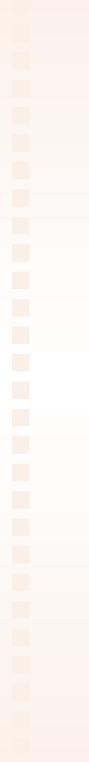
Hierarchy of probabilistic systems

Ana Sokolova, Erik de Vink, Falk Bartels

{asokolov,evink}@win.tue.nl falk.bartels@cwi.nl.

TU/e and CWI



Basic coalgebraic notions



- Basic coalgebraic notions
 - * labelled transition systems

- Basic coalgebraic notions
 - * labelled transition systems
 - * bisimulation

- Basic coalgebraic notions
 - * labelled transition systems
 - * bisimulation
- Probabilistic system types

- Basic coalgebraic notions
 - * labelled transition systems
 - * bisimulation
- Probabilistic system types
- Comparison of system types

- Basic coalgebraic notions
 - * labelled transition systems
 - * bisimulation
- Probabilistic system types
- Comparison of system types
 - * expressiveness criterion

- Basic coalgebraic notions
 - * labelled transition systems
 - * bisimulation
- Probabilistic system types
- Comparison of system types
 - * expressiveness criterion
 - * translation of coalgebras

- Basic coalgebraic notions
 - * labelled transition systems
 - * bisimulation
- Probabilistic system types
- Comparison of system types
 - * expressiveness criterion
 - * translation of coalgebras
 - * preservation and reflection of bisimulation

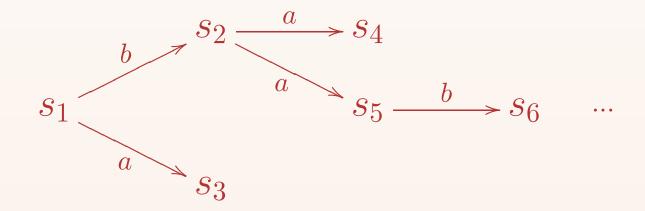
- Basic coalgebraic notions
 - * labelled transition systems
 - * bisimulation
- Probabilistic system types
- Comparison of system types
 - * expressiveness criterion
 - * translation of coalgebras
 - * preservation and reflection of bisimulation
- Building the hierarchy

- Basic coalgebraic notions
 - * labelled transition systems
 - * bisimulation
- Probabilistic system types
- Comparison of system types
 - * expressiveness criterion
 - * translation of coalgebras
 - * preservation and reflection of bisimulation
- Building the hierarchy
- Conclusions

LTS is a pair $\langle S, \alpha : S \to \mathcal{P}(A \times S) \rangle$ A - a fixed set of actions

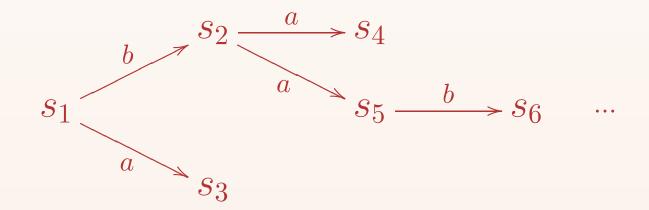
LTS is a pair $\langle S, \alpha : S \to \mathcal{P}(A \times S) \rangle$ A - a fixed set of actions Hence a coalgebra $\langle S, \alpha \rangle, \ \alpha : S \to \mathcal{F}S$ of the functor $\mathcal{F} = \mathcal{P}(A \times \mathcal{I})$

LTS is a pair $\langle S, \alpha : S \to \mathcal{P}(A \times S) \rangle$ A - a fixed set of actions



LTS is a pair $\langle S, \alpha : S \to \mathcal{P}(A \times S) \rangle$ A - a fixed set of actions

Example:



Note: $\mathcal{P}(A \times \mathcal{I}) \cong \mathcal{P}^A$

 $\langle S, \alpha \rangle$, $\langle T, \beta \rangle$ - LTS

 $\langle S, \alpha \rangle$, $\langle T, \beta \rangle$ - LTS

 $R \subseteq S \times T$ is a concrete bisimulation if for all $\langle s, t \rangle \in R$ and all $a \in A$

 $\langle S, \alpha \rangle$, $\langle T, \beta \rangle$ - LTS

 $R \subseteq S \times T$ is a concrete bisimulation if for all $\langle s, t \rangle \in R$ and all $a \in A$

> $s \xrightarrow{a} s' \Rightarrow (\exists t')t \xrightarrow{a} t', \langle s', t' \rangle \in R$ and $t \xrightarrow{a} t' \Rightarrow (\exists s')s \xrightarrow{a} s', \langle s', t' \rangle \in R$

 $\langle S, \alpha \rangle$, $\langle T, \beta \rangle$ - LTS

 $R \subseteq S \times T$ is a concrete bisimulation if for all $\langle s, t \rangle \in R$ and all $a \in A$

$$s \xrightarrow{a} s' \Rightarrow (\exists t')t \xrightarrow{a} t', \langle s', t' \rangle \in R$$
 and
 $t \xrightarrow{a} t' \Rightarrow (\exists s')s \xrightarrow{a} s', \langle s', t' \rangle \in R$

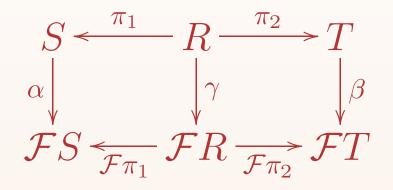
 $s \approx t$ - there exists a concrete bisimulation R with $\langle s, t \rangle \in R$

Coalgebraic bisimulation

A bisimulation between two \mathcal{F} -coalgebras $\langle S, \alpha \rangle$ and $\langle T, \beta \rangle$ is a relation $R \subseteq S \times T$ such that there exists a \mathcal{F} -coalgebra structure γ on R making

Coalgebraic bisimulation

A bisimulation between two \mathcal{F} -coalgebras $\langle S, \alpha \rangle$ and $\langle T, \beta \rangle$ is a relation $R \subseteq S \times T$ such that there exists a \mathcal{F} -coalgebra structure γ on R making



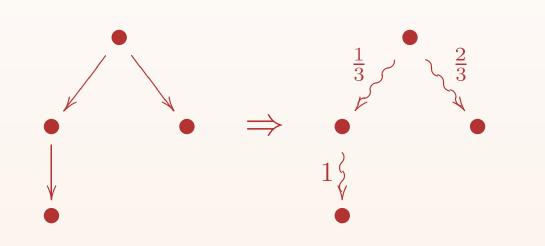
Concrete vs coalgebraic (LTS) $\langle S, \alpha \rangle, \langle T, \beta \rangle$ - LTS (coalgebras of type $\mathcal{F} = \mathcal{P}(A \times \mathcal{I})$)

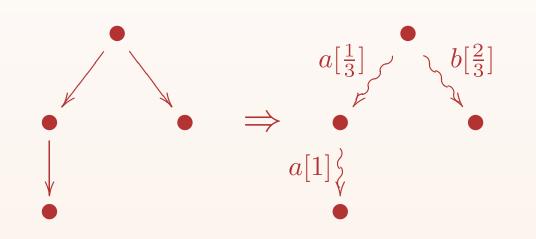
 $s \sim t$ - there exists a bisimulation R with $\langle s, t \rangle \in R$.

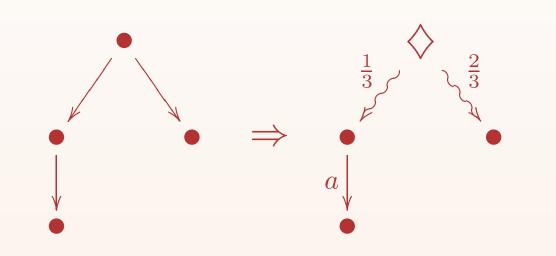
Concrete vs coalgebraic (LTS) $\langle S, \alpha \rangle, \langle T, \beta \rangle$ - LTS (coalgebras of type $\mathcal{F} = \mathcal{P}(A \times \mathcal{I})$)

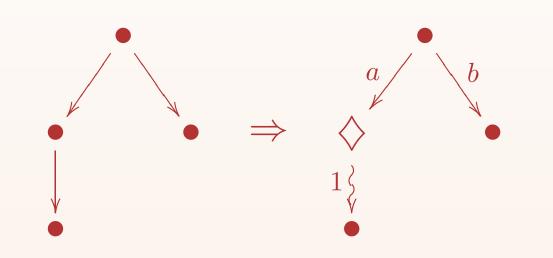
 $s \sim t$ - there exists a bisimulation R with $\langle s, t \rangle \in R$.

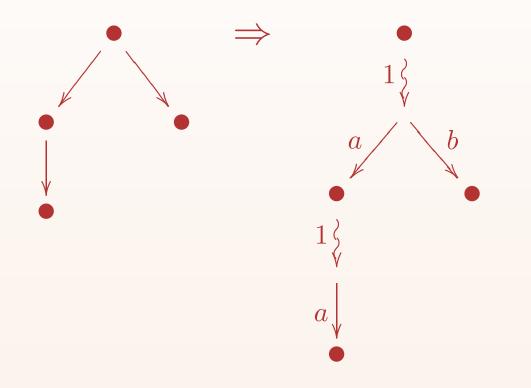
known: $s \approx t$ if and only if $s \sim t$

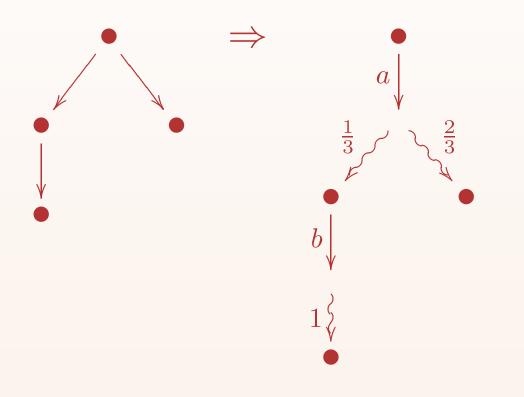






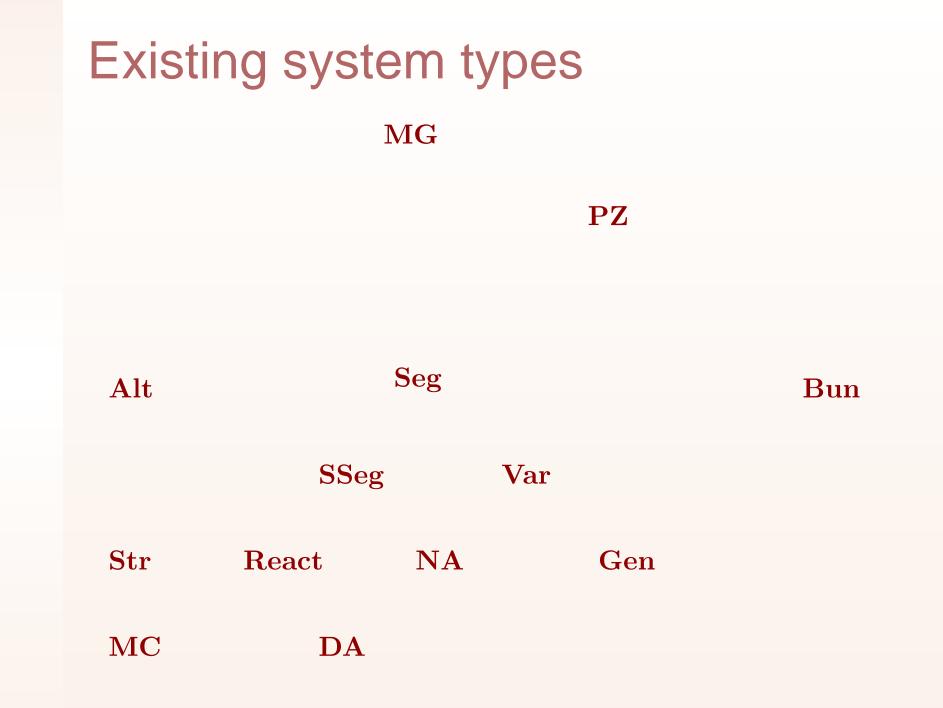






13 types of systems - from the literature with (or without):

- action labels
- nondeterminism
- probabilities





The (probabilistic) models of systems we consider are coalgebras

 $\langle S, \alpha \rangle, \ \alpha : S \to \mathcal{F}S$

for a functor \mathcal{F} built by the following syntax

 $\mathcal{F} ::= \mathcal{C} \mid \mathcal{I} \mid \mathcal{P} \mid \mathcal{D}_{\omega} \mid \mathcal{F}_1 + \mathcal{F}_2 \mid \mathcal{F}_1 \times \mathcal{F}_2 \mid \mathcal{F}^{\mathcal{C}} \mid \mathcal{F}_2 \mathcal{F}_1$

where

 $\mathcal{D}_{\omega}X := \left\{ \mu : X \to [0,1] \mid \mathsf{supp}(\mu) \text{ finite}, \ \mu[X] = 1 \right\}$

Reactive and generative systems

evolve from LTS - functor $\mathcal{P}(A \times \mathcal{I}) \cong \mathcal{P}^A$

Reactive and generative systems



Reactive and generative systems

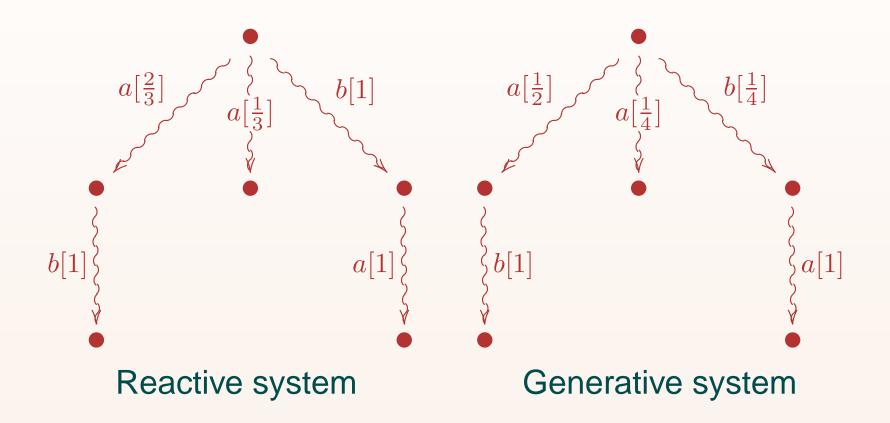
evolve from LTS - functor $\mathcal{P}(A \times \mathcal{I}) \cong \mathcal{P}^{A}$ Reactive systems functor $(\mathcal{D}_{\omega} + 1)^{A}$ Generative systems functor $(\mathcal{D}_{\omega} + 1)(A \times \mathcal{I}) = \mathcal{D}_{\omega}(A \times \mathcal{I}) + 1$

Reactive and generative systems

evolve from LTS - functor $(\mathcal{P})(A \times \mathcal{I}) \cong (\mathcal{P})^A$ **Reactive systems** functor $(\mathcal{D}_{\omega}+1)^A$ Generative systems functor $(\mathcal{D}_{\omega} + 1)(A \times \mathcal{I}) = \mathcal{D}_{\omega}(A \times \mathcal{I}) + 1$ note: In the probabilistic case $(\mathcal{D}_{\omega}+1)^A \not\cong \mathcal{D}_{\omega}(A \times \mathcal{I}) + 1$

Reactive and generative systems

Example:



Bisimulation - generative systems $\langle S, \alpha \rangle, \langle T, \beta \rangle$ - generative systems $R \subseteq S \times T$ is a concrete bisimulation if for all $a \in A$, for all $\langle s, t \rangle \in R$ with $\mu = \alpha(s), \nu = \beta(t)$ and every component *C* of *R*:

 $\mu(a, C) = \nu(a, C)$

Bisimulation - generative systems $\langle S, \alpha \rangle, \langle T, \beta \rangle$ - generative systems $R \subseteq S \times T$ is a concrete bisimulation if for all $a \in A$, for all $\langle s, t \rangle \in R$ with $\mu = \alpha(s), \nu = \beta(t)$ and every component *C* of *R*:

 $\mu(a, C) = \nu(a, C)$

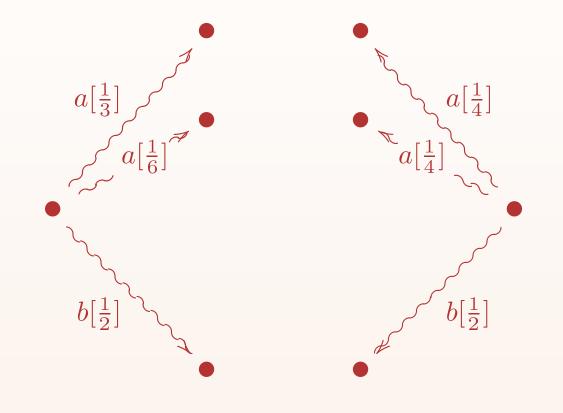
$$\sum_{s'\in\pi_1(C)}\mu(a,s') = \sum_{t'\in\pi_2(C)}\nu(a,t')$$

Bisimulation - generative systems $\langle S, \alpha \rangle, \langle T, \beta \rangle$ - generative systems $R \subseteq S \times T$ is a concrete bisimulation if for all $a \in A$, for all $\langle s, t \rangle \in R$ with $\mu = \alpha(s), \nu = \beta(t)$ and every component *C* of *R*:

 $\mu(a, C) = \nu(a, C)$

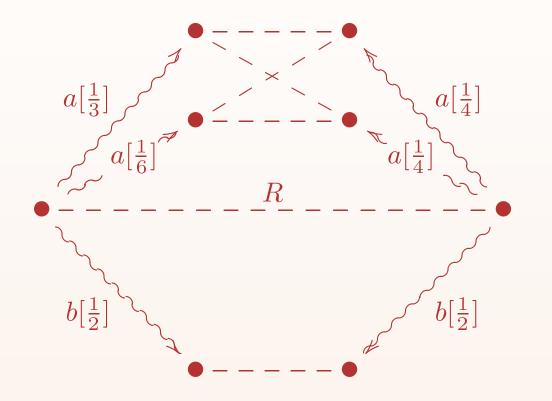
 $s \thickapprox t$ - there exists a concrete bisimulation R with $\langle s,t \rangle \in R$

Bisimulation - generative systems Example:



Bisimulation - generative systems

Example:



Bisimulation - generative systems

 $\langle S, \alpha \rangle, \langle T, \beta \rangle$ - generative systems

 $R \subseteq S \times T$ is a concrete bisimulation if for all $a \in A$, for all $\langle s, t \rangle \in R$ with $\mu = \alpha(s)$, $\nu = \beta(t)$ and every component *C* of *R*:

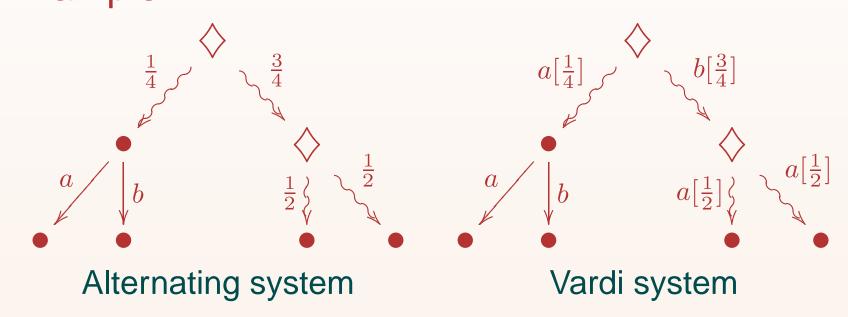
 $\mu(a, C) = \nu(a, C)$

 $s \thickapprox t$ - there exists a concrete bisimulation R with $\langle s,t\rangle \in R$

Property:

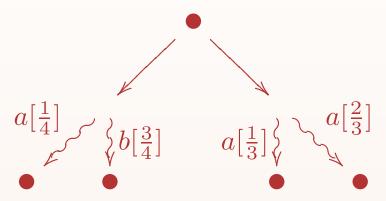
 $s \approx t$ if and only if $s \sim t$

Systems with distinction of states Alternating systems - functor $\mathcal{D}_{\omega} + \mathcal{P}(A \times \mathcal{I})$ Vardi systems - functor $\mathcal{D}_{\omega}(A \times \mathcal{I}) + \mathcal{P}(A \times \mathcal{I})$ Systems with distinction of states Alternating systems - functor $\mathcal{D}_{\omega} + \mathcal{P}(A \times \mathcal{I})$ Vardi systems - functor $\mathcal{D}_{\omega}(A \times \mathcal{I}) + \mathcal{P}(A \times \mathcal{I})$ Example:

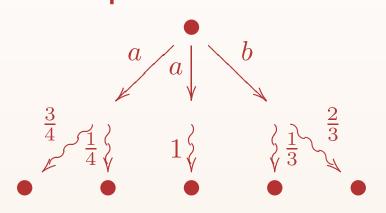


Structured transition function Segala systems - functor $\mathcal{PD}_{\omega}(A \times \mathcal{I})$

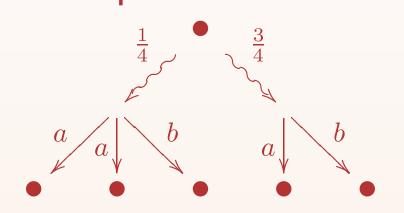
Structured transition function Segala systems - functor $\mathcal{PD}_{\omega}(A \times \mathcal{I})$ Example:



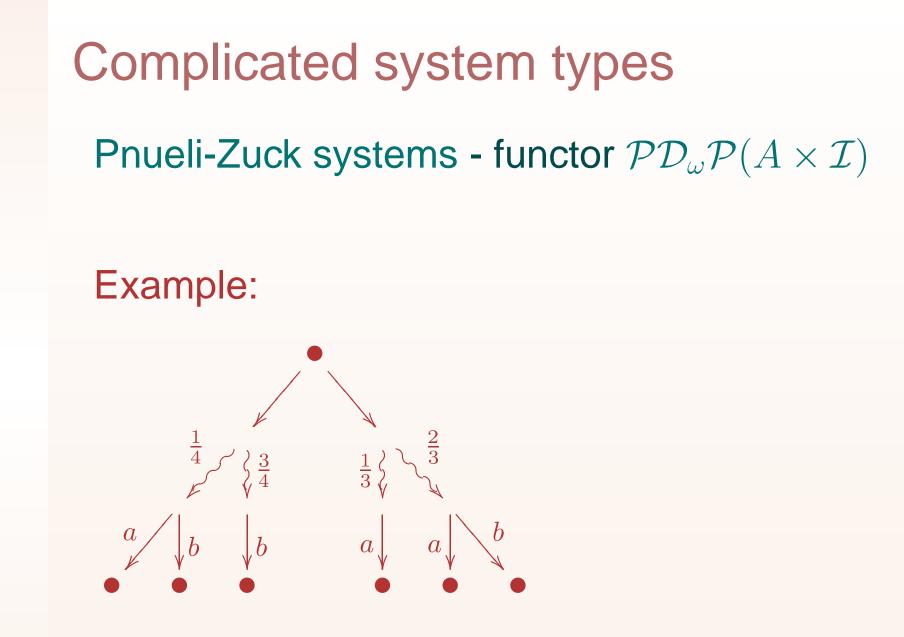
Structured transition function Segala systems - functor $\mathcal{PD}_{\omega}(A \times \mathcal{I})$ simple Segala systems - functor $\mathcal{P}(A \times \mathcal{D}_{\omega})$ Structured transition function Segala systems - functor $\mathcal{PD}_{\omega}(A \times \mathcal{I})$ simple Segala systems - functor $\mathcal{P}(A \times \mathcal{D}_{\omega})$ Example:



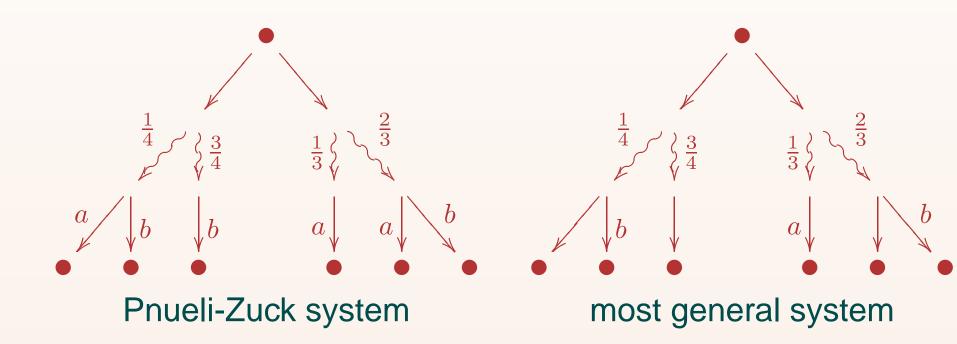
Structured transition function Segala systems - functor $\mathcal{PD}_{\omega}(A \times \mathcal{I})$ simple Segala systems - functor $\mathcal{P}(A \times \mathcal{D}_{\omega})$ Structured transition function Segala systems - functor $\mathcal{PD}_{\omega}(A \times \mathcal{I})$ simple Segala systems - functor $\mathcal{P}(A \times \mathcal{D}_{\omega})$ Bundle systems - functor $\mathcal{D}_{\omega}\mathcal{P}(A \times \mathcal{I})$ Structured transition function Segala systems - functor $\mathcal{PD}_{\omega}(A \times \mathcal{I})$ simple Segala systems - functor $\mathcal{P}(A \times \mathcal{D}_{\omega})$ Bundle systems - functor $\mathcal{D}_{\omega}\mathcal{P}(A \times \mathcal{I})$ Example:

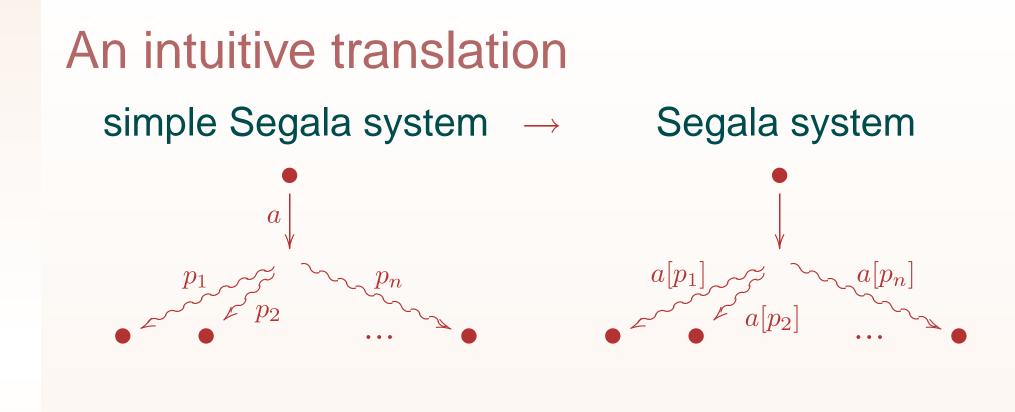


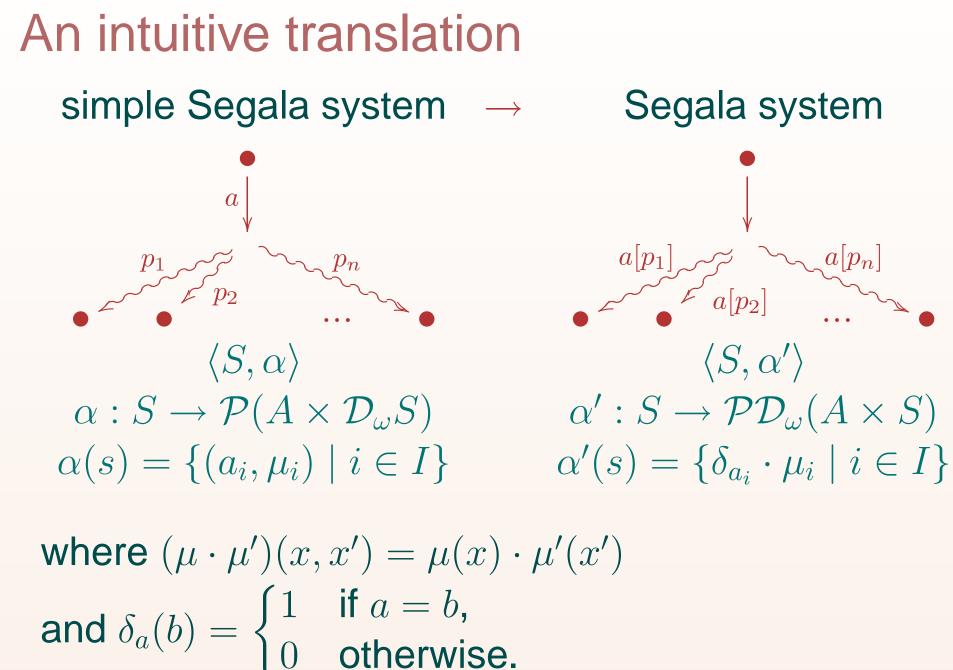
Structured transition function Segala systems - functor $\mathcal{PD}_{\omega}(A \times \mathcal{I})$ simple Segala systems - functor $\mathcal{P}(A \times \mathcal{D}_{\omega})$ Bundle systems - functor $\mathcal{D}_{\omega}\mathcal{P}(A \times \mathcal{I})$ Simple Segala system \perp Bundle system $\frac{2}{3}$

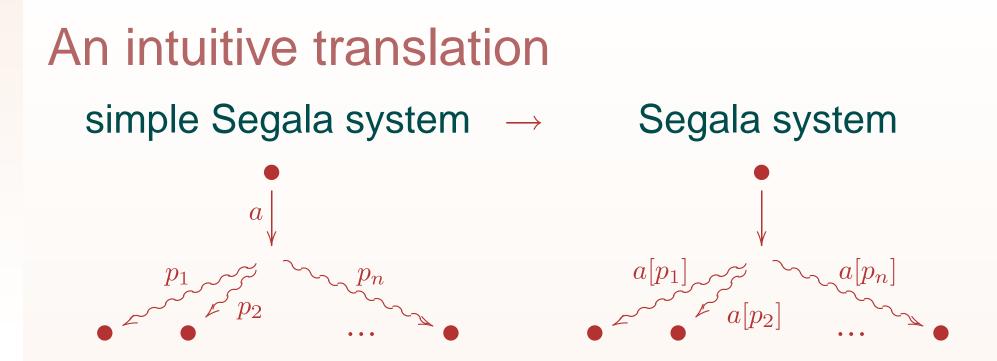


Complicated system types Pnueli-Zuck systems - functor $\mathcal{PD}_{\omega}\mathcal{P}(A \times \mathcal{I})$ most general systems - functor $\mathcal{PD}_{\omega}\mathcal{P}(A \times \mathcal{I}+\mathcal{I})$ Example:









When do we consider one type of systems more expressive than another?



When do we consider one type of system more expressive than another?



When do we consider one type of system more expressive than another?

Example: LTS ($\mathcal{P}(A \times \mathcal{I})$) less expressive than Alternating Systems ($\mathcal{D}_{\omega} + \mathcal{P}(A \times \mathcal{I})$)

Expressiveness (2) Our approach: Systems of type \mathcal{F} are at most as expressive as systems of type \mathcal{G} , if there is a mapping $\mathcal{T}: \operatorname{Coalg}_{\mathcal{F}} \to \operatorname{Coalg}_{\mathcal{G}}$ with $\langle S, \alpha \rangle \stackrel{T}{\mapsto} \langle S, \tilde{\alpha} \rangle$ that *preserves* and *reflects* bisimilarity:

 $s_{\langle S, \alpha \rangle} \sim t_{\langle T, \beta \rangle} \iff s_{\mathcal{T} \langle S, \alpha \rangle} \sim t_{\mathcal{T} \langle T, \beta \rangle}$

Translation of coalgebras

For LTS vs. Alternating Systems there exists a natural transformation

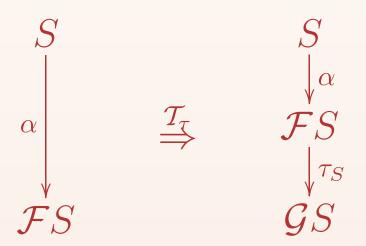
 $\iota_r: \mathcal{P}(A \times \mathcal{I}) \Rightarrow \mathcal{D}_\omega + \mathcal{P}(A \times \mathcal{I}).$

Translation of coalgebras

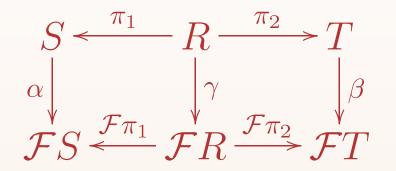
For LTS vs. Alternating Systems there exists a natural transformation

 $\iota_r: \mathcal{P}(A \times \mathcal{I}) \Rightarrow \mathcal{D}_\omega + \mathcal{P}(A \times \mathcal{I}).$

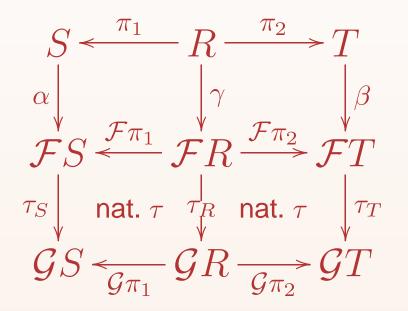
Generally, a natural transformation $\tau : \mathcal{F} \Rightarrow \mathcal{G}$ gives rise to a translation of coalgebras $\mathcal{T}_{\tau} : \operatorname{Coalg}_{\mathcal{F}} \to \operatorname{Coalg}_{\mathcal{G}}$ as follows:



Preservation of bisimulations The translation \mathcal{T}_{τ} preserves bisimulations: A bisimulation $R \subseteq S \times T$ between $\langle S, \alpha \rangle$ and $\langle T, \beta \rangle$



Preservation of bisimulations The translation \mathcal{T}_{τ} preserves bisimulations: A bisimulation $R \subseteq S \times T$ between $\langle S, \alpha \rangle$ and $\langle T, \beta \rangle$



is a bisimulation between $\mathcal{T}_{\tau}\langle S, \alpha \rangle$ and $\mathcal{T}_{\tau}\langle T, \beta \rangle$ as well.

Reflection of bisimilarity But: T_{τ} need not reflect bisimilarity. Example: Let τ be the natural transformation $\widetilde{\operatorname{supp}}: \mathcal{D}_{\omega} + 1 \Rightarrow \mathcal{P}$ that *forgets* the probabilities.

Reflection of bisimilarity But: T_{τ} need not reflect bisimilarity. Example: Let τ be the natural transformation $\widetilde{\operatorname{supp}}: \mathcal{D}_{\omega} + 1 \Rightarrow \mathcal{P}$ that *forgets* the probabilities. $\frac{2}{3}$ $\frac{1}{3}$ T_{τ} \mathcal{T}_{τ}

 $\frac{1}{3}$

 $\frac{2}{3}$

Assumption: Injectivity

Observation: the components of supp are not injective.

Assumption: Injectivity

Observation: the components of supp are not injective.

 \Rightarrow to obtain reflection of bisimilarity we assume that τ is componentwise injective.

Assumption: Injectivity

Observation: the components of supp are not injective.

 \Rightarrow to obtain reflection of bisimilarity we assume that τ is componentwise injective.

Injectivity is not necessary Example: $supp : \mathcal{D}_{\omega} \Rightarrow \mathcal{P}$

Assumption: Injectivity

Observation: the components of supp are not injective.

 \Rightarrow to obtain reflection of bisimilarity we assume that τ is componentwise injective.

Injectivity is not necessary Example: $supp : \mathcal{D}_{\omega} \Rightarrow \mathcal{P}$

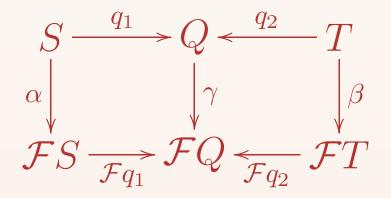
... for the proof another notion of behaviour equivalence is needed...

Cocongruences

A *cocongruence* between two \mathcal{F} -coalgebras $\langle S, \alpha \rangle$ and $\langle T, \beta \rangle$ is a *cospan*

 $\langle Q, q_1 : S \to Q, q_2 : T \to Q \rangle$

such that there exists a \mathcal{F} -coalgebra structure γ on Q making the diagram below commute.



Behavioural equivalence

states *s* and *t* in two \mathcal{F} -coalgebras $\langle S, \alpha \rangle$ and $\langle T, \beta \rangle$ are *behavioural equivalent* if they are identified by some cocongruence.

Behavioural equivalence

states *s* and *t* in two \mathcal{F} -coalgebras $\langle S, \alpha \rangle$ and $\langle T, \beta \rangle$ are *behavioural equivalent* if they are identified by some cocongruence.

Result: If all components of the natural transformation

 $\tau: \mathcal{F} \Rightarrow \mathcal{G}$

are injective, then \mathcal{T}_{τ} reflects behavioural equivalence.

Bisimularity vs. beh. equivalence

• Generally, bisimilarity implies behavioural equivalence.

Bisimularity vs. beh. equivalence

- Generally, bisimilarity implies behavioural equivalence.
- If the functor *F* preserves weak pullbacks, then behavioural equivalence implies bisimilarity.
 - \Rightarrow both notions coincide.

Bisimularity vs. beh. equivalence

- Generally, bisimilarity implies behavioural equivalence.
- If the functor *F* preserves weak pullbacks, then behavioural equivalence implies bisimilarity.

 \Rightarrow both notions coincide.

Corollary:

If \mathcal{F} preserves weak pullbacks and all components of $\tau : \mathcal{F} \Rightarrow \mathcal{G}$ are injective, then \mathcal{T}_{τ} reflects bisimilarity.

Need of w.p. preservation

The assumption that \mathcal{F} preserves weak pullbacks is necessary.

Example: Consider the functors

$$\mathcal{F}X := \left\{ \langle x, y, z \rangle \in X^3 \mid |\{x, y, z\}| \le 2 \right\}$$

and

 $\mathcal{G}X := X^3$

and let $\tau : \mathcal{F} \Rightarrow \mathcal{G}$ be the set inclusion.

Weak pullback preservation here

• The functors $A, \mathcal{I}, \mathcal{P}$, and \mathcal{D}_{ω} preserve weak pullbacks.

Weak pullback preservation here

- The functors $A, \mathcal{I}, \mathcal{P}$, and \mathcal{D}_{ω} preserve weak pullbacks.
- If \mathcal{F} and \mathcal{G} preserve weak pullbacks, so do $\mathcal{F} + \mathcal{G}$, $\mathcal{F} \times \mathcal{G}$, \mathcal{F}^C , and $\mathcal{F}\mathcal{G}$.

Weak pullback preservation here

- The functors $A, \mathcal{I}, \mathcal{P}$, and \mathcal{D}_{ω} preserve weak pullbacks.
- If \mathcal{F} and \mathcal{G} preserve weak pullbacks, so do $\mathcal{F} + \mathcal{G}$, $\mathcal{F} \times \mathcal{G}$, \mathcal{F}^C , and $\mathcal{F}\mathcal{G}$.

 \Rightarrow All functors used to define the different probabilistic system types preserve weak pullbacks.

Some basic transformations Examples of natural transformations with injective components:

• $\eta: 1 \Rightarrow \mathcal{P}$ with $\eta_X(*) := \emptyset$,

Examples of natural transformations with injective components:

- $\eta: 1 \Rightarrow \mathcal{P}$ with $\eta_X(*) := \emptyset$,
- $\sigma: \mathcal{I} \Rightarrow \mathcal{P}$ with $\sigma_X(x) := \{x\}$,

Examples of natural transformations with injective components:

- $\eta: 1 \Rightarrow \mathcal{P}$ with $\eta_X(*) := \emptyset$,
- $\sigma: \mathcal{I} \Rightarrow \mathcal{P}$ with $\sigma_X(x) := \{x\}$,
- $\delta : \mathcal{I} \Rightarrow \mathcal{D}_{\omega}$ with $\delta_X(x) := \delta_x$ (*Dirac*),

Examples of natural transformations with injective components:

• $\eta: 1 \Rightarrow \mathcal{P}$ with $\eta_X(*) := \emptyset$,

• $\sigma: \mathcal{I} \Rightarrow \mathcal{P}$ with $\sigma_X(x) := \{x\}$,

• $\delta : \mathcal{I} \Rightarrow \mathcal{D}_{\omega}$ with $\delta_X(x) := \delta_x$ (*Dirac*),

• $\iota_l: \mathcal{F} \Rightarrow \mathcal{F} + \mathcal{G} \text{ and } \iota_r: \mathcal{G} \Rightarrow \mathcal{F} + \mathcal{G},$

Examples of natural transformations with injective components:

- $\eta: 1 \Rightarrow \mathcal{P}$ with $\eta_X(*) := \emptyset$,
- $\sigma: \mathcal{I} \Rightarrow \mathcal{P}$ with $\sigma_X(x) := \{x\}$,
- $\delta : \mathcal{I} \Rightarrow \mathcal{D}_{\omega}$ with $\delta_X(x) := \delta_x$ (*Dirac*),
- $\iota_l : \mathcal{F} \Rightarrow \mathcal{F} + \mathcal{G} \text{ and } \iota_r : \mathcal{G} \Rightarrow \mathcal{F} + \mathcal{G}$,
- $\phi + \psi : \mathcal{F} + \mathcal{G} \Rightarrow \mathcal{F}' + \mathcal{G}'$ for $\phi : \mathcal{F} \Rightarrow \mathcal{F}'$ and $\psi : \mathcal{G} \Rightarrow \mathcal{G}'$ (both with i.c.),

Examples of natural transformations with injective components:

- $\eta: 1 \Rightarrow \mathcal{P}$ with $\eta_X(*) := \emptyset$,
- $\sigma: \mathcal{I} \Rightarrow \mathcal{P}$ with $\sigma_X(x) := \{x\}$,
- $\delta : \mathcal{I} \Rightarrow \mathcal{D}_{\omega}$ with $\delta_X(x) := \delta_x$ (*Dirac*),
- $\iota_l : \mathcal{F} \Rightarrow \mathcal{F} + \mathcal{G} \text{ and } \iota_r : \mathcal{G} \Rightarrow \mathcal{F} + \mathcal{G},$
- $\phi + \psi : \mathcal{F} + \mathcal{G} \Rightarrow \mathcal{F}' + \mathcal{G}'$ for $\phi : \mathcal{F} \Rightarrow \mathcal{F}'$ and $\psi : \mathcal{G} \Rightarrow \mathcal{G}'$ (both with i.c.),
- $\kappa : \mathcal{A} \times \mathcal{P} \Rightarrow \mathcal{P}(\mathcal{A} \times \mathcal{I})$ with $\kappa_X(a, M) := \{ \langle a, x \rangle \mid x \in M \},\$

Examples of natural transformations with injective components:

- $\eta: 1 \Rightarrow \mathcal{P}$ with $\eta_X(*) := \emptyset$,
- $\sigma: \mathcal{I} \Rightarrow \mathcal{P}$ with $\sigma_X(x) := \{x\}$,
- $\delta : \mathcal{I} \Rightarrow \mathcal{D}_{\omega}$ with $\delta_X(x) := \delta_x$ (*Dirac*),
- $\iota_l : \mathcal{F} \Rightarrow \mathcal{F} + \mathcal{G} \text{ and } \iota_r : \mathcal{G} \Rightarrow \mathcal{F} + \mathcal{G},$
- $\phi + \psi : \mathcal{F} + \mathcal{G} \Rightarrow \mathcal{F}' + \mathcal{G}'$ for $\phi : \mathcal{F} \Rightarrow \mathcal{F}'$ and $\psi : \mathcal{G} \Rightarrow \mathcal{G}'$ (both with i.c.),
- $\kappa : \mathcal{A} \times \mathcal{P} \Rightarrow \mathcal{P}(\mathcal{A} \times \mathcal{I})$ with $\kappa_X(a, M) := \{ \langle a, x \rangle \mid x \in M \},\$

One expressiveness statement

Generative systems ($\mathcal{F} := \mathcal{D}_{\omega}(\mathbf{A} \times \mathcal{I}) + 1$)

are at most as expressive as Vardi systems ($\mathcal{G} := \mathcal{D}_{\omega}(A \times \mathcal{I}) + \mathcal{P}(A \times \mathcal{I})$)

natural transformation

 $\mathcal{D}_{\omega}(\mathbf{A} \times \mathcal{I}) + \eta(\mathbf{A} \times \mathcal{I}) : \mathcal{F} \Rightarrow \mathcal{G}.$

Another expressiveness statement

simple Segala systems ($\mathcal{F} := \mathcal{P}(A \times \mathcal{D}_{\omega})$)

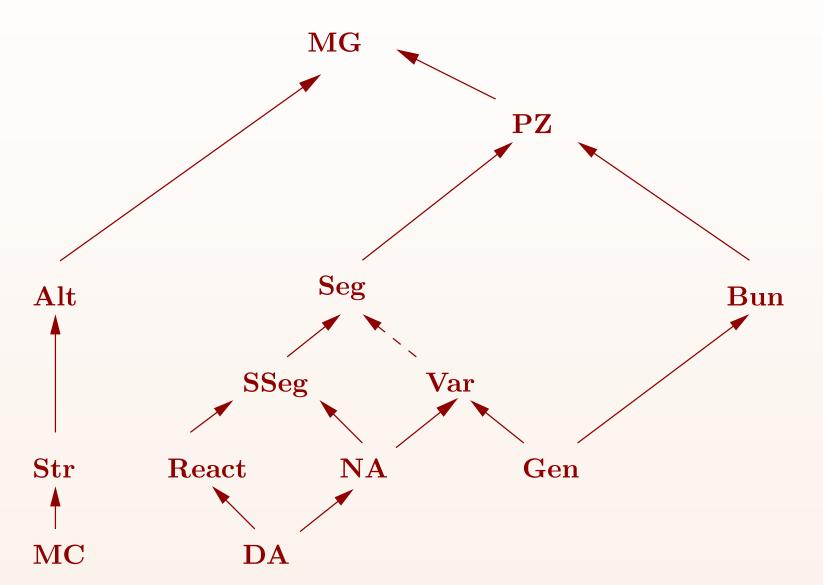
are at most as expressive as Segala systems ($\mathcal{G} := \mathcal{PD}_{\omega}(A \times \mathcal{I})$)

natural transformation

 $\mathcal{P}\tau:\mathcal{F}\Rightarrow\mathcal{G}$

for $\tau_X(\langle a, \mu \rangle) = \delta_a \cdot \mu$ where $(\mu \cdot \mu')(x, x') = \mu(x) \cdot \mu'(x')$ and ...

The hierarchy of system types



 Various probabilistic system types were compared

- Various probabilistic system types were compared
- The coalgebraic approach proved useful for:

- Various probabilistic system types were compared
- The coalgebraic approach proved useful for:
 * providing a uniform framework

- Various probabilistic system types were compared
- The coalgebraic approach proved useful for:
 - * providing a uniform framework
 - * a general notion of bisimulation

- Various probabilistic system types were compared
- The coalgebraic approach proved useful for:
 - * providing a uniform framework
 - * a general notion of bisimulation
 - * proving a comparison result