset, subsets

Rabin PA

$$X \rightarrow [0, 1] \times (\mathcal{D}_{\leq 1}X)^A$$

$M = \mathcal{D}_{\leq 1}$
for probability

Subdistributions

Simple PA

$$X \rightarrow ? \times (\mathcal{E}X)^A$$

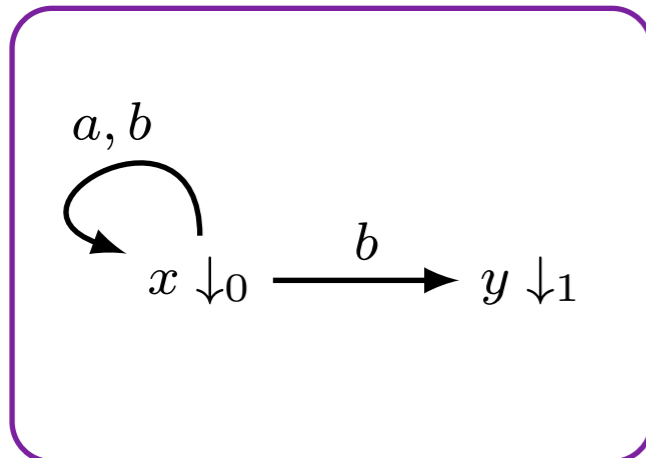
$M = \mathcal{E}$
for nondeterminism
and probability !

Nonempty f.g. convex
subsets of
distributions

Trace Semantics

NFA = LTS + termination

$$X \rightarrow 2 \times (\mathcal{P}X)^A$$



$$\text{tr}: X \rightarrow 2^{A^*}$$

$$\text{tr}(x) = (a \cup b)^* b = \{w \in \{a, b\}^* \mid w \text{ ends with a } b\}$$

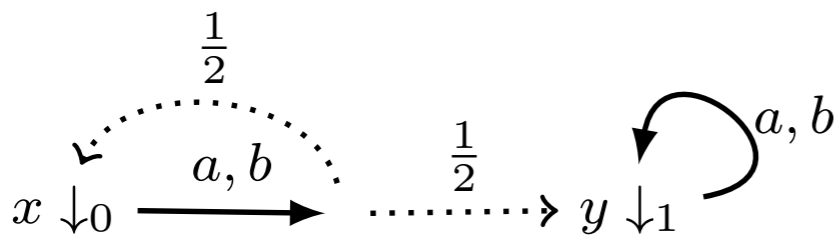
language
semantics

Trace Semantics

Rabin PA = RPTS + termination

$$X \rightarrow [0, 1] \times (\mathcal{D}_{\leq 1} X)^A$$

probabilistic
language
semantics



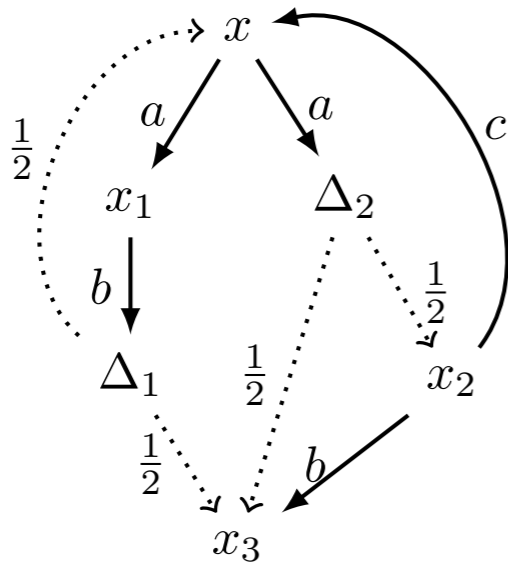
$$\text{tr}(x) = \left(a \mapsto \frac{1}{2}, aa \mapsto \frac{3}{4}, \dots \right)$$

$$\text{tr}: X \rightarrow [0, 1]^{A^*}$$

Trace Semantics

Simple NPA

$$X \rightarrow ? x (\mathcal{PDX})^A$$



$$\text{tr}(x) = ???$$

$$\text{tr}: X \rightarrow ?^{A^*}$$

nondet.
probabilistic
language
semantics ?

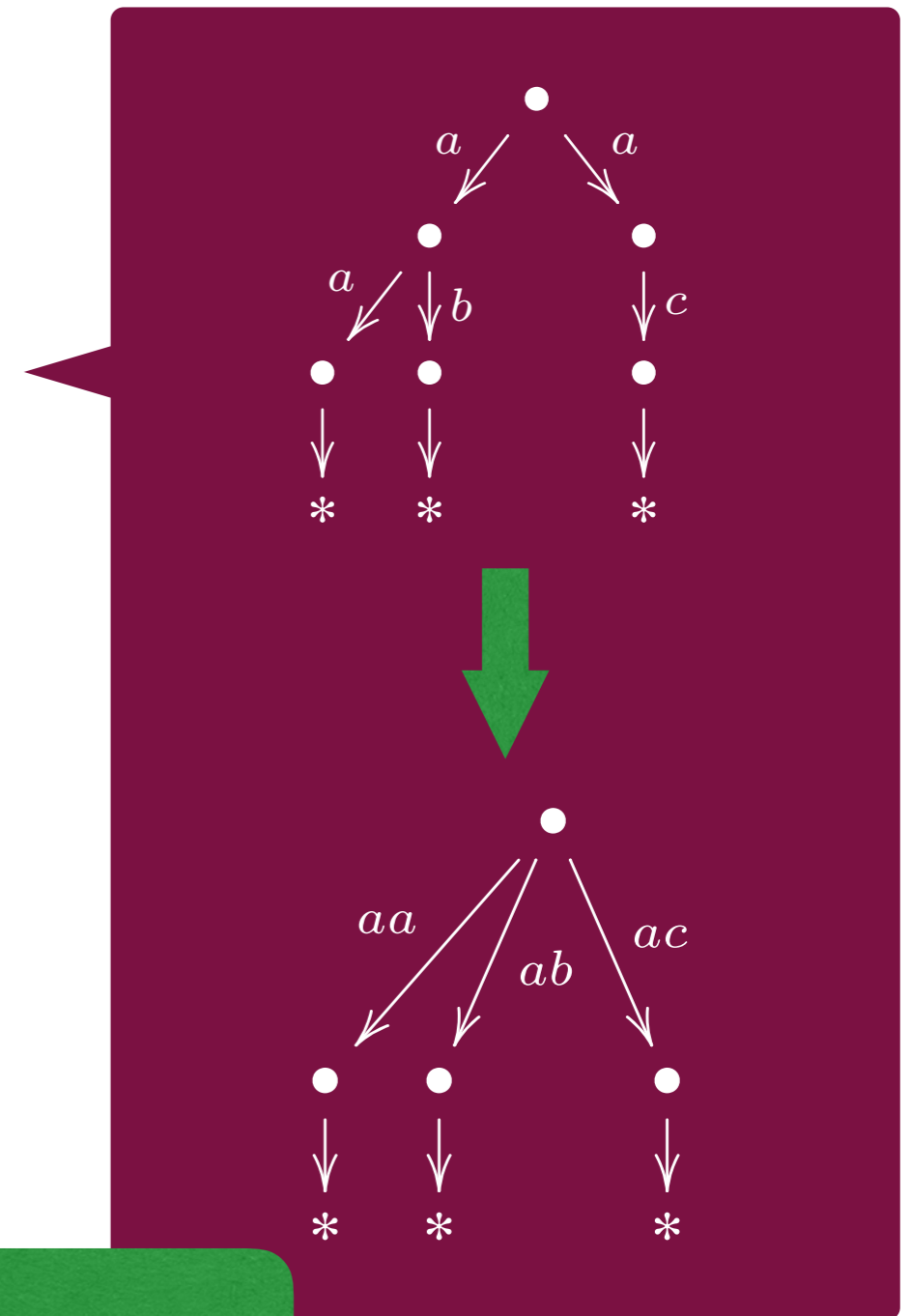
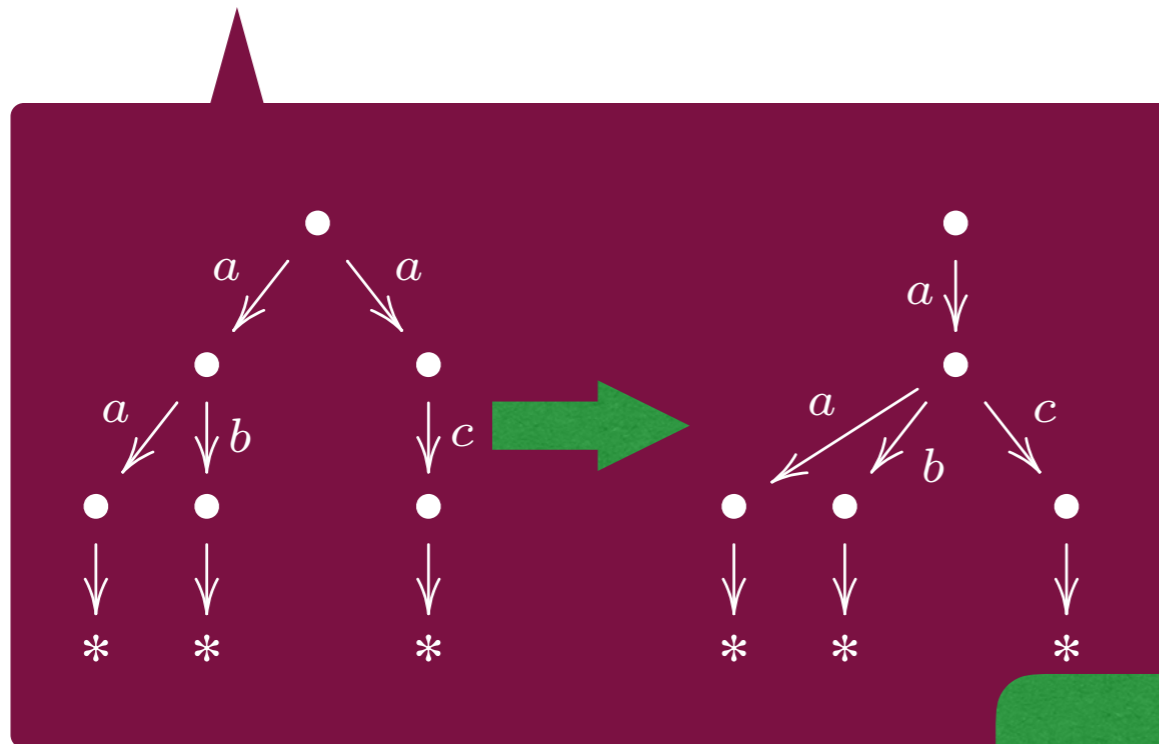
Existing definitions
are “local”
given in terms of
schedulers

Trace semantics coalgebraically?

NFA / LTS

Two ideas:

- (1) unfold branching + transitions on words
- (2) trace = bisimilarity after determinisation



monads !

Trace semantics coalgebraically

Two approaches:

(1) modelling in a Kleisli category

(2) modelling in an Eilenberg-Moore category

Hasuo,
Jacobs, S.
LMCS '07

Silva, Bonchi,
Bonsangue, Rutten
FSTTCS'10

algebras of a monad M

Jacobs, Silva, S.
JCSS'15

(1) and (2) are related

Traces via determinisation

Automaton with M-effects

$$X \rightarrow O \times (MX)^A$$

O has to be an M-algebra!

Determinisation

$$MX \rightarrow O \times (MX)^A$$

MX carries the free M-algebra

trace = bisimilarity after determinisation

Algebras for M

ideally we have a presentation

$$\text{tr}: X \rightarrow O^{A^*}$$

Eilenberg-Moore algebras

$$\text{tr}(x)(a_1 a_2 \dots a_n) = o \iff x \xrightarrow{a_1} t_1 \xrightarrow{a_2} t_2 \dots t_{n-1} \xrightarrow{a_n} t_n \wedge t_n \downarrow o$$



Eilenberg-Moore Algebras

abstractly

$\mathcal{EM}(M)$

- objects

$$\begin{array}{c} MA \\ \downarrow a \\ A \end{array}$$

satisfying

$$\begin{array}{ccc} A & \xrightarrow{\eta} & MA \\ & \searrow a & \downarrow a \\ & & A \end{array} \qquad \begin{array}{ccc} MMA & \xrightarrow{\mu} & MA \\ Ma \downarrow & & \downarrow a \\ MA & \xrightarrow{a} & A \end{array}$$

- morphisms

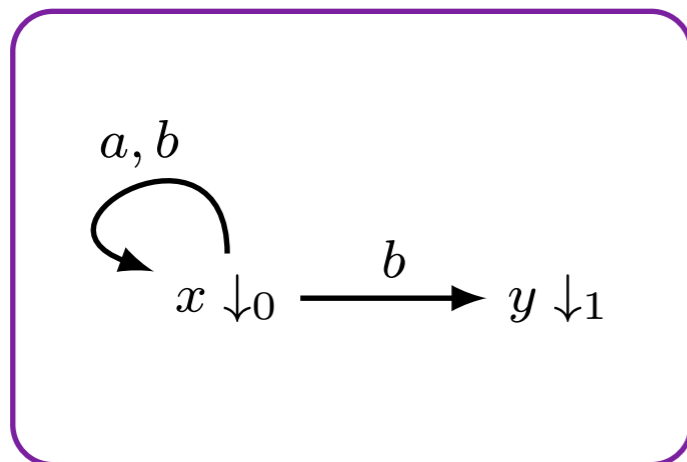
$$\begin{array}{c} MA \\ \downarrow a \\ A \end{array} \xrightarrow{h} \begin{array}{c} MB \\ \downarrow b \\ B \end{array}$$

$$\begin{array}{ccc} MA & \xrightarrow{Mh} & MB \\ a \downarrow & & \downarrow b \\ A & \xrightarrow{h} & B \end{array}$$

Traces via determinisation

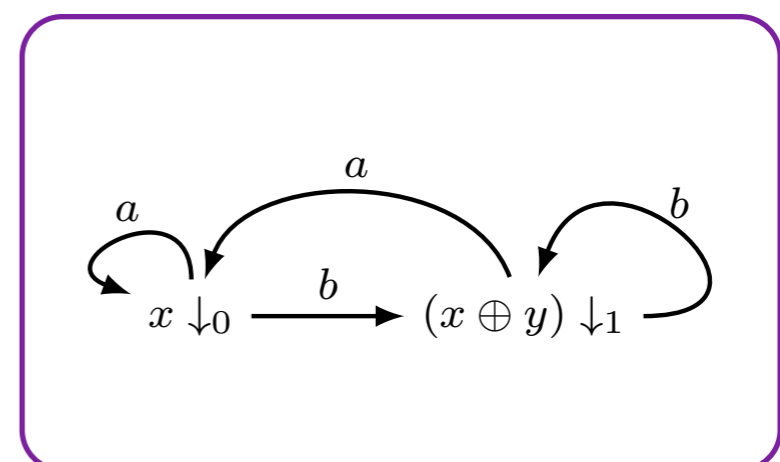
NFA

$$X \rightarrow 2 \times (\mathcal{P}X)^A$$



DFA

$$\mathcal{P}X \rightarrow 2 \times (\mathcal{P}X)^A$$



$$x \xrightarrow{a} t_x, y \xrightarrow{a} t_y$$

$$x \oplus y \xrightarrow{a} t_x \oplus t_y$$

$$x \downarrow o_x, y \downarrow o_y$$

$$x \oplus y \downarrow o_x \oplus o_y$$

finite powerset !

Algebras for \mathcal{P}

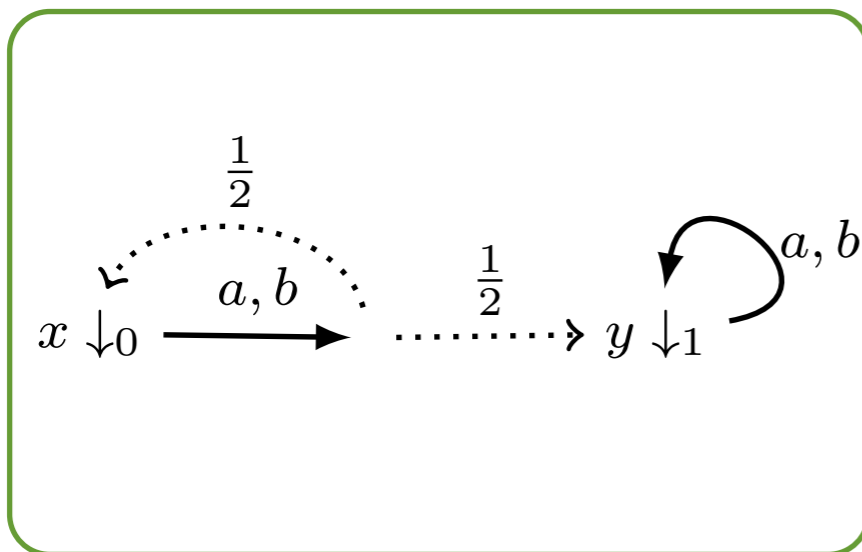
join
semilattices
with bottom

$$2 = \mathcal{P}1$$

Traces via determinisation

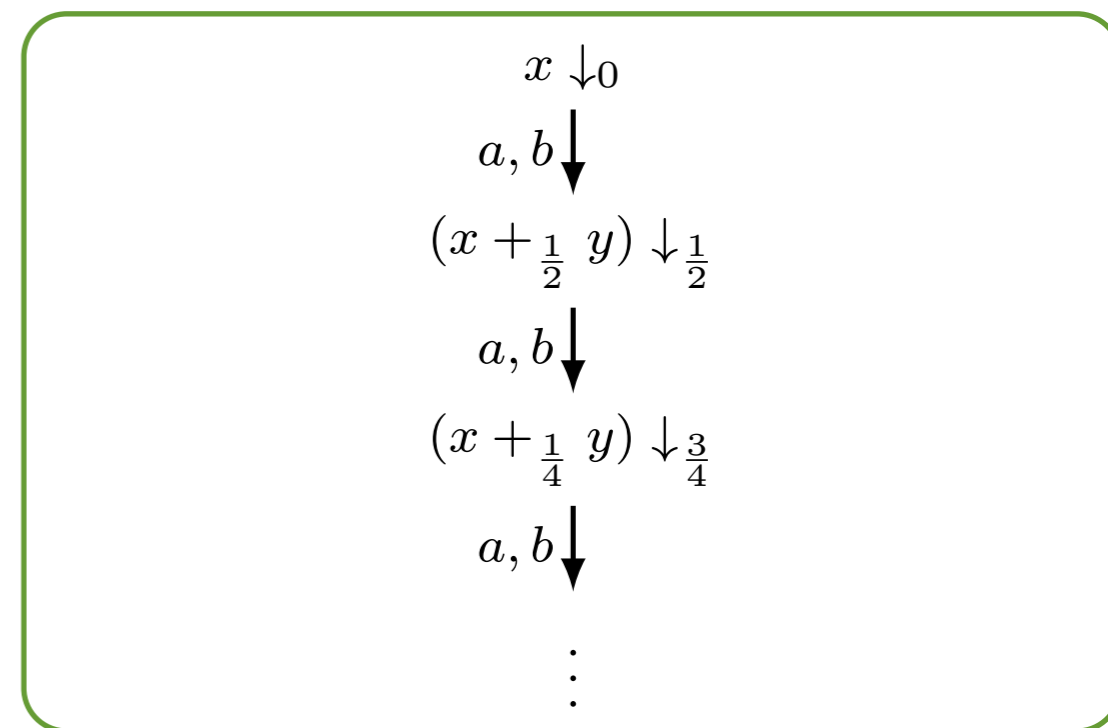
Rabin PA

$$X \rightarrow [0, 1] \times (\mathcal{D}_{\leq 1} X)^A$$



DPA

$$\mathcal{D}_{\leq 1} X \rightarrow [0, 1] \times (\mathcal{D}_{\leq 1} X)^A$$



Algebras for $\mathcal{D}_{\leq 1}$

positive
convex
algebras

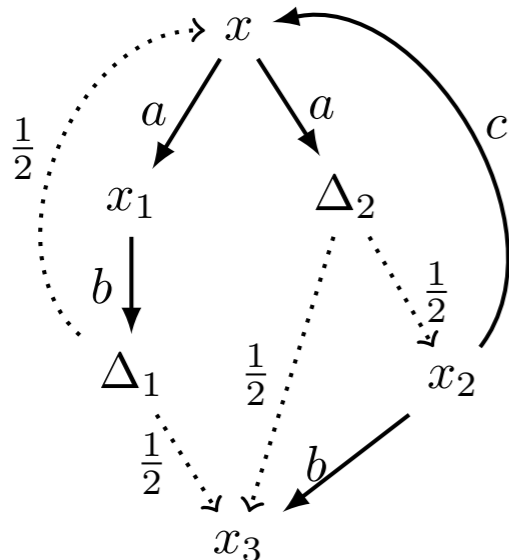
finitely supported
subdistributions!

$$[0, 1] = \mathcal{D}_{\leq 1} 1$$

Traces via determinisation

Simple NPA

$$X \rightarrow ? x (eX)^A$$



DNPA

$$eX \rightarrow ? x (eX)^A$$

$$\begin{array}{c}
 x_1 \\
 \downarrow a \\
 x_1 \oplus (x_3 + \frac{1}{2} x_2)
 \end{array}$$



$$? = e1$$

Algebras for \mathcal{C}

convex
semilattices

finitely generated
convex sets of distr...

Presentation for \mathcal{C}

Algebras for \mathcal{C}

convex
semilattices

Bonchi, S.,
Vignudelli '19

finitely generated
convex sets of distr...

$$\begin{array}{lcl} (x \oplus y) \oplus z & \stackrel{(A)}{=} & x \oplus (y \oplus z) \\ x \oplus y & \stackrel{(C)}{=} & y \oplus x \\ x \oplus x & \stackrel{(I)}{=} & x \end{array}$$

semilattice

$$\mathbb{A} = (A, \oplus, +_p)$$

$p \in (0, 1)$

$$\begin{array}{lcl} (x +_q y) +_p z & \stackrel{(A_p)}{=} & x +_{pq} (y +_{\frac{p(1-q)}{1-pq}} z) \\ x +_p y & \stackrel{(C_p)}{=} & y +_{1-p} x \\ x +_p x & \stackrel{(I_p)}{=} & x \end{array}$$

convex
algebra

S., Woracek
'15, '17, '18

$$(x \oplus y) +_p z \stackrel{(D)}{=} (x +_p z) \oplus (y +_p z)$$

distributivity

Three variants for “ e ”

Algebras for “ e ”

nonempty f.g.
convex subsets of
subdistr...

I. pointed
convex
semilattices

Intervals
in $[0, 1]$ with min-
max, Minkowski,
and $[0, 0] =$
“ e ”

II.
with bottom

$[0, 1]$ with
max, $+_p$ and $0 =$
“ e ”

III.
with top

$[0, 1]$ with
min, $+_p$ and $0 =$
“ e ”

Bonchi, S.,
Vignudelli '19

We explore the whole space
and
prove coincidence with “local”
trace semantics

Three things to take home:

Many general properties follow
also a sound up-to context
proof technique

1. Semantics via determinisation is easy for automata with M-effects
2. Having a presentation for M gives us syntax
3. Having the syntax makes determinisation natural !

combining
nondeterminism
and probability
becomes easy

Thank You !